

**ELITE™**

*DMSS 2.4GHz SPREAD SPECTRUM SYSTEM*

## Operation Manual

Prior to use, please read this manual thoroughly.  
Keep this manual in a convenient place for quick  
and easy reference.



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## ■ Features

Your new TX is one of the finest model aircraft transmitters ever created. It sets a new benchmark in performance and ergonomics. In order to make full use of the features of this radio and to safely enjoy your RC activities, please carefully read this operation manual.

- Integrated touch screen android interface

The TX is the first RC system to offer an Android operating system. This technology is accessible through a 480 x 273 pixel, 4.3" WQVGA-TFT full-color touch screen. The transmitter is equipped with dual processors to allow for smooth interfacing and reliable radio frequency output. There is 4GB of internal memory with 512MB RAM

- 28 channels – up to 14ms refresh rates!

The transmitter is configured for sixteen 14ms channels. If you require more than 16 channels, you can choose to add four (56ms) channels at a time, in place of one 14ms channel. So the final 28 channels are in a configuration of twelve 14ms channels, and sixteen 56ms channels. Note all the channels are proportional, and you are unlikely to notice a difference in response between the 14ms and 56ms channels.

- CNC aluminum ball-bearing supported gimbals

The TX stick units have 65,536 step stick resolution, which is 16 times more precise than any other RC transmitter. The CNC machined aluminum gimbals are supported by ball bearings and can be adjusted to suit any pilot.

- Customizable voice and vibration alerts

Another great feature of the JR TX is an audio controller, which you can use for voice and telemetry notifications. These audio and vibration notifications can also be customized as you see fit.

- JR's revolutionary DMSS system

The TX uses JR's proprietary 2.4GHz DMSS protocol for a super secure RF link. JR's newly developed DMSS system maintains high speed servo response while allowing simultaneous use of telemetry functions. The high-speed telemetry function allows information from the aircraft (that was previously unknown to the user) to be monitored on the transmitter. In addition, alarms with unique sounds alert the user to the situation on the aircraft without even looking at the screen.

- Support with Multi Telemetry Display

Adopted with Serial bus connection which does not require relay dongle between the telemetry Sensor. Desired telemetry sensors can be connected in parallel or extended or added.

- Long lasting power

The TX comes with one 3350mAh Li-Ion battery, and supports an

optional second battery for extended operation. The included charger fully charges the transmitter in approximately 4 hours.

- Multiple flight modes

Fifteen flight modes are available for each aircraft type (acro/heli/sailplane). Each flight mode can be fully customized.

- Curve adjustment by trim device

Trim input switches can be used for adjustment of almost all mixing curves and other functions during flight. The entire curve can be increased/decreased using the trim input switch while the curve shape does not change, or alternatively individual points on a curve can be adjusted during flight.

- Wing types

Many varied pre-settings help as a wizard during the set-up: 4 flaps, 4 ailerons, 2 spoilers, 4 engines, etc.

### ■ Transmitter specifications

| Item             | Specification  |
|------------------|--|
| Part Number      | ELITE  |
| Type of control  | 16 channel computer mixing   |
| RF               | 2.4GHz   |
| Modulation       | DMSS(Dual Modulation Spectrum System)<br>2.4GHz FHSS Spread Spectrum Method            |
| Power source     | 7.2V Li-Ion battery x 2 (each 3350mAh<br>2L3350(3350mA) ※ 1 or 2 batteries can be used |
| Neutral position | 1.5ms  |

## ■ AC adaptor specifications

| Item            | Specification       |
|-----------------|---------------------|
| Part number:    | #JAC-A1220          |
| Input voltage:  | AC100V-240V 50/60Hz |
| Output voltage: | DC12V 2.0A 24W      |

## ■ Safety Information

JR Propo cannot be held responsible for any accident or failure that may occur due to any modification of this product, use of non-genuine parts, natural disaster, or nonobservance of the precautions described in this manual. Further, for damages caused by an accident or failure, please understand that items (excluding this product and this Company's genuine parts) such as aircraft, competitor's products, etc will not be covered under the warranty.

The use of radio waves required by this product is defined in the Radio Law of Japan.

- When this product is used overseas, authorization by the law of the country will be required.
- When this product is used overseas for a purpose other than as radio control system for a model, it may be subject to restrictions in accordance with the Export Trade Control Order. In such a case, an export permit under the Order is required. This is the responsibility of the end user.

## ■ Basic precautions for safe use of the 2.4GHz band

The 2.4GHz band is not exclusively for use with RC aircraft. This frequency band is also used by ISM (industry, science, and medical care) products. It is also used for short distance microwave transmissions, wireless LAN, digital cordless phones, audio games, cellphone Bluetooth, etc. Therefore, control response of a 2.4GHz system may be degraded in urban areas. Further, as it is also used for ham and local area radio communications for mobile identification, please pay attention to possible influences from these. In the event of any adverse radio wave interference, immediately stop emitting radio waves and seek to solve any issues..

- At a race track or airfield, minimize use of devices that can affect the transmitter/receiver and always confirm a solid RF link before flight by performing a range check(page 3-7).
- If an aircraft is allowed to fly behind a building, trees, etc. the RF signal may be blocked and control response may drop, even resulting in an

'out-of-control' situation. Always fly the aircraft within a range that can be visually observed.

## ■ Indications and symbols related to safety

The following symbols are used in this manual to indicate the precautions regarding possible danger which may occur following improper handling. Be sure to strictly observe them, as they contain important safety instructions. If incorrect operation methods are used, there will be a danger of death or serious injury, and/or damage to property.

 **DANGER**

If incorrect operation methods are used, it may result in death or serious injury.

 **WARNING**

If incorrect operation methods are used, there will be a possibility of death or serious injury.

 **CAUTION**

If incorrect operation methods are used, it can be expected that problems will occur.

## ■ Safety precautions

Before using this transmitter for the first time, check that all the parts and accessories have been provided. First fully charge the transmitter and receiver batteries. Next, connect the switch harness, battery and servos to the receiver. Turn on the transmitter then receiver and confirm that they operate correctly. If they do not operate, first check the batteries. If a rechargeable battery is being used for the first time after purchase, or is being used after being left unused for a long period, be sure to charge it with the battery charger before use. Confirm the transmitter and receiver are correctly bound. **Refer to page 3-7 (Binding procedure)**

 **DANGER**⊗ **Out-of-control and dangerous situations can be caused.**

DO NOT use the product on rainy days since it may malfunction if water gets inside the transmitter or receiver. If use is a necessity, be sure to take appropriate waterproofing measures.

⊗ **Injury due to heat generation, fire, or electric shock can occur.**

Never disassemble or modify this product.

△ **The engine or motor (in the case of an electrically-driven model) can start rotating at high speed, causing danger.**

When turning on the power switch, set the transmitter throttle stick to the lowest speed position (where the engine/motor is off) and turn on the transmitter power switch, and then the receiver power switch in this order. When turning off the power, turn off the receiver and then transmitter in this order.

△ **Injury can be caused.**

When adjusting the engine (or motor), pay attention to the dangers presented.

△ **DO NOT start the engine with the transmitter throttle in a high speed position. This is very dangerous.**



⊗ **Failure can be caused.**

DO NOT use this transmitter in combination with a competitor's product (receiver, servo, gyroscope, etc).

⊗ **Malfunction can be caused.**

As the electronic parts mounted on the transmitter and receiver are susceptible to impact, do not allow a strong impact (crash) or drop them.

⊗ **Out-of-control and dangerous situations can be caused.**

When degraded servo movement is detected, immediately stop operating and check the battery power remaining, RF link, servos, etc.

⊗ **DO NOT use the product in the following places, as there is a risk of an out-of-control state or an accident occurring:**

- ▶ RF interference exists.
- ▶ Flying near to traffic consisting of cars or motorbikes.
- ▶ Near a high-tension electric line, building, bank, or in a mountainous area.
- ▶ Near a FM/TV station, or any radio transmitting station.
- ▶ Near residences and buildings, and near people.

⊗ **A sudden malfunction may occur and will be dangerous.**

If the receiver, servo etc. get water logged, they may look to operate normally. However, they may fail at any time in the future. Do not continue to use the product, and contact your JR dealer or distributor to arrange an inspection regardless of normal operation.



△ **Prior to flying, check the following items for safety:**

- ▶ Is there enough battery charge remaining in the transmitter and receiver?
- ▶ Is there any fuel spillage on the receiver, servos, etc. which was caused by leakage from the fuel tank? Is there enough fuel? Check that no linkage is in contact with the aircraft body. Also, conduct a vibration test by setting the engine (motor) to high while holding the model and confirm that each control surface moves correctly (airplanes only).

△ **In the case of the initial flight, avoid flying at great distances, choose a safe place, and perform flying practice in close vicinity for several minutes.**

■ **Rechargeable battery and battery charger**

Abide by the following to prevent potential leakage, explosion, heat generation, or fire.



⊗ **The AC/DC Adapter is multi-voltage (100V-240V). Be sure to use appropriate outlet plugs.**

⊗ **DO NOT use any adapter with (+) or (-) set in the opposite direction.**

⊗ **DO NOT place near fire or heat.**

⊗ **DO NOT connect (+) or (-) to any material that may conduct electricity including metals (wire, etc.), carbon materials, etc.**

⊗ **DO NOT disassemble, remodel, or solder.**

△ **It may cause a loss of vision if the liquid inside the battery gets into your eyes.**

Consult a doctor immediately after washing eyes with clean water, and do not rub the eye areas.



⊗ **Failure can be caused.**

Only use genuine JR batteries. Stop charging when the specified charging time is complete.

⊗ **DO NOT allow the battery to get wet with water or sea water.**

⊗ **DO NOT damage or tear off the insulating tube, the lead wire, or the connector.**

△ **DO NOT use the battery if there is damage to the insulating tube, lead wire, or connector, or if the insulation is damaged.**

△ **Skin may be damaged if leaked battery liquid stays on your skin or clothes. Wash away immediately with clean water.**

⊗ **Out-of-control and dangerous situations can be caused.**

The rechargeable battery is composed several individual batteries. Note that the actual battery level cannot be precisely confirmed by testers such as a battery checker. Check the state of charge in a comprehensive way by using a battery checker, checking the recharge time, and operating time.



- ⊘ **Do not store the battery in a place with high temperature/humidity or dust.**
- ⚠ **Store the battery out of reach of children.**
- ⊘ **Do not charge the battery in a place with low temperature (below zero degrees Celsius).**
- ⚠ **Dispose of old batteries according to the local disposal regulations - do not throw them away in garbage cans, etc.**

### ■ Recycling rechargeable batteries

Used Li-Ion batteries are important resources. Place a piece of tape or similar over the terminal areas, and drop them off to recycling depots that collect small rechargeable batteries.

## ■ Introduction to the Transmitter

Your new JR ELITE will provide years of reliable service. To get the best performance from your new transmitter, please be sure to fully understand all its controls and functions. Reading this manual will help greatly with this task.

### ■ Color touch screen

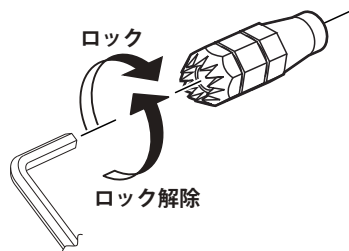
The ELITE features an all new color touch screen. This is used to quickly program even very complex functions within the radio. The screen should only be operated using light finger pressure. Never use a sharp object such as a pen, etc to press on the screen.

### ■ Switch identification

If you look closely at the transmitter, you will see that each switch is labeled with a letter (A, B, C, etc), as are the various digital auxiliary controls (page 3-9).

### ■ Stick length adjustment

Undo the recessed set screw located at the tip of the control stick. Now rotate the entire stick to adjust its length. When finished, lock the recessed set screw.



### ■ Neck strap attachment

For added comfort and stability during use, you may choose to use a neck strap.

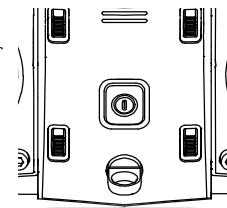


### ■ Cleaning the transmitter and screen

Your transmitter and screen can be cleaned using a soft cloth – ideally a microfiber cloth, as sold for cleaning eyewear. Never use solvents or detergents when cleaning your transmitter.

## ■ Turning the transmitter on

To turn the transmitter on, briefly press the power button located on the face of the transmitter.



## ■ Warning display

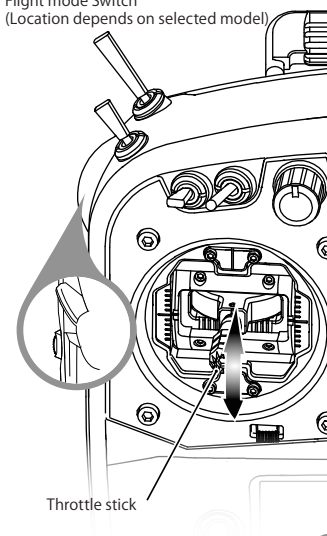
If the transmitter is turned on and the transmitter stick or other switches are in incorrect positions, a warning tone is generated and the following screen appears.

The stick position or switch(s) creating the warning are identified on this screen. Simply move the controls to the correct position to cancel the warning.

You can customize the warnings for each model by setting the warning parameters in the warning menu **see page 5-9**. This menu can be accessed directly from the warning display.

△ The warning message will not display while booting

Flight mode Switch  
(Location depends on selected model)



Throttle stick



### ■ Transmitter LED's

JR PROPO logo shall change the color of LED to indicate the condition of the battery or the RF linkage.

- Steady lit in blue => RF Transmission
- Flashing in blue => Under the low power RF transmission or Servo hold.
- Steady lit in red => NO RF transmission.
- Quick flashing in blue => Dropping of the battery voltage.
- Explanation of the condition under the battery charging.



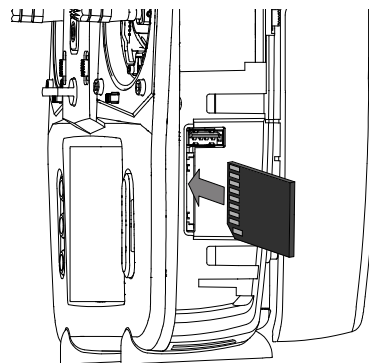
If the transmitter is under the charge mode, the LED shall steady lit in red. If the battery is connected to the terminal "A" LED indicator of the left- hand side shall be steady lit in red. If the battery is connected to the terminal "B", the LED indicator of the right- hand side steady lit in red. If the both batteries are connected to Terminal "A" and "B", both LEDs shall steady lit in red.

### ■ Shutting down the transmitter

To avoid discharging the TX battery, this transmitter is designed to shut down the power completely. Also note that Power Switch is designed to turn the power "ON" or "OFF" properly without slight touching, it is required to press down the switch all the way down at the bottom of the switch. Be sure to turn the Power "ON" or "OFF" by pressing down completely.

### ■ Inserting and removing the SD card

For maximum compatibility and reliability, we recommend you purchase a SD card. If you choose to use a third party card, please ensure it is less than 32GB in size, and formatted in FAT. Inserting and removing SD cards should be carried out with the transmitter switched off. The SD card slot is located under a cover on the right side of the transmitter.



#### ■ Inserting the card

Switch off the transmitter, and then slowly insert the SD card into the slot until you feel a "click". Note correct orientation of the card.

#### ■ Removing the card

Lightly press in the middle of the SD card until it clicks - the card will pop out slightly when you remove your finger - now carefully pull the card out the rest of the way.

Please follow the following procedure to eject the SD card.



Swipe down the top screen, SD card logo will appear, continuously swipe down the SD card logo, "EJECT" will appear on the screen, Touch the "EJECT", then "SD card is safely ejected" message will appear and complete the process.

#### ■ USB ports

There are USB ports available. It allows you to plug in a USB memory stick, and access files from it. The USB stick should be inserted and removed with the transmitter turned off. Please do not use a USB extension harness to connect USB Memory devices - plug the devices in directly.

## ■ Trainer jack, charge jack

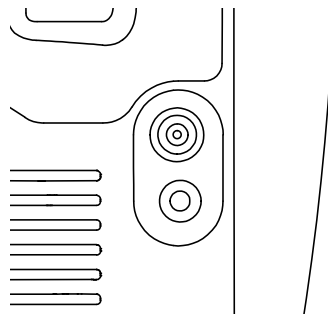
These ports are located under a protective cover on the back of the transmitter.

### ■ Trainer jack

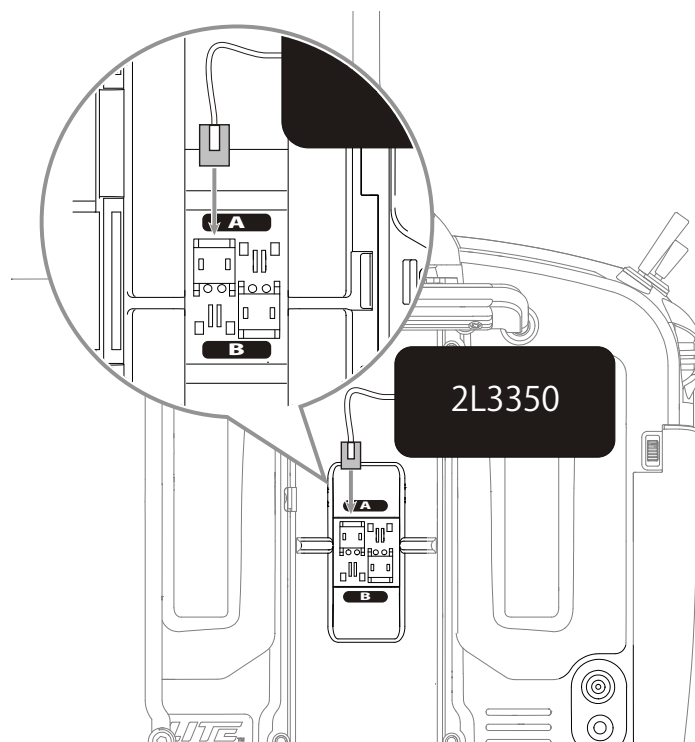
The 3.5mm mono trainer jack is accessible here to allow flight training to take place. Please see **page 5-11** for information regarding the trainer system.

### ■ Charge jack

The charge jack is conveniently located under this cover. Please refer to **page 2-3** for information on charging the transmitter.



## ■ Inserting and removing the transmitter batteries



- ① By Unscrewing four (4) M3 Hex screw from the battery cover plate, it is possible to open the battery compartment.
- ② Insert the battery connector to the transmitter's battery terminal.
- ③ As shown on the diagram, connect at the terminal "A" or "B". Install the battery pack to the compartment. Be sure not to pinch the battery cable between the battery cover plate and close the battery cover plate carefully.

**[Charging 2L 3350 Battery]** Be sure to connect the battery cable to the terminal to charge the battery.

**[Indication of the battery connection]** Display shall show the location of the terminal either "A" or "B" or both "A" and "B" in case use of two battery packs in the transmitter.

## ■ Charging the transmitter batteries

The transmitter operates exclusively using genuine JR Li-Ion batteries. One battery is supplied, and a second may be purchased as an optional extra for extended operation. If using one battery, it can be in either the upper or lower battery location. Do not use the transmitter with other rechargeable batteries or with dry cell batteries.

Even though the transmitter power is turned "ON", battery charging will continue as long as the AC/DC adapter is connected to the transmitter.

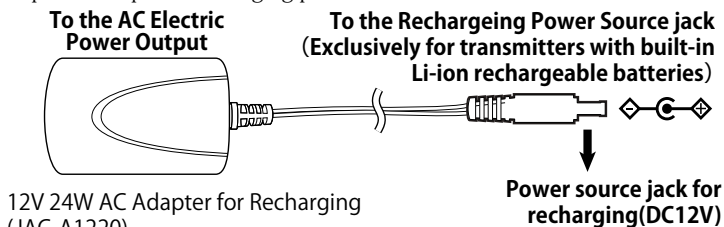
※ Note that if using a flight simulator with the control cable plugged into the trainer jack (and the power switch off on the transmitter), it is possible to plug the charge cable into the transmitter and use the power adaptor to supply power. Since the built-in battery will not be used, this will allow extended simulator time while not running down the transmitter battery packs. However, the internal batteries will not charge with the trainer lead plugged in.

- ① Insert the power adaptor into an AC electric power socket.
- ② Insert the plug of the adaptor as far as it will go into the DC power jack of the transmitter. The DC power jack is located on the rear of the transmitter.
- ③ Either one or two RED LED's will be illuminated at that JR PROPO logo at the top of the transmitter while charging. One of each side LED's indicate the two of the batteries inside the transmitter are connected. These represent the one or two batteries installed in the transmitter. If the LED's do not light, it means, the batteries are fully charged or If the appropriate number of LED's do not illuminate, an error may have occurred. In this situation, detach the power AC/DC adapter plug, and re-insert it a few times. If the LED(s) do not light even after the cable has been removed and inserted several times, please contact your JR agent or distributor in your country.

④ During charging, the LED(s) will remain illuminated. When charging is complete, the LED(s) will switch off. The standard charging time is approximately 3 hours, regardless if one or two batteries are being charged.

⑤ After charging is complete, detach all the connections. Do not leave the charger connected to the transmitter.

※ Be certain to only use the genuine JR ELITE dedicated power adapter. Charging is not possible using other adapters. Further, do not use this power adapter for charging products other than the ELITE.



12V 24W AC Adapter for Recharging (JAC-A1220)  
 ※ Note: This adapter can only be used when plugged into the TX it is not a stand alone charger.



## ⚠ WARNING

### △ Abnormal heat generation may cause explosion of the battery!

After charging is complete, detach all of the connections including the AC adaptor from the power outlet. Never leave the AC adaptor connected to the transmitter or plugged into the AC outlet. This is to avoid possible fire risk after charging the battery. Do not use the AC adapter while the cord is still bundled together, since there will be a risk of heat generation.

## ■ Voice prompts

By default, the flight mode indicator widget provides information on which flight mode is currently selected. Voice annunciations can be turned on and off by touching the flight mode widget on the home screen. FM information is announced in preference to telemetry. Announcements are only made when the flight mode name is an English word. Telemetry widgets include common settings such as unit selection, voice output, and no link alarm. See

page 8-1.

## ■ 28 channels – up to 14ms refresh rates

The transmitter is configured for sixteen 14ms channels. If you require more than 16 channels, refer to the channel setting menu (page 5-15) for information on channel configuration.

## ■ Stick mode

Changing the stick mode is done in the channel setting menu, by re-arranging the stick inputs for throttle, aileron, elevator and rudder as required. Please see page 5-15 – channel setting - for information on defining control input devices.

For some mode changes the spring function on the elevator and throttle sticks must be changed. Please see page 2-6 for information on this procedure.

- Settings related to the swash type or wing type are not performed here. Be sure to set the swash type or wing type using the appropriate functions in the system menu (page 5-16 and page 5-17).
- Note a dedicated function for changing stick mode is not used or required.

### ■ Mode 1

|     |          |      |     |         |      |
|-----|----------|------|-----|---------|------|
| CH1 | Throttle | [S1] | CH2 | Aileron | [S2] |
| CH3 | Elevator | [S3] | CH4 | Rudder  | [S4] |

### ■ Mode 2

|     |          |      |     |         |      |
|-----|----------|------|-----|---------|------|
| CH1 | Throttle | [S3] | CH2 | Aileron | [S2] |
| CH3 | Elevator | [S1] | CH4 | Rudder  | [S4] |

### ■ Mode 3

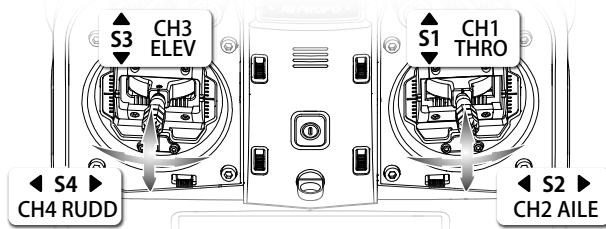
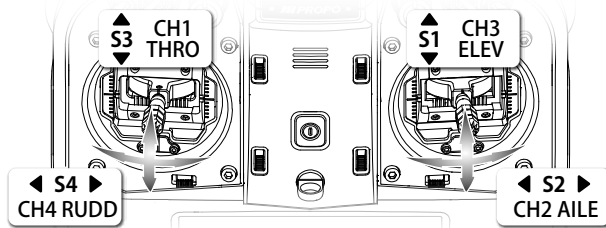
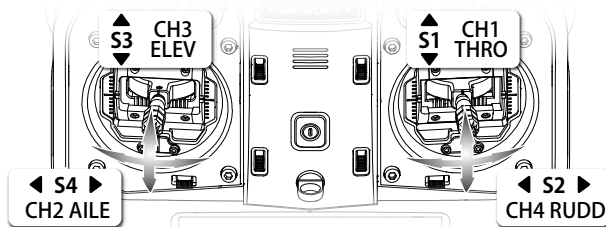
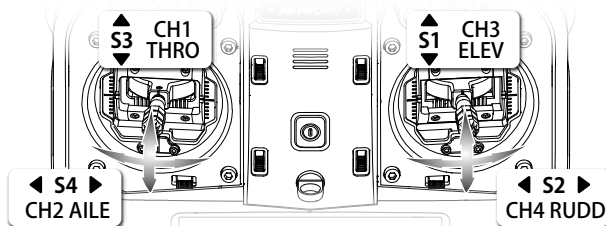
|     |          |      |     |         |      |
|-----|----------|------|-----|---------|------|
| CH1 | Throttle | [S1] | CH2 | Aileron | [S4] |
| CH3 | Elevator | [S3] | CH4 | Rudder  | [S2] |

### ■ Mode 4

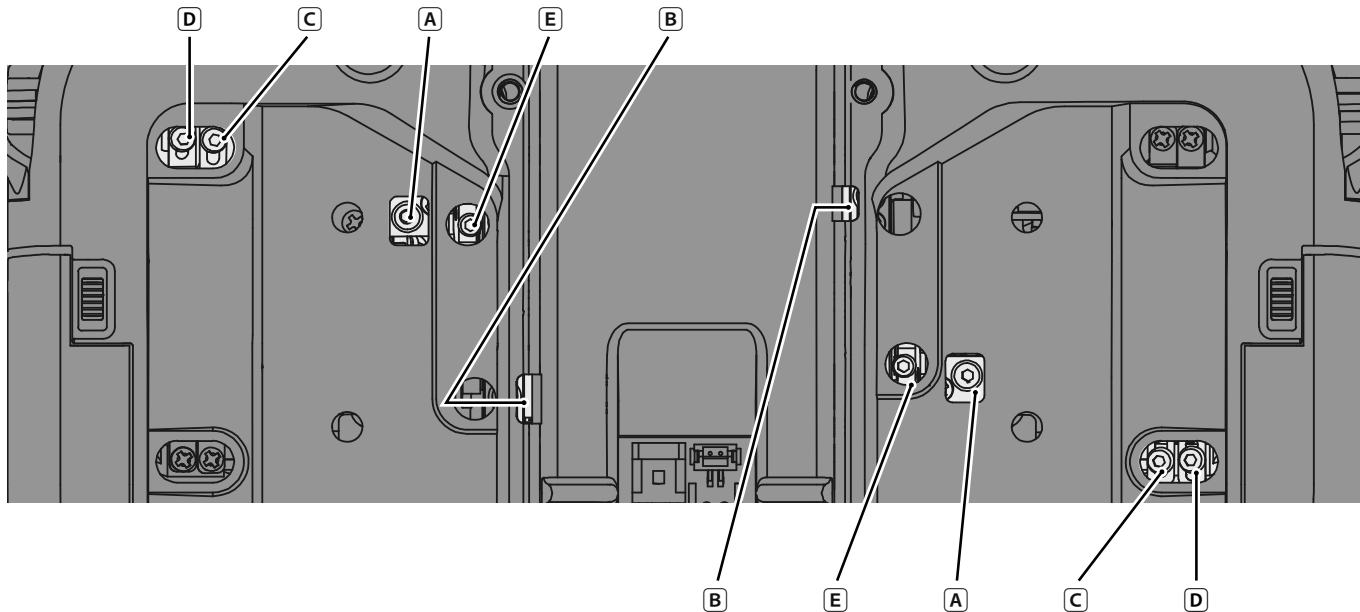
|     |          |      |     |         |      |
|-----|----------|------|-----|---------|------|
| CH1 | Throttle | [S3] | CH2 | Aileron | [S4] |
| CH3 | Elevator | [S1] | CH4 | Rudder  | [S2] |

## ■ Caution note

Be sure to calibrate both stick gimbals after changing the stick mode. Refer to the page 5-10 for calibration information.

**MODE 1****MODE 2****MODE 3****MODE 4**

## Stick spring tension and travel adjustment



### Stick spring tension adjustment

- Remove the batteries before carrying out any adjustments.
- Remove the molded rubber sections from the back of the transmitter.
- Adjust the springs to the desired spring tension. By carefully adjusting each of the screws, you can achieve a range of spring tensions.

#### Vertical axis spring adjustment:

Turn B counterclockwise. This increases the spring pressure to return the stick to center.

If there is play near center, turn E counterclockwise two or three turns.

Do not turn E too much, otherwise it may fall out. Use the included 1.5mm ball ended hex wrench to make adjustments.

#### Horizontal axis spring adjustment:

Adjust A to achieve the desired stick tension. Use the included ball ended hex wrench, which will need to be inserted at a slight angle. Turn clockwise for less tension.

- Replace the rubber covers.

See the following section for information on changing the throttle stick

feel from smooth clutch to ratchet.

Never touch the printed circuit board or any related parts inside the transmitter.

Touching the board may result in electric shock, uncontrolled microcomputer operation, or damage to model data, and normal operation may become impossible.

### Elevator and throttle stick configuration (mode change)

Sometimes when changing transmitter modes, you may find it necessary to swap the functions of the elevator and throttle sticks, which would necessitate changing the friction and spring functions.

Either stick can be configured as either elevator or throttle sticks. Screws B to E are adjusted using the included hex wrench.

#### How to disable the stick return spring and change to a friction throttle

- 1) Turn B clockwise until it stops.  
This reduces the spring pressure on the return to center.
- 2) Turn E clockwise until it stops.  
This reduces the spring pressure to zero, disabling it to return to center.
- 3) Turn C clockwise for helicopter throttle or D clockwise for airplane. This

increases the pressure on the throttle clutch, as either a smooth feel or ratchet.

- 4) Adjust the pressure to the desired strength, while testing the throttle stick feel.

#### ■ How to disable throttle operation and enable the stick return spring

- 1) Reduce the pressure of the throttle clutch to zero.  
Turn C counterclockwise for helicopter throttle or D counterclockwise for airplane. This reduces the pressure of the throttle clutch. When the throttle becomes free and moves with no load, stop adjusting the screw C or D.  
Do not loosen the screw too much, otherwise it may fall out.
- 2) Turn E counterclockwise ten times.  
Do not turn E too much, otherwise it may fall out.  
At this point, do not turn the screw more than ten turns.
- 3) Turn B counterclockwise.
- 4) This increases the spring pressure to return the stick to center.

#### ■ Adjust the tension as desired.

If there is play near center, turn E counterclockwise two or three turns. After making this hardware change, it is necessary to go to the channel setting menu (page 5-15) to define which functions will be performed by which sticks. This transmitter does not have traditional mode selection - functions are simply freely defined in the channel settings menu.

#### ■ Caution

Do not disassemble the transmitter. Disassembly may result in electric shock, microcomputer error or data corruption, disabling normal operation or control.

#### ■ Throttle stick travel adjustment

By adding optional throttle stroke adjustment blocks to the gimbal, the throttle stroke can be adjusted. The same procedure can be used to decrease elevator stick travel if required. There are four different adjuster blocks available. The adjuster blocks can change the stick stroke angle by  $-5^\circ$ ,  $-10^\circ$ ,  $-15^\circ$ , and an option for fixing the throttle stick in the neutral position. More information is provided with the adjustment blocks. When adding this "limiter plate" it is essential to recalibrate the throttle stick range (page 5-10). Be sure to follow this procedure.

#### ■ Caution note

Be sure to calibrate both stick gimbals after changing stick travel. Refer to the page 5-10 for calibration information.

- △ After the adjustments described above, be sure to confirm the output channels in channel settings (page 5-15).

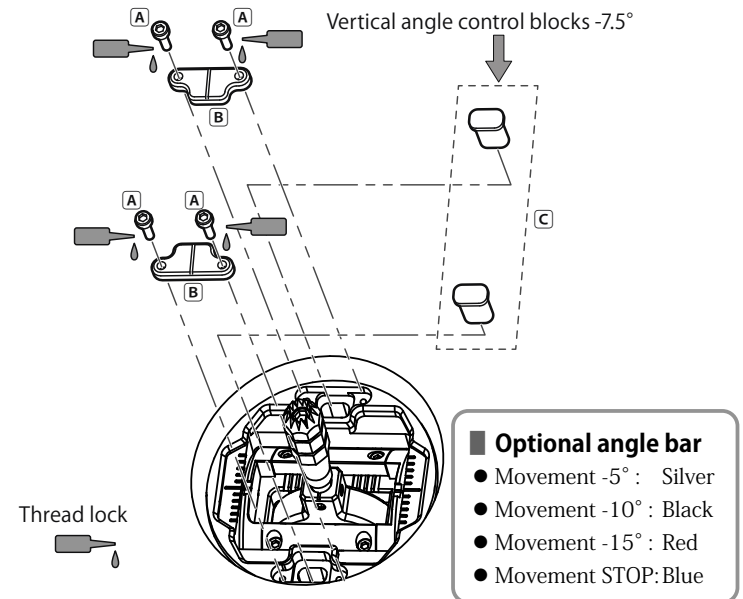
The concept of mode (such as 'mode 1' and 'mode 2') are no longer used. You freely define which function is allocated to which stick in the

channel setting function.

#### ⊗ Do not dismantle the transmitter.

Doing so may cause an electrical shock, a microcomputer crash, and damage to model data, resulting in a product that does not function or operate as it should.

### ■ Installing the stick vertical angle control blocks

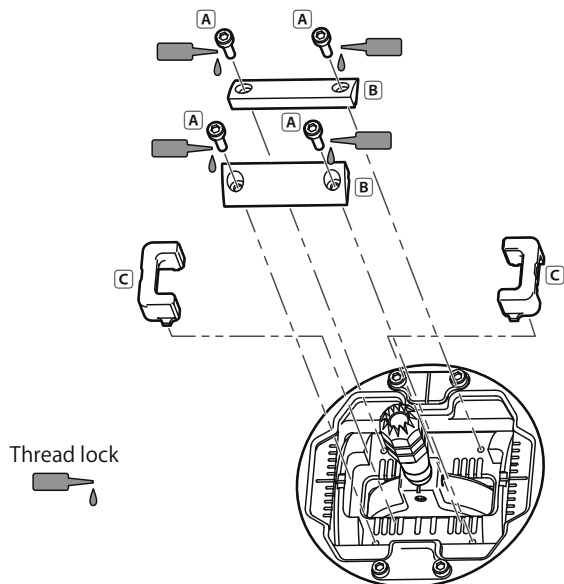


- 1) Remove the four screws [A]
- 2) Remove the two vertical angle control block covers [B]
- 3) Insert your choice of vertical angle control blocks [C]  
Five lengths of vertical angle control blocks [C] are available. The blocks reduce the range of the stick movement. Two vertical angle control blocks (gold) of  $-7.5^\circ$  are provided as a standard. The other types of angle control blocks are sold as optional items. Please purchase them as required.
- 4) Put the vertical angle control block covers [B] on the blocks and securely tighten the screws [A].  
Applying a small amount of a weak thread lock agent to the screws to prevent them from loosening (eg JR screw Lock soft type - red).
- 5) After replacing the vertical angle control blocks, be sure to carry out

stick calibration (see page 5-10).

- ※ When turning on the transmitter, a warning may be issued after replacing the blocks. To release the warning status, display the warning screen, touch "setting", and increase the numeric value for the position of the throttle stick.
- ※ After carrying out stick calibration, be sure to return the warning value to the original setting (page 5-9).

## Changing the stick horizontal angle control blocks



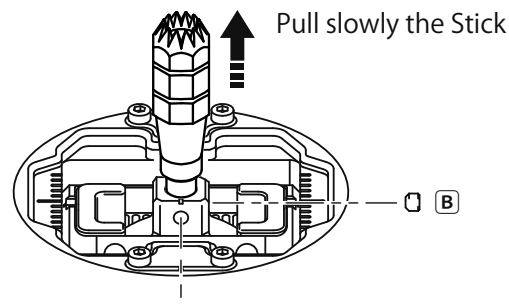
- 1) Remove the four screws [A] .
- 2) Remove the two horizontal angle control block covers [B] .
- 3) Remove the horizontal angle control blocks [C] .
- 4) Securely fit the projections of the horizontal angle control blocks [C] into the grooves for the horizontal angle control blocks.  
The stick movement angle can be adjusted in five levels by selecting which grooves to use.
- 5) Put the horizontal angle control block covers [B] on the blocks and securely tighten the screws [A] . Applying a small amount of a thread lock to the screws is recommended to prevent them from loosening (eg JR screw lock soft type - red).

- 6) After changing the position of the horizontal angle control blocks, be sure to carry out stick calibration (see page 5-10).

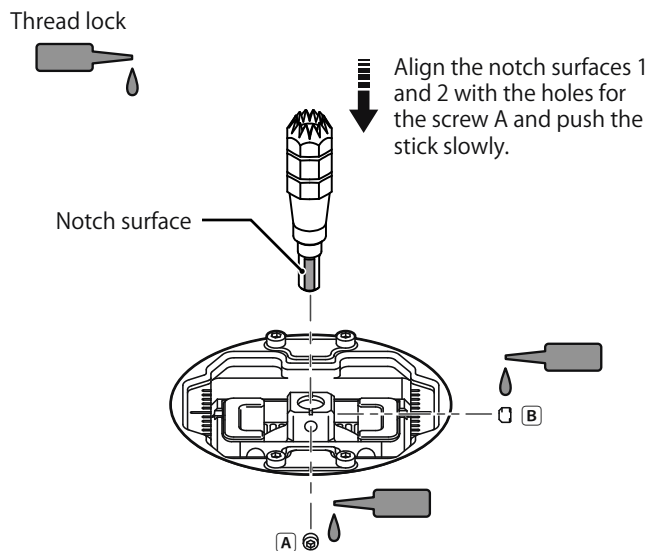
## Removing and installing the stick

### Removing method

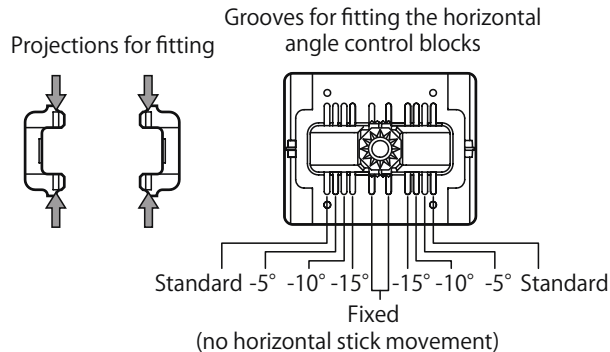
- 1) Remove the socket screws [A] and [B] ..
- 2) Slowly pull out the stick.



### Installation method



- 1) Insert the stick switch while keeping the notch surface 1 and the notch surface 2 aligned with the hole for the socket screw **A** .  
Forcefully pushing the stick switch may cause damage to the equipment.  
When the stick switch cannot be inserted easily, check the positions of the notches and screw hole and try to insert it again instead of pushing forcefully.  
Confirm that the stick switch is fully inserted.
- 2) Look through the hole of the socket screw **A** to check that the notch surface 1 is in line with the hole.  
Be sure to tighten socket screw **A** first.  
Confirm that the socket screw **A** is tightened, and then tighten the socket screw **B** .  
Be careful not to install the socket screws in the wrong order. If doing so, the center position cannot be set securely.  
Applying a small amount of a thread lock to the screws to prevent them from loosening (eg JR screw lock soft type -red).
- 3) Confirm that the stick switch knob moves smoothly. **see page 5-10** for information on calibrating the stick switch.



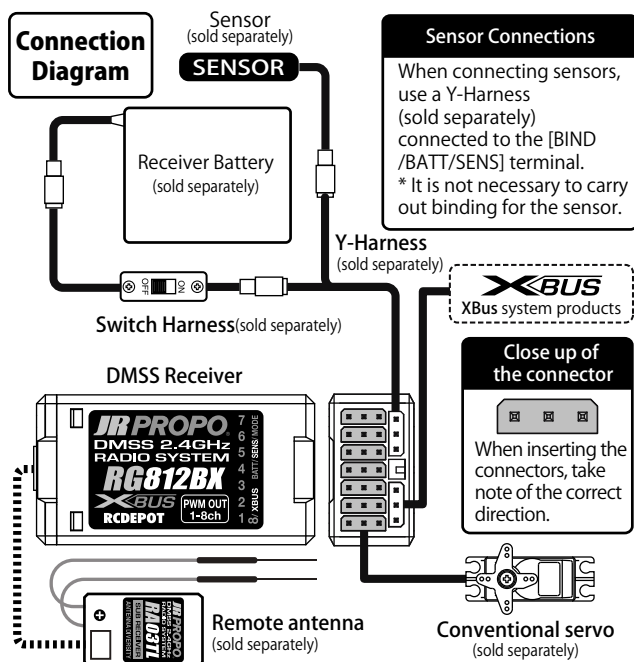
## Receiver connections

### Receiver connections to the servos and the power supply

The channels on the receiver are labeled with names rather than numbers. These will not always match the names of the required functions, depending on how you have configured the transmitter.

With reference to the transmitter monitor (page 4-55) and channel setting (page 5-15) screens, it is easy to confirm the output position of each servo.

If using more than 8 channels, optional XBus servos or XBus to PWM converter harnesses make expansion easy. Please refer to XBus information on the JR website.



- ※ We recommend using a remote antenna when the receiver is mounted on an aircraft where signal reception conditions are poor, such as one made of carbon.
- ※ When using a remote antenna, be sure to carry out the binding process with the remote antenna connected.

Since all receivers are sensitive to vibration, shock, and water, anti-vibration and waterproofing measures should be implemented as necessary.

If the connectors become detached while flying, there will be a risk of the model crashing. Please securely insert all connectors as far as they will go.

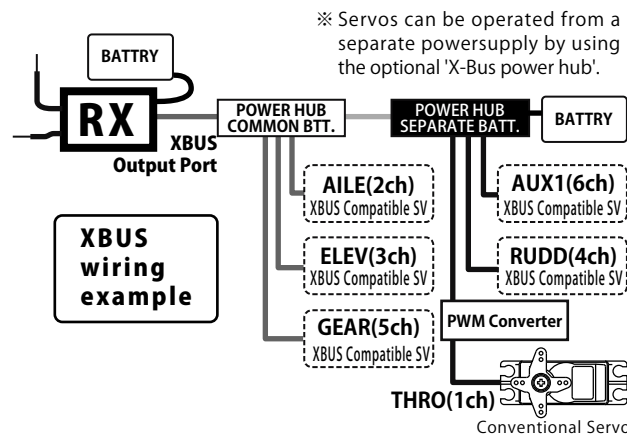
If extension leads are used during installation, sticky tape should be wrapped round the connectors to secure them, or commercially available safety clips used. Be absolutely sure not to leave the connectors hanging unsupported.

### Connections to the receiver

The connections to the receiver vary widely depending on your model setup. The monitor screen (page 4-55) and channel setting menu (page 5-15) can be used to help identify exact servo connections. Always carefully check each function and switch before flying.

### About XBus

- The XBus system employs a serial data transmission method with products supporting XBus instead of control using PWM signals which have conventionally been employed for radio controlled aircraft. The XBus signals contain all channels. Each device selects data that is assigned to it and respond according to the data.
- Before connecting XBus products, carry out channel assignment using the transmitter or other devices. Otherwise, the devices will not respond to the signals. Do not directly connect conventional PWM devices to the XBus output. Doing so may result in damage.
- The power supply can be separated using an optional JR XBus hub for separate power supply.



## ■ List of receiver connecting channels

| Receiver | Helicopter | Airplane | Glider |
|----------|------------|----------|--------|
| 1) THRO  | THRO       | THRO     | LAIL   |
| 2) AILE  | AILE       | AILE     | RAIL   |
| 3) ELEV  | ELEV       | ELEV     | ELEV   |
| 4) RUDD  | RUDD       | RUDD     | RUDD   |
| 5) GEAR  | GYRO 1     | GEAR 1   | AUX 05 |
| 6) AUX1  | PIT.       | FLAP     | FLAP   |
| 7) AUX2  | AUX 07     | AUX 07   | SPOI   |

## ■ Installing telemetry sensors

If installing two or more telemetry sensors, be sure to use the telemetry sensor adapter.

※ It is not necessary to bind the telemetry sensors.

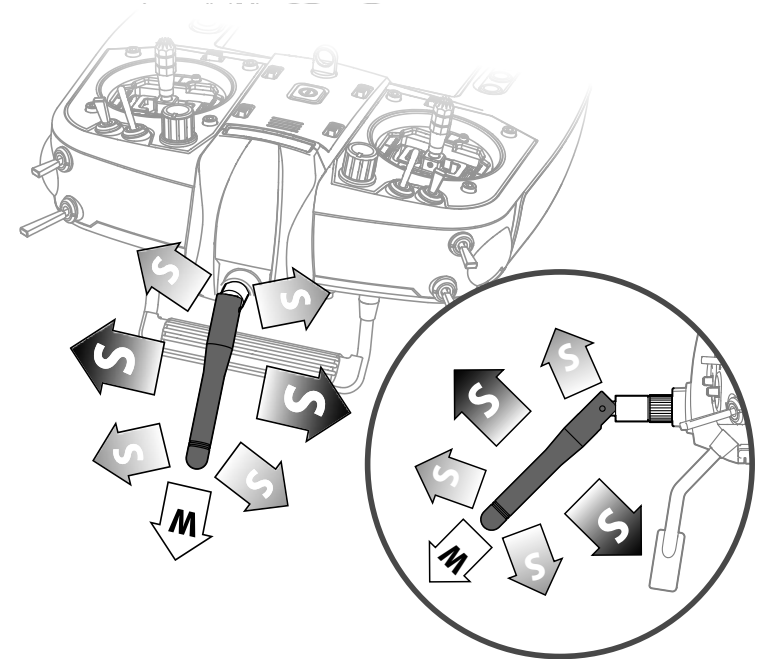
## ■ 2.4GHz RF characteristics

The 2.4GHz band radio waves are very directional. The receiver signal is very dependent on the direction of the transmitter and receiver antenna. Since the antenna receives radio waves from the sides rather than from the tip, please appropriately position the receiver antenna when installing the receiver in the model.

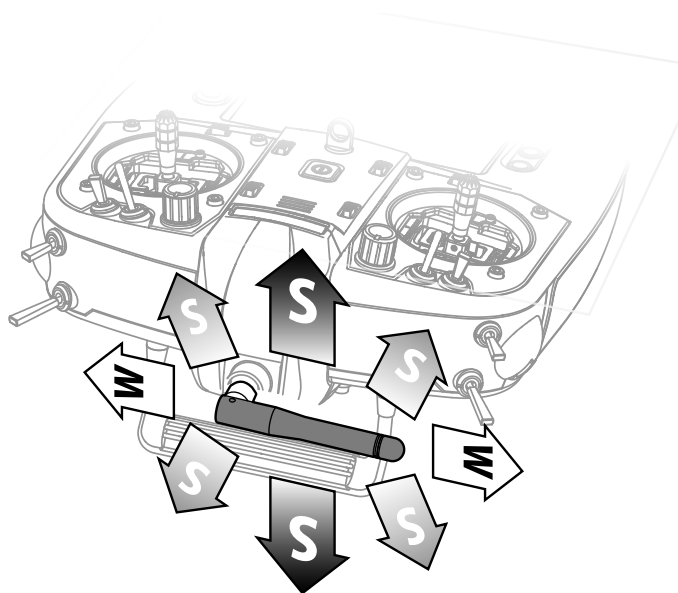
### ■ Transmitter antenna orientation

Because the strongest radio wave radiate from the sides of the antenna, this orientation allows the best transmission to the receiver and provides the safest operation.

As strong radio waves radiate from the sides of the antenna, this orientation provides the best transmission to the receiver for those who fly helicopters or airplanes. It is also the suggested orientation for those pilots who hold the radio horizontally.



This position provides the best signal to the receiver for those who fly gliders and also those pilots who hold the transmitter vertically to the aircraft.



## Meaning of symbol



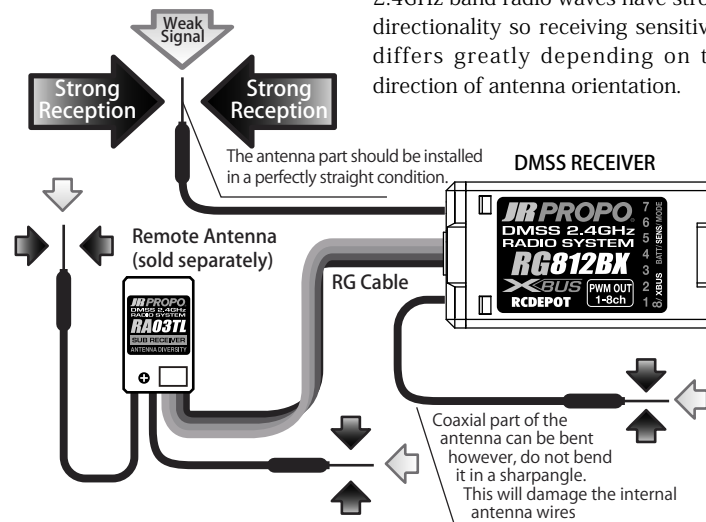
**Strong radio wave**  
Strong radio wave transmitted to the aircraft, helicopter, etc.



**Weak radio wave**  
Radio wave is weak.

## Receiver antenna considerations

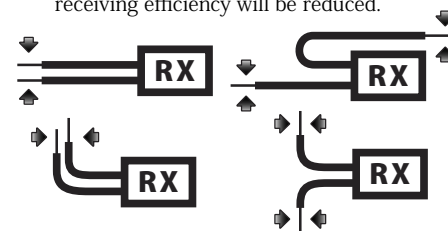
2.4GHz band radio waves have strong directionality so receiving sensitivity differs greatly depending on the direction of antenna orientation.



If the antenna is attached directly to a shielding material such as carbon or metal, the receiving sensitivity of the antenna is also considerably reduced.

## × Wrong Antenna Installation

If each antenna is installed in parallel, the receiving efficiency will be reduced.

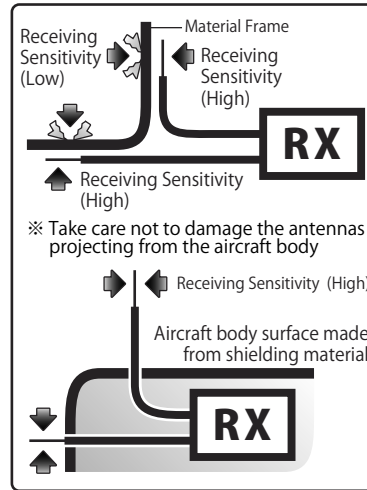


The arrows show the receiving direction with regard to the antenna.

- Multi coaxial antenna type receivers (more than one coaxial antenna extending from the receiver): Be sure to install the antennas at right angles to each other, rather than parallel.
- Single coaxial antenna type receivers: Avoid placing the antenna along a carbon fuselage, or surrounded by metal materials.

## Remote antenna installation

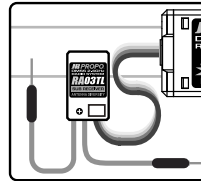
It is possible to use an optional remote antenna with the RG712BX receiver. This is useful when using the receiver in models which are constructed from RF blocking materials such as those including a lot of carbon fiber. The remote antenna RAO1T/RAO2T receives data from the transmitter, and also feeds telemetry data back to the transmitter, so it is highly recommended to locate the remote antenna away from the main receiver unit, ESC, regulator, servos, gyro sensors, harness or power cables, etc to avoid interference.



## Binding procedure

In order for the transmitter and receiver to communicate, it is essential to pair or bind them together. Please follow this procedure:

- 1) Ensure the transmitter and receiver batteries are fully charged. If using an optional remote antenna, be sure this is properly connected to the receiver before binding. Locate the included bind plug.



- ※ Note that when installed, the remote antenna acts as both a receiver and also transmits data back to the transmitter.
- 2) On the transmitter access the 'bind and range' menu under the system menu.

Refer to page 5-13 (BIND & RANGE CHECK)



- 3) Insert the bind plug into the bind terminal of the receiver and connect the battery to a spare channel (such as an aux channel) - the LED's on the

receiver (and the remote antenna if purchased) will begin to blink (ready to bind).

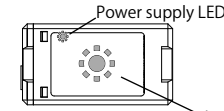
[Example of RG812BX]

Connecting the battery to a spare channel (such as AUX channel)

AUX/XBus Terminal

Switch plug

Battery & Output Mode Switching Terminal



Location of LED light

※ If the bind LED continues to flash, repeat the procedure over again from the beginning.

※ If you use an optional remote antenna, please be sure that the remote antenna is connected during the binding process, and confirm that the remote antenna's LED also changes from flashing to steady lit.

※ **Note:** Be sure to insert the bind plug before connecting the battery.

- 4) Refer to the 'bind and range check' screen on the transmitter. Touch 'bind' to start the binding process.

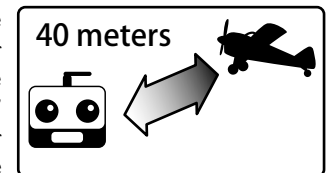


- 5) 'Binding' will display on the transmitter display, and upon completion of the binding process, it will display "SUCCESS! PLEASE CHECK FAIL SAFE". Concurrently, both receiver's LED's will stop flashing and be solid - signifying completion of the bind process. Disconnect the bind plug from receiver, disconnect the receiver battery and switch off transmitter. If the LED's continued to blink, or the transmitter reports timeout, repeat the procedure from the beginning.
  - 6) Lastly, connect a servo, turn on the transmitter then receiver, and confirm that communications have been established.
- Refer to page 5-13 (BIND & RANGE CHECK)

## Range check

This checks the performance of the transmitter by lowering the power output to simulate a long distance range test. Under the 'bind & range check' setting screen (page 5-13), touch under range check and select yes to turn the transmitter power to low.

The transmitter LED will flash blue to indicate it is set to low power mode.



When in this mode, walk a distance of approximately 40m from the aircraft and confirm that the transmitter operates the aircraft normally. Continue testing as you walk around the aircraft. Touch under range check again and confirm yes to return the transmitter to standard transmission power.

### If the bind process or range check is not successful, check the following items

1. Are the transmitter and receiver batteries fully charged?
2. Is the remote antenna securely connected?
3. Is the distance between the transmitter and receiver too close?
4. When the procedure is carried out on the top of a desk or bench top that is made from metal, the binding procedure may not be successful.

### Be sure to configure the failsafe settings after the bind process.

After the bind process, configure the failsafe settings by using the failsafe function of the transmitter and confirm that the failsafe properly works.

Be sure that the failsafe settings are set in the transmitter (page 5-14).



Please note that when the model or model type is changed in the transmitter, re-binding will be required. Never fly the aircraft in range check mode.

## DMSS EZ BIND system



### EZ BIND system

The EZ BIND system is a unique system designed for park flyer receivers. With the EZ BIND system, binding can be carried out without using a binding plug.

### If the power supply for the receiver is switched on prior to the transmitter after binding

If the power supply for the receiver is switched on prior to the transmitter after the bind process is completed, the receiver enters a bind standby state in [3 seconds]. The bind standby lasts in [5 seconds].

If the transmitter for which the receiver is bound is switched on, communication will immediately start.

If the transmitter is changed, communication will not be performed. Be sure



to carry out the bind process again.

### Binding method

To establish communication with a transmitter, binding (pairing) must be carried out. Here, the bind method is described.

1) Display "BIND & RANGE CHECK" in the system list of the transmitter.(see BIND & RANGE CHECK, page 5-13)

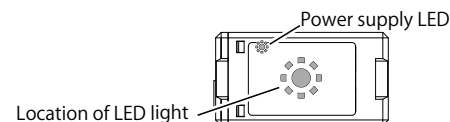
2) Touch on 'bind'. 'Binding...' will be displayed and the bind process will begin.

The transmitter will remain in bind mode for approximately 20 seconds.

3) While the transmitter is in bind mode, switch on the receiver. The LED will start flashing, and it will automatically bind to the transmitter.

When the LED light changes from flashing to solid on, the bind process is complete.

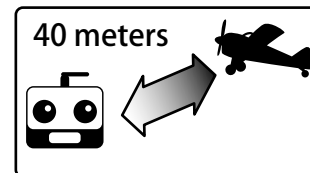
If the bind LED continues flashing, repeat the procedure again from the beginning.



4) Finally, connect the servos and confirm they work as expected.

When conducting a range test, place the aircraft approximately 40 meters from the transmitter, and select low power output mode in the transmitter. Walk around the aircraft, and check that the aircraft can be operated from any position.

see page 5-13 (BIND & RANGE CHECK).



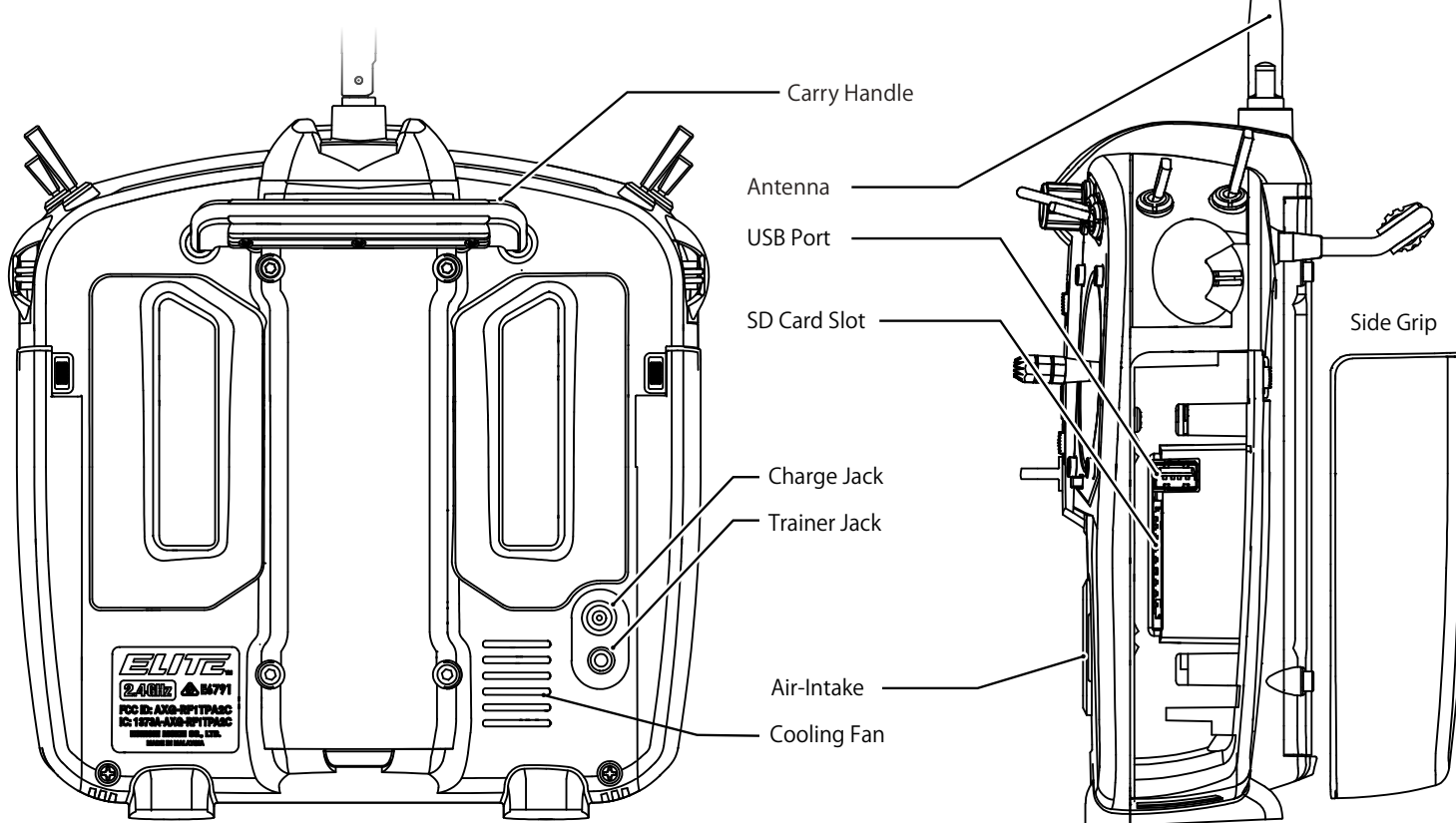
### In normal use, be sure to turn on the transmitter before the receiver.

Turning on the transmitter first ensures the receiver does not enter ez-bind mode. If the receiver happens to enter this mode, it could become bound to another transmitter if it was close by in bind mode.



3-9

- Touch screen
- Home key
- Submenu key
- Back key



## Names and functions of the input keys

### Touch screen

This transmitter employs a touch screen. When programming the transmitter, almost all operations can be performed very intuitively using the touch screen. There are also three standard button keys.

### Return key for Category Top

This key is not intended to return to the previous menus, it is the key to return to the Top menus of the function list, while setting the function menus. In addition, while you are setting the System menus, this key shall return you to the System Top menus. Likewise, while you are setting the home screen's APP configuration (location), when you hit this key, it returns you to the Home screen.

### Submenu key

- Pressing this key while on the home screen gives access to the wallpaper and system settings menus.
- Pressing this key while within a function gives access to various submenus (if available).

### Back key

Pressing this key returns the display to the previous screen. This is very useful when programming various functions.



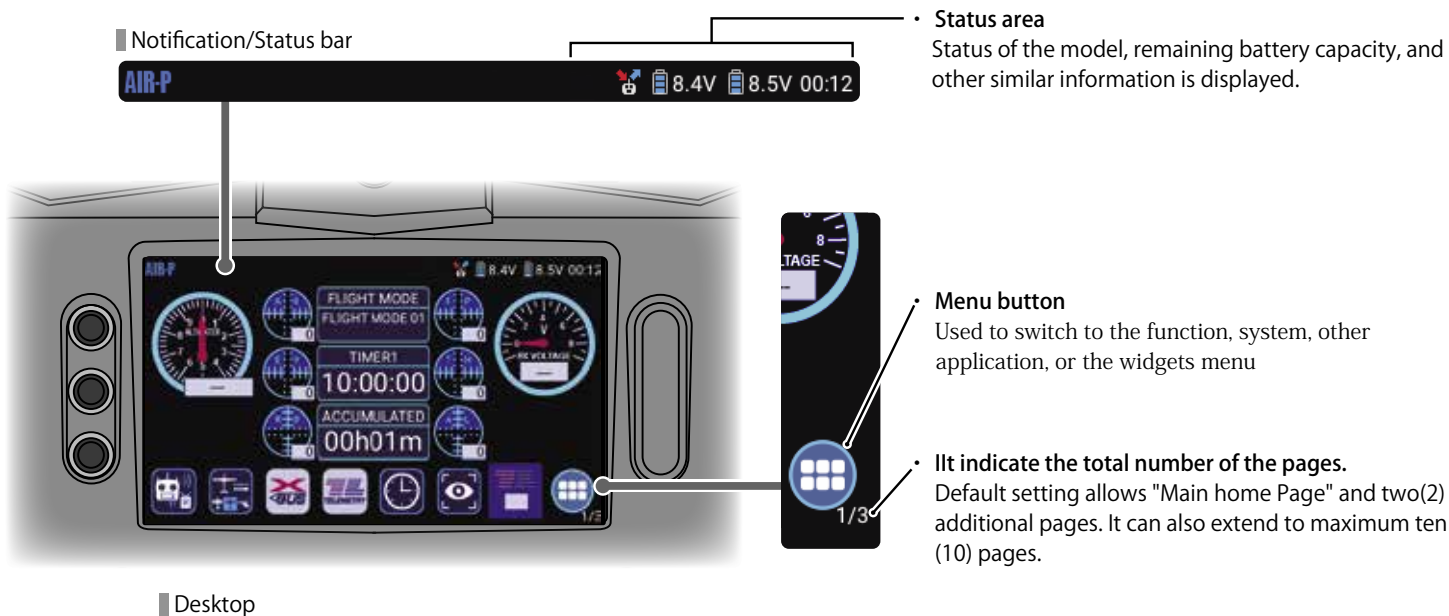
## Home Screens



●By Swiping the screen to the right, it can restore 10screens page.

The transmitter features a main home screen as a maximum of 10 additional home screens including one main home screen, which can be used for a variety of purposes. The various home screens are accessed by 'swiping' the screen left and right.

Widgets can be added to each of these screens – see page 8-1 to learn all about widgets. These widgets allow the display of information during flight – such as trim positions, telemetry data, etc.



In this area, items such as shortcuts to the function, system, other applications and widgets displaying telemetry can be placed.

## About items and widgets

### ※ 1 • • • Icons

An icon refers to a shortcut to an application from the function/system/other lists, and it can be placed on the home screen or dock bar. By touching the icon, you can activate and use the function.

### ※ 2 • • • Widgets

A widget refers to a function that can be placed on the home screen, for example, to display current flight mode or telemetry values, or a small program, such as a calculator or Music Player.

- For details about placing these items on the home screen, **see Adding items to the home screen, page 3-13.**

## ■ Registry of items & widgets to the home screen.

1) Display the home screen where you would like to place an item. If there is no space to place the item, make a space by, for example, removing unnecessary items.

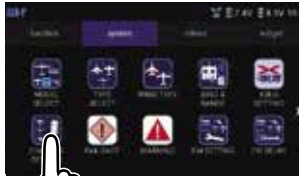


Application Menu Button

2) Touch the application menu button to display a screen for selecting function/system/other/widgets.

Touch and hold an icon you would like to place on the home screen.

The shortcut of the icon becomes movable, and the screen is changed to the home screen.



3) Move the icon to your favorite position on the home screen. When you release the icon, it will be placed on the selected home screen.

If you would like to place the icon on the next home screen (to the right page)

while the icon is movable, move the icon to the right edge of the screen. The main home screen will be changed to the next page.



## ■ Removing items from the home screen

1) Touch and hold an icon you would like to remove then “Cut” shall be displayed.



ON 2x2  
Upper Top Left



ON 2x1  
Left Hand Side



2) Touch “Cut” thence icon shall be removed.



△ Even if an icon of a function is removed from the home screen, the function itself is not deleted

△ **Note:** When you place a complete new icon move to the right hand side, shall create the complete new page automatically.

※ Display forms (size or shape) of icons for timer, trim, and other widgets can be selected. Touch the icon to display the sub window and the selection dialog, and select your favorite display forms

# ■ OS setting menu

Under the "others" of settings, the basic menus of the Operating System displays the settings menus. Here you can adjust the time, select the language, and set the vocal sound.

## ■ System settings

Basic functions controlled by the operating system (Android), such as vibration, screen brightness, and sound volume, can be set here.

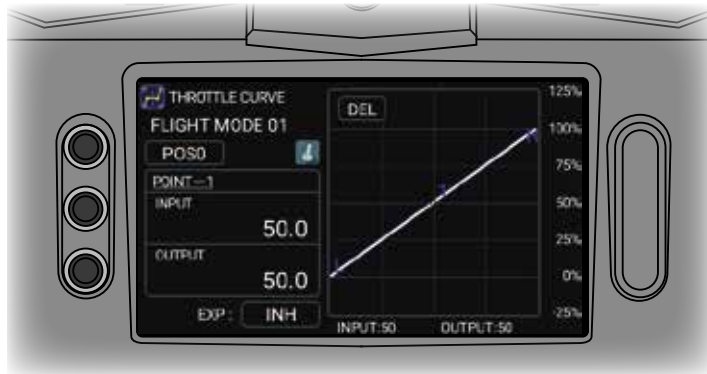
### ■ Device

- Sound
  - ▶ Volume  
Used to change the volume of sound that is controlled by the Android OS.
  - ▶ Notification
  - ▶ Alarm  
Vibration: Unchecking the checkbox will stop vibration notifications.
  - ▶ System  
Sound when locking a screen, or vibration for touch conformation: if not required, uncheck the checkbox.
- Display  
Screen brightness: Move the slide bar left or right to change the brightness of the screen.  
Wallpaper: Home screen wallpaper can be changed (See Wallpaper above).  
Sleep: When the time elapses without any screen operations, the screen display will turn off.
- Language and input  
Keyboard and input method  
Default: English  
For Japanese input, touch "**default**" to change it to Japanese.
- About Propo  
Used for updating.  
Be sure to save the file downloaded from the JR website to an SD card and insert it into the transmitter.  
If you touch the software update area, the update will automatically begin.

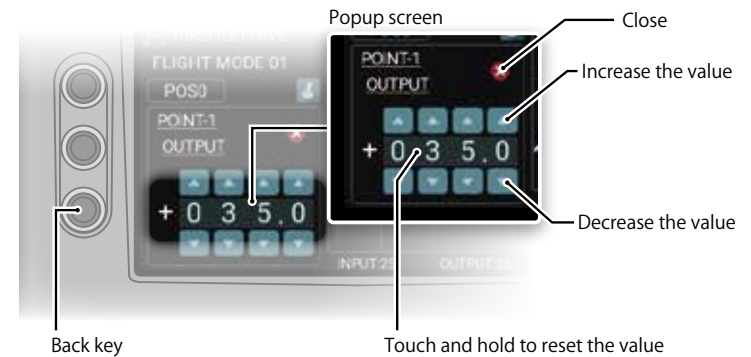
## Mixing curve

The mixing curve is formed by a horizontal axis which represents input (for example, the position of a stick or lever on the transmitter) and a vertical axis which represents output (actual servo movement).

- To add a point, move the red vertical line to the desired position by operating the corresponding device and press [ADD]. A point is added at the position where the red vertical line and the curve cross each other.
- When the device is set to the added point on the curve, the coordinate of the point is displayed as INPUT (input) value and OUTPUT (output) value.
- The point can be moved right and left by changing the INPUT value. However, the point L is fixed at 0 while the point H is fixed at 100.
- The point can be moved up and down by changing the OUTPUT value.
- To remove a point, move the red vertical line to the position of the point you would like to remove by operating the corresponding device, display the coordinate values, and press [REMOVE].
- In each mixing curve, up to 10 points can be added. Set the mix by adjusting the coordinates of each point.



## Changing values



In various setting screens, a popup screen for setting a value opens when you touch a value that can be changed, and you can change the value.

- Change the value by touching  $\triangle$  or  $\nabla$  on the popup screen.

► Increase the value . . . . .  $\triangle$

► Decrease the value . . . . .  $\nabla$

Each pair of  $\triangle$  and  $\nabla$  correspond to each digit.

- To reset a value (return it to a default value), touch and hold the value on the popup screen.
- To close the popup screen, touch the "X" mark on the upper right corner or press the back key.

## What are the function and system lists?

The function list contains items which you will commonly change during the setup and trimming of your model. Examples here are dual rate and exponential adjustment, differential adjustment, etc.

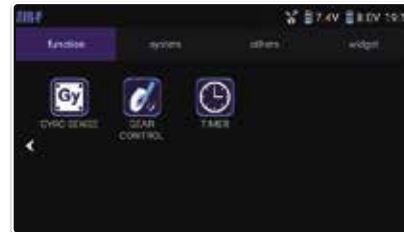
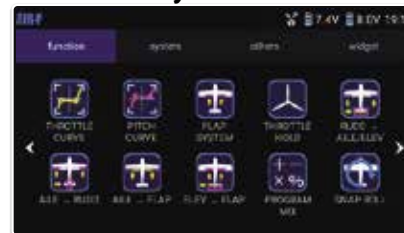
The system list contains items which are set once and then likely to not be changed as you setup the model. For example, in the system list choose the model type, bind your receiver, change transmitter settings like battery alarm voltage, etc.

In this manual we list the function list first, as these are items you would commonly refer to. But when you first set up a model, it would be the system list you would first refer to.

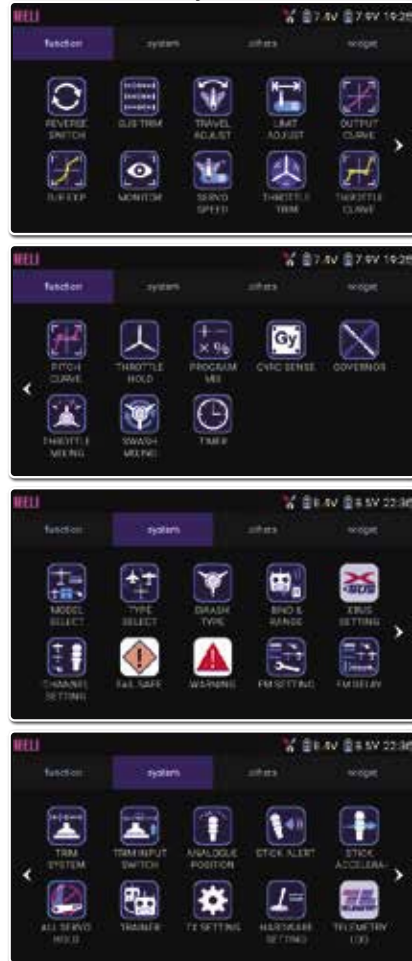
The function list (**page 4-1**) populates three screens, and you simply 'swipe' the screen to change between these. The items on these screens are displayed alphabetically, and will vary depending on the type of model selected (helicopter, plane, or glider).

Continuing to swipe the screen will lead to the system list (**page 5-1**). The system list can be entered directly by touching the 'system' heading on the screen. The items on the system list again vary by model type.

## Airplane function and system lists



## ■ Helicopter function and system lists



## ■ Glider function and system lists



Continuing to swipe the screen will bring up the 'other' menu items (page 7-1). These are related to the Android operating system which runs the transmitters input interface.

## Other



## Widgets



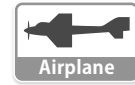
Finally you can access the widgets menu (page 8-1).

Four additional widgets can be placed on this quick access menu to allow easy access to important functions at all times. See page 8-1 to learn all about widgets.

## New model setup

When you create a new model, it is important some basic parameters are defined when you start setting up the model.

### Airplane



- ① Create a new model in the model select menu (page 5-1). Select 'airplane' as the aircraft type. Name the model with a name you can recognize.
  - ② Select XBus if required (page 5-22). XBus is used with the JR Axis gyro system, and when using other XBus products.
  - ③ Plug the bind plug into your receiver, plug in a battery, and bind the transmitter to the receiver (page 5-13).
  - ④ Next select the required wing, tail and throttle types (page 5-17).
  - ⑤ Next define any additional flight modes (page 5-3). Normally the three default modes is enough, but you may wish to redefine the names or switches used to select these modes.
  - ⑥ Next go to channel settings (page 5-15). Here you can move the position of the servo outputs on the receiver. Here you can also define channels as gyro outputs, which must be done before you can use the gyro menu. You can set the gyro values in the gyro menu (page 4-15).
  - ⑦ Now you may wish to setup the throttle stick to start and stop a timer. You need to define the throttle stick as an 'analogue position switch – APS' (page 5-7). You will set the input as the throttle channel, and define the left end as 'off' and the other two positions as 'on'.
  - ⑧ Having done this, go ahead and set up a timer (page 4-53) using the APS to turn it on and off.
  - ⑨ Now you should plug in your servos, and get them working in the correct directions. Use the servo reverse function (page 4-7) to do this.
  - ⑩ Next set the servo arms in neutral. The sub trim function (page 4-6) is useful here.
  - ⑪ Now set maximum servo travel using the travel adjust menu (page 4-4).
  - ⑫ Next setup dual rates and exponential (page 4-1). This function is useful to allow different control responses to be selected in flight. It is common to use the flight mode switch to control all your dual rates at the same time.
  - ⑬ Next setup aileron differential if required (page 4-26). Differential is available if using more than one aileron servo. Most models require slightly more up than down aileron throw to roll in an axial manner.
- This completes the basic setup of an airplane. You may wish to use some of the advanced functionality of the transmitter – set up a throttle curve

for linear motor response ([page 4-9](#)), change the behavior of the throttle trim ([page 4-21](#)), set up the snap roll function ([page 4-25](#)) and continue to explore the radio further.

## ■ Glider



- ① Create a new model in the model select menu ([page 5-1](#)). Select 'glider' as the aircraft type. Name the model with a name you can recognize.
- ② Select XBus if required ([page 5-22](#)). XBus is used with the JR Axis gyro system, and when using other XBus products.
- ③ Plug the bind plug into your receiver, plug in a battery, and bind the transmitter to the receiver ([page 5-13](#)).
- ④ Next select the required wing, tail and throttle types ([page 5-17](#)). This is important, especially on a glider where the wing and tail servo configuration may be quite complex.
- ⑤ Next define any additional flight modes ([page 5-3](#)). Normally the four default modes is enough, but you may wish to redefine the names or switches used to select these modes.
- ⑥ Next go to channel settings ([page 5-15](#)). Here you can move the position of the servo outputs on the receiver. Here you can also define channels as gyro outputs, which must be done before you can use the gyro menu. You can set the gyro values in the gyro menu ([page 4-15](#)).
- ⑦ Now you should plug in your servos, and get them working in the correct directions. Use the servo reverse function ([page 4-7](#)) to do this.
- ⑧ Next set the servo arms in neutral. The sub trim function ([page 4-6](#)) is useful here.
- ⑨ Now set maximum servo travel using the travel adjust menu ([page 4-4](#)).
- ⑩ Next setup dual rates and exponential ([page 4-1](#)). This function is useful to allow different control responses to be selected in flight. It is common to use the flight mode switch to control all your dual rates at the same time.
- ⑪ Next setup aileron differential if required ([page 4-26](#)). Differential is available if using more than one aileron servo. Most models require slightly more up than down aileron throw to roll in an axial manner.

This completes the basic setup of a glider. You may wish to use some of the advanced functionality of the transmitter – set up a motor system ([page 4-39](#)), a brake system ([page 4-41](#)), set up flaperon mixing ([page 4-44](#)), and continue to explore the radio further.

## ■ Helicopter



Most helicopters on the market are flybarless (FBL), and each FBL system requires a unique setup. The following describes the basic setup of a flybar (FB) helicopter, as it describes many of the functions used with many FBL control units.

- ① Create a new model in the model select menu ([page 5-1](#)). Select 'helicopter' as the aircraft type. Name the model with a name you can recognize.
- ② Select XBus if required ([page 5-22](#)). XBus mode A can be used with the JR TAGSmini gyro system (adaptor required). XBus mode B uses the UDI protocol, which is compatible with a variety of other FBL units like the Vbar, BeastX, Skookum and other units.
- ③ Plug the bind plug into your receiver, plug in a battery, and bind the transmitter to the receiver ([page 5-13](#)).
- ④ Next select the required swash type ([page 5-16](#)). Some FBL systems require 'normal' swash selected regardless of the actual helicopter configuration. The JR TAGSmini/TAGSO1 requires the Tx setup to match the actual helicopter configuration. For a FB heli, always choose the actual helicopter swash configuration. This menu also describes the required servo positions when using a FB helicopter.
- ⑤ Next define any additional flight modes ([page 5-3](#)). Normally the four default modes is enough, but you may wish to redefine the names or switches used to select these modes. Note that the throttle hold flight mode (hold) does not have a switch defined. So if you wish to use hold, define a switch using this menu.
- ⑥ Next go to channel settings ([page 5-15](#)). Here you can move the position of the servo outputs on the receiver. You can also define channels as gyro outputs, which must be done before you can use the gyro menu. You can set the gyro values in the gyro menu ([page 4-15](#)). The gyro menu on a FB helicopter would be used to control the gyro rate for the tail gyro. On a FBL helicopter, the gyro menu can be used in several different ways depending on the system being used. Often you may use it for 'bank' or 'setup' selection. This menu is also used to define a governor channel if required.
- ⑦ Now you may wish to setup the throttle stick to start and stop a timer. You need to define the throttle stick as an 'analogue position switch – APS' ([page 5-7](#)). You will set the input as the throttle channel, and define the left end as 'off' and the other two positions as 'on'.
- ⑧ Having done this, go ahead and set up a timer ([page 4-53](#)) using the APS to turn it on and off.
- ⑨ Now you should plug in your servos, and get them working in the correct

directions. Use the servo reverse function (page 4-7) to do this. With most FBL units, you would set the transmitter reverse directions to match the FBL unit.

- ⑩ Next set the servo arms in neutral. The sub trim function (page 4-6) is useful here. With most FBL units, you would set the transmitter sub trim to match the FBL unit.
- ⑪ Now set maximum servo travel using the travel adjust menu (page 4-4). With most FBL units, you would set the transmitter travel adjust to match the FBL unit.
- ⑫ Next setup dual rates and exponential (page 4-1). This function is useful to allow different control responses to be selected in flight. It is common to use the flight mode switch to control all your dual rates at the same time.
- ⑬ Next setup the required pitch curves (page 4-11). These should be set to match your required flight style.
- ⑭ Now setup the required throttle curves (page 4-9). These should be set to match your required flight style.
- ⑮ Again, depending on your setup, the governor menu (page 4-18) may be used to control rotor rpm.

This completes the basic setup of an airplane. You may wish to use some of the advanced functionality of the transmitter – set up a throttle curve for linear motor response (page 4-9), change the behavior of the throttle trim (page 4-21), set up the snap roll function (page 4-25) and continue to explore the radio further.

## Flight modes

### Function explanation

The flight mode function allows switching between various aircraft settings using a single switch.

- Up to fifteen flight modes are possible.
- The default settings vary with model type.
- The flight mode that is currently selected can be confirmed on the home screen using the flight mode widget.

Flight mode display names can be changed in flight mode setup, in the system list (page 5-3).

### Functions that can be selected by flight mode

Almost every function in this transmitter can have multiple options selected by flight mode switch position. Trims, dual rate settings, mixes, etc can all be changed with the flip of one switch. Simply select flight mode as the switch for various functions. This is further explained in the switch selection information on page 3-22.

### Functions relevant for different model types



The functions available in your radio function and system menus vary depending on the selected model type – either airplane, helicopter or glider. In this manual we use the above symbols to indicate for which model types each function is available.

### Display of the current flight mode

The flight mode that is currently used is displayed as a widget on the home screen at the time of shipment (see About items and widgets, page 3-12).

Since a widget is an item that can be deleted from or placed again on the home screen, the display of the flight mode (the flight mode widget) may not be present.

When the flight mode widget is placed on the home screen, the current flight mode can be confirmed. Touching the flight mode widget allows the voice annunciation options to be changed (page 7-4).

The default settings for flight mode switches for helicopter and glider at the time of shipment are different from those for airplanes.

If any changes are necessary, change switch allocated to each flight mode in flight mode setup (page 5-3).



## ■ Helicopter

- Normal mode(NORMAL) . . . . . [K] SW POS0
- Stunt mode 1(STUNT-1) . . . . . [K] SW POS1
- Stunt mode 2(STUNT-2) . . . . . [K] SW POS2
- ▽ Hold mode(HOLD)
- ▽ Stunt mode 3(STUNT-3)
- ▽ Stunt mode 4(STUNT-4)

"▽" indicates a mode that can be added in flight mode setup.

## ■ Expanding flight modes

Add flight modes, such as stunt mode 3 or 4, as necessary.

To add flight modes, touch the add area in flight mode setup in the system list to add modes, and set names, types (only for helicopters), and switches (see FLIGHT MODE SETUP, page 5-3).

※ Hold mode is not allocated by default. Set by changing the type to hold.

※ When conditions are met for several flight modes at the same time, the hold type is prioritized over other flight modes. Priorities for other flight modes can be defined in priority settings.

## ■ Airplane

- Flight mode 01(FLIGHT MODE 01) . . . . . [F] SW POS0
- Flight mode 02(FLIGHT MODE 02) . . . . . [F] SW POS1
- Flight mode 03(FLIGHT MODE 03) . . . . . [F] SW POS2
- ▽ Flight mode 04(FLIGHT MODE 04)
- ▽ Flight mode 05(FLIGHT MODE 05)
- ▽ Flight mode 06(FLIGHT MODE 06)

## ■ Using flight modes

"▽" indicates a mode that can be added in flight mode setup.

\* Priorities for flight modes when conditions are met for several flight modes can be defined in priority settings included in the submenu (see FLIGHT MODE SETUP, page 5-3).

## ■ Glider

- ▲ Launch mode(LAUNCH) . . . . . [C] SW POS1
- ▲ Speed mode(SPEED) . . . . . [K] SW POS0
- ▲ Thermal mode(THERMAL) . . . . . [K] SW POS1
- ▲ Cruise mode(CRUISE) . . . . . [K] SW POS2
- ▽ Landing mode(LANDING)
- ▽ Distance mode(DISTANCE)

"▲" indicates a mode that is included in the default settings.

"▽" indicates a mode that is added in the flight mode setup.

When further expansion of flight modes is necessary, you can add flight modes such as landing.

To add flight modes, touch the add area in flight mode setup in the system list to add modes, and set names and switches.

\* Priorities for flight modes when conditions are met for several flight modes can be defined in priority settings included in the submenu (see FLIGHT MODE SETUP, page 5-3).

## ■ Examples of items that can be changed by flight mode

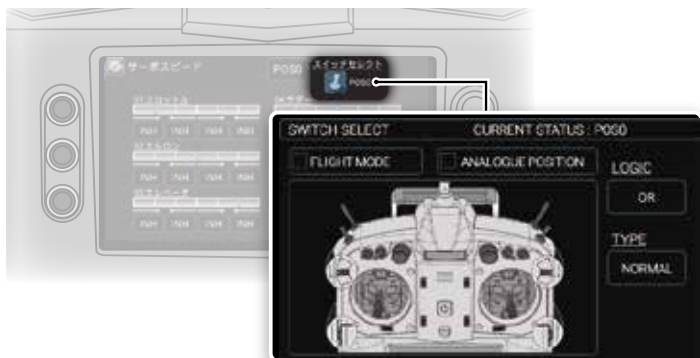
Items that can be changed by flight mode include digital trims and various functions.

When you are in various switch selection dialogues, you can often select flight mode as a switch selection.

## Understanding the switch selection menus

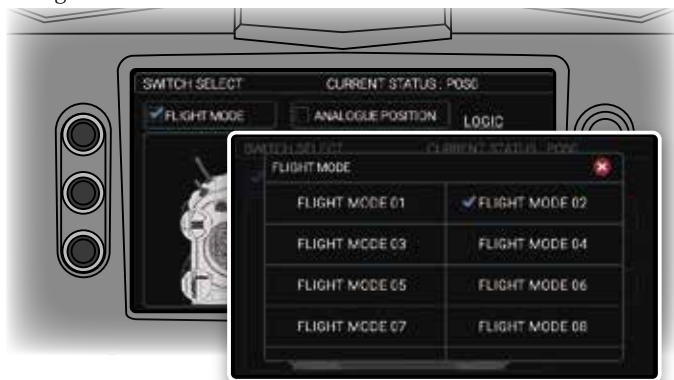
Many of the transmitter functions require you to select a switch or input to use for that function. The switch select dialogues are all very similar, and the following describes their logic.

- You access the switch select screen by touching on the switch icon.



### There are 3 basic types of switches possible

#### ① Flight mode



- Touching the flight mode box allows you to select which flight modes the selected profile will be active in. Multiple flight modes can be selected if you wish.
- Simply un-tick each flight mode if you no longer wish to link the profile to flight mode position.

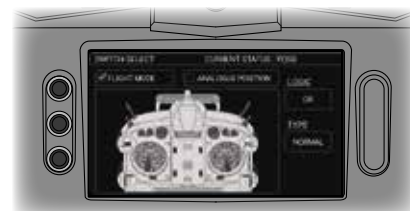
#### ② Analogue position switch (APS)



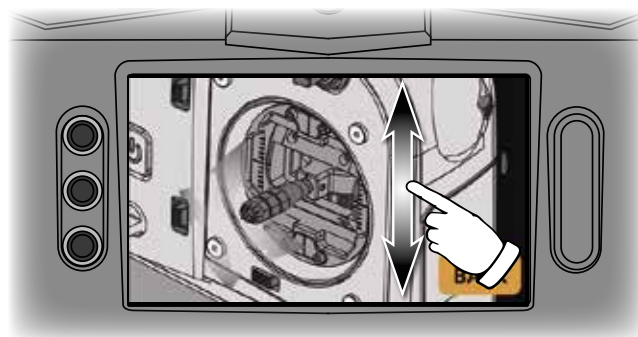
- Touching the analogue position box allows you to select one or more (up to 10) analogue position switches to activate profile selection.
- The analogue position switch needs to be defined in the analogue position menu, [page 5-7](#).

#### ③ Transmitter switches

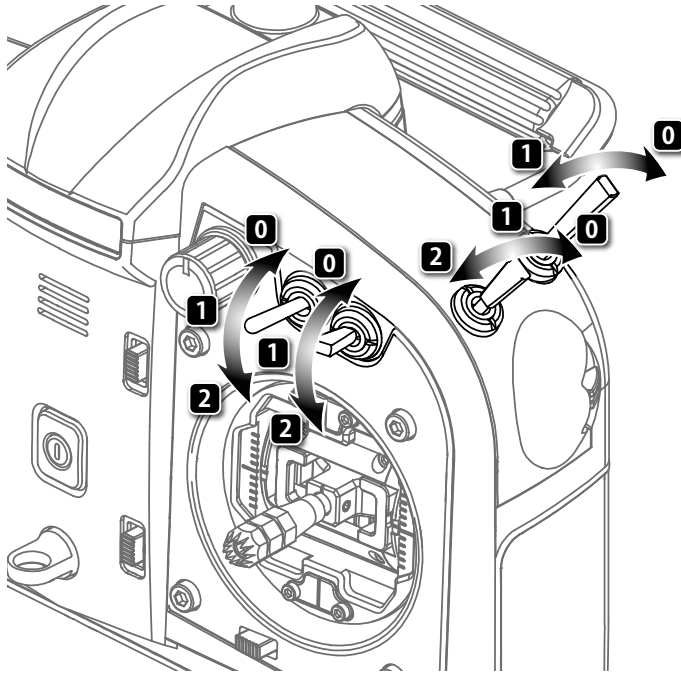
- Touching on the transmitter graphic allows you to select the switch or switches you wish to use for the particular function.



- Touch on the graphic on the switch you wish to select. This will enlarge the picture. Now you can touch the screen and move it around to find the desired switch. Simply touch the switch and select the switch position you wish the function to be active in. The direction of each switch position is shown below.



- Note that the transmitter sticks can be used directly as 3 position switches, or alternatively they can be used as an analogue position switch (page 5-7) with greater flexibility.
- Multiple switches or stick switches (and positions) can be selected.



■ Normal – Possible logics are:



- On The profile is on regardless of switch position
- Off The profile is off regardless of switch position
- Or The profile is active if any one of the switches (flight mode, APS or transmitter switches) is on.
- And The profile is active only when all the selected switches are on.

■ Trigger – Both on and off triggers can be set separately. Possible logics for the on and off triggers are:

- On The profile is on regardless of switch position
- Off The profile is off regardless of switch position
- Or The profile is active if any one of the switches (flight mode, APS or transmitter switches) is on.
- And The profile is active only when all the selected switches are on.

## ■ Switch logic

- First select the type of switching - normal or trigger – both of which have different logics associated with them.





## DUAL RATE & EXPONENTIAL

### Function explanation

This function allows different control throw, exponential and user defined curve settings for aileron, elevator, rudder, and one auxiliary channel, selectable using switches on the transmitter. Exponential is a curve adjusting function that logarithmically changes the servo movement in response to the stick action, allowing the movement in the vicinity of the neutral position to be adjusted from mild (+ direction) to quick (- direction) without changing the maximum control surface angle. Additionally, a user

definable curve function allows up to 8 user definable points to be used to create your own curves, rather than use an exponential setting. Adjustments made can be confirmed by looking at the graph on the screen. A sub menu provides access to a delay function and auxiliary channel selection.



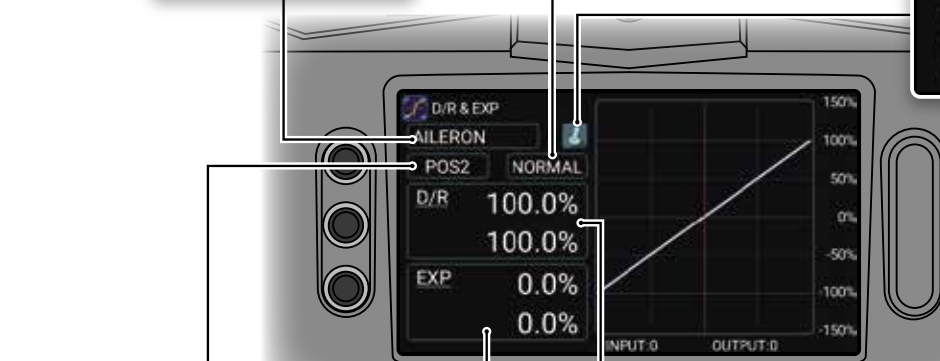
Channel select options



Type select options



Switch select options



ADD/DEL Positions



Exponential amount



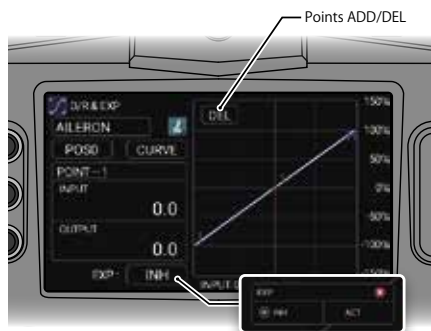
Dual rate amount

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select D/R EXP (dual rate and exponential).
- ③ Next select the channel you wish to set up dual rate and exponential for. Touch the channel select zone, and select from the options given. If you wish to setup dual rates and exponential for an auxiliary channel, you must first select the auxiliary channel in the submenu. Return to the previous screen by pressing the back button.
- ④ Now touch the 'position' indication. From here you can 'add' possible D/R and exponential curves, so you can use up to 15 different D/R and exponential settings. You can also delete any unwanted curves.

Return to the previous screen by pressing the back button.

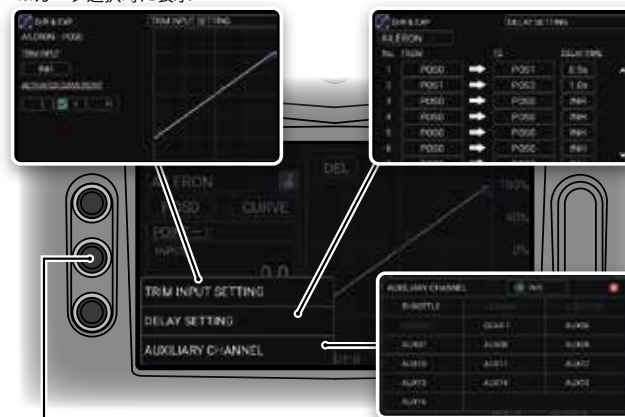
- ⑤ Next click the switch icon. Here you are able to select from up to 15 switches or combinations of switches to select different D/R and exponential curves which you can define. **Refer to page 3-22 (Understanding the switch selection menus)** for a description on how to select various switches.
- ⑥ Now click on the position icon associated with the switch you just selected. Here you can decide which curve will be active when the switch position criteria are met.
- ⑦ Continue setting up to 15 D/R and exponential selections. Use the back button to return to the main D/R and exponential screen.
- ⑧ Select each previously programmed switch position in turn (or touch the 'POSx' indicator and select from the options), and click on the normal or curve icon to select a standard exponential curve, or a user defined curve setting.
- ⑨ Now touch the D/R icon to set the left/right (up/down) total throw for each direction, and also set the exponential settings.
- ⑩ With the control stick in the middle position, settings can be changed for both control directions at the same time. Touching the input area for a couple of seconds returns the values to the default settings.
- ⑪ Alternatively, if curve was selected, you can add up to 8 user defined points to the response curve as well as change the end points of the curve. Points can be deleted or added as required.
- ⑫ The position of these user defined points can be changed by positioning the control stick over a defined point and touching 'Input', and changing the value here.
- ⑬ The value of these user defined points can be changed by positioning the control stick over a defined point and touching 'Output', and changing the value here.
- ⑭ You can also click on "EXP" to activate or inhibit this to smooth the response curve.



## Submenu functions

Pressing the submenu button provides access to the trim input function, a delay function as well as auxiliary channel selection.

※カーブ選択時に表示



Sub menu key

### • Trim input

This option allows a trim input device (see page 5-8) to be chosen to fine tune selected points on the dual rate curve. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the dual rate value using a trim lever, making it easy to fine tune during flight.

This option is only available when 'curve' is selected.

### • Delay

Touching the delay indication opens the delay menu. Here you can program delays between various dual rate settings, so settings change smoothly. Use the 'add' button to add up to ten different delays as required. You can select which dual rate profile change the delay applies to, and set the delay time between 0-10 seconds. Servos operate slowly when transitioning between selected dual rate settings.

### • Auxiliary channel selection

From this menu it is possible to select one auxiliary channel to also apply dual rate and exponential settings for. Simply select the required auxiliary channel from the list of available channels.

Finally, you can touch the channel selection to select the next channel to program D/R and exponential settings for. Once you are finished, press the back button twice to return to the home screen.

### Tips

- When you are in the switch selection dialogue, it is possible to change the priority of dual rate selection. When two or more dual rate settings are active (on), the highest up the list (closest to #1) is selected as active automatically. To move a particular dual rate selection higher up the priority list, simply touch on the number, and then 'yes' to move. This moves the particular dual rate one position up the list. continue in this manner to move it higher up the list as required.
- The dual rate setting numerical value can be between 0 and 150%, and expo can be between 0 and  $\pm 100$ .
- To reset a numerical value to default, simply long touch on the value.
- By moving the appropriate control stick, the numerical values can be independently changed for left and right (up and down), so that the control surface angles and curves can be individually adjusted.
- Typically you may decide to use a flight mode switch to control D/R and exponential setting for ailerons, elevator and rudder simultaneously.
- The D/R function is useful for allowing high control throws for maneuvers such as snaps and spins, and lower control throws for general flying

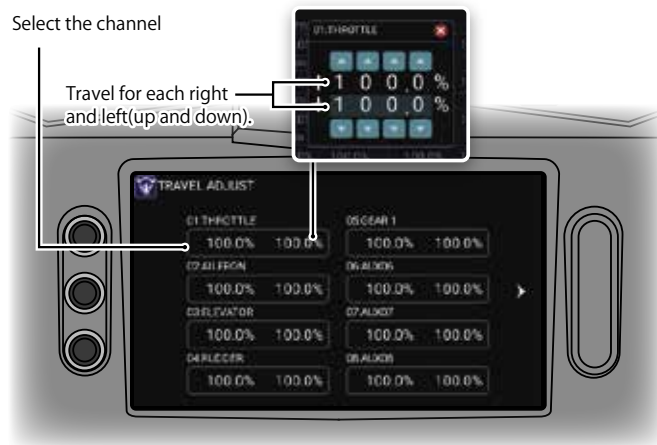
### ■ Caution note

- Operate the servos and switches and carefully confirm the operational settings before flying.



## TRAVEL ADJUST

### Function explanation



This function allows independent adjustment of the servo left/right (or up/down) movement for each channel. The adjustment is carried out with reference to the neutral position. Adjustment is possible over an adjusting range between 0 and 300% in each direction. Although servo movement is limited to  $\pm 150\%$ , a setting of  $\pm 300\%$  is available. The reason for this is, particularly on some gliders, large amounts of sub trim are used for various functions. Having a large travel adjust available allows the full servo travel to still be utilized. The default value is 100%, and this gives standard servo movement.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select travel adjust.
- ③ Next select the channel you wish to change travel adjust values for. The channels are displayed over two screens – touch the arrows to change between screens.
- ④ With the control function in neutral, both left/right (up/down) endpoints can be changed together.
- ⑤ By moving the appropriate control stick, the numerical values can be independently changed for left and right (up and down), so that each endpoint can be individually adjusted. The value can be reset to default by

touching the number for approximately one second.

- ⑥ Return to the previous screen by pressing the back button.
- ⑦ Depending on functions activated, occasionally it will not be possible to set travel adjust. For example, any gyro gain channels will only be controlled by the gyro gain menu, and travel adjust will not be available.
- ⑧ After selecting each channel and setting the travel adjust values, return to the home screen by again pressing the back button.



### Tips

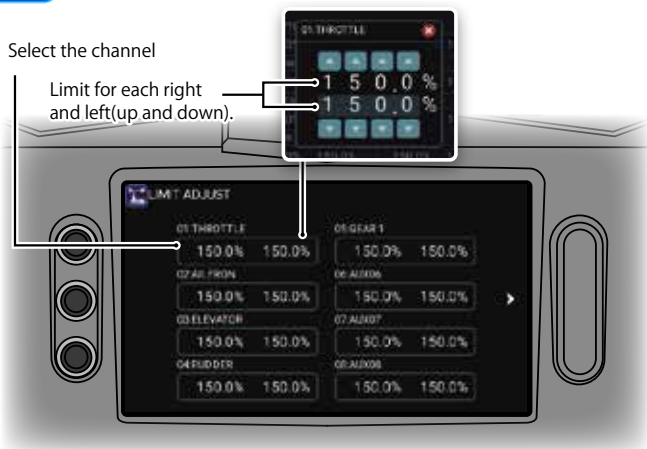
- Try and modify servo arm length so the travel adjust values remain around 100%. This will help maximize servo speed, resolution and power at the control surface.
- In special circumstances, extreme travel adjust values may be used (up to 300%). However, under normal conditions, travel adjust values should remain less than 150%.
- To reset a numerical value to default, simply long press on the value.

### Caution note

- Operate the servos and carefully confirm the control surfaces move as expected before flying.



## LIMIT ADJUST



### Function explanation

When multiple channel mixing is used, the resultant servo movement angle may become too large and the linkage or control surface may jam, causing the servo to stall, and an unreasonable force be applied to the linkages. If limit values are set, it is possible to limit the maximum movement of the servos, regardless of programmable mixing, etc. The limit can be set independently for each direction, over a range of 0-150%.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select limit adjust.
- ③ Next select the channel you wish to change limit adjust vales for. Do this by touching the appropriate limit values. The function spans two pages – use the arrows to change between pages.
- ④ With the control function in neutral, both left/right (up/down) endpoints can be changed together.
- ⑤ By moving the appropriate control stick, the numerical values can be independently changed for left and right (up and down), so that each end point can be individually adjusted. Touching a particular limit for more than one second will return the limit to its default value. Return to the previous screen by pressing the back button.
- ⑥ Depending on functions activated, occasionally it will not be possible to

set channel limits. For example, any gyro gain channels will only be controlled by the gyro gain menu, and limit adjust will not be available.

- ⑦ After selecting each channel and setting the limit adjust values, return to the home screen by again pressing the back button.

### Tips

- This function is very handy when programmable mixers may overdrive a servo to the point the servo stalls. Use the limit adjust to provide an appropriate hard endpoint for servo movement.
- To reset a numerical value to default, simply long press on the value. The default values for limit adjust are +/- 150%

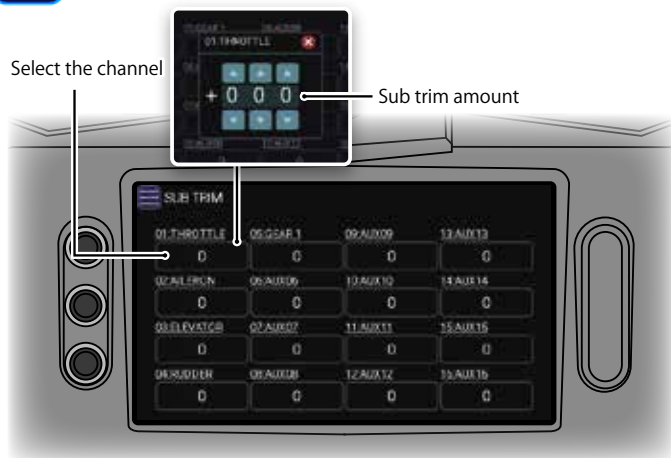
### Caution note

- Operate the servos and carefully confirm the control surfaces move as expected before flying.





## SUB TRIM



### Tips

- Be sure to only use minimal amounts of sub trim. First position the servo arm close to the correct position, and then use sub trim to fine tune as required.
- When trimming your model, it is always best to alter the linkage lengths as necessary, rather than use sub trim.
- Extreme sub trim values are available – please use these with caution. In some specific installations these can be very useful.
- To reset a numerical value to default, simply long press on the value.



Helicopter



Airplane



Glider

### Caution note

- Operate the servos and carefully confirm the control surfaces move as expected before flying.

## Function explanation

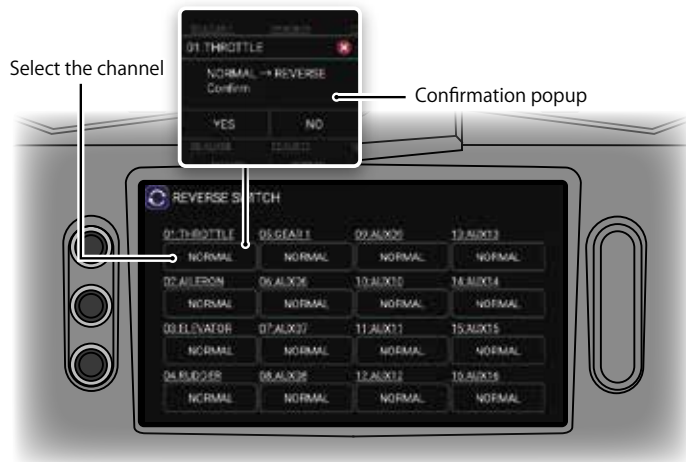
This allows fine trimming of the servos attached to each channel. The sub trim should be used as a fine adjustment when the servo horn angle is not 90 degrees with regard to the linkage. Note that if large amounts of sub trim are used, it will affect the maximum deflection of the servo. It is therefore recommended to use only small values here. The sub trim can be adjusted over a range of +/-512. We would recommend limiting sub trim values to +/-100. Higher values should only be used in specific situations.

## Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select sub trim.
- ③ Next select the channel you wish to change sub trim values for. With the control function in neutral, alter the sub trim as required. Return to the previous screen by pressing the back button.
- ④ Depending on functions activated, occasionally it will not be possible to change sub trim values. For example, any gyro gain channels will only be controlled by the gyro gain menu, and sub trim will not be available.
- ⑤ After selecting each channel and setting the sub trim values, return to the home screen by again pressing the back button.



## REVERSE SWITCH



### Caution note

#### △ Important

Whenever you make changes to the model setup (and reverse switches in particular), please reset the failsafe settings (see page 5-14). For example, if the throttle failsafe had been set to motor cut, and now the throttle servo is reversed, the failsafe setting will now be for full throttle – a very dangerous situation. After completing all transmitter settings, or after changing any transmitter settings, always be sure to set the failsafe again and check correct operation.



### Function explanation

This function reverses the servo operating direction of each channel.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
  - ② From the function list, select reverse switch.
  - ③ Under each channel is an indication of current channel direction – either 'normal' or 'reverse'. Touch this indication to change the servo direction for the required channel. You will then need to confirm this change by touching on 'yes'.
  - ④ Depending on functions activated, occasionally it will not be possible to set channel reverse. For example, any gyro gain channels will only be controlled by the gyro gain menu, and reverse will not be available.
  - ⑤ After setting the servo directions, return to the home screen by pressing the back button.
- ※ The channel names on the screen will differ according to the model type.



## SERVO SPEED



### Function explanation

This function slows down the operation speed of the servos independently for each channel. This function should be considered as a speed limiter. The speed setting can be set separately for left/right (up/down), and different speeds can be set for servo travel away from neutral, and then returning to neutral. Additionally, two different speed profiles can be set and controlled using optional switches, including a programmed throttle position switch.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select servo speed.  
There are 3 pages of servo speed selections – use the left and right arrows to change between the screens.
- ③ Depending on functions activated, occasionally it will not be possible to change servo speed. For example, any gyro gain channels will only be

controlled by the gyro gain menu, and servo speed will not be available.

- ④ Two different servo speed profiles can be selected. First select a switch for choosing between these two profiles. Touch the switch icon and select a switch or switches in the usual manner. **see page 3-22** for information on switch selection. Use the back button to return to the previous screen.
- ⑤ Next select the profile you wish to modify. Either select the profile using the switch you have selected, or touch the 'POSx' indicator, and select from the available options.
- ⑥ Under each channel is an indication of current servo speed. 'inh' means the servo is being moved at its fastest speed. A slower speed of 0.1-10 seconds over half the servo travel can be set. This indicates the time that the servo takes to rotate through 60 degrees. Note there may be some slight variation depending on the servos used. The servo can be slowed independently when moving to the left or right (up or down) and also have an independent speed set when returning to neutral from either direction.
- ⑦ After setting the servo speeds, return to the home screen by pressing the back button.

※ The channel names on the screen will differ according to the model type. This function cannot move a servo faster than its rated maximum speed. 'inh' (inhibit) means the servo is being moved as fast as it can. The slowest programmable transit speed for half the servo travel is 10 seconds.

### Tips

- Depending on the application, some channels may not be able to have a speed set, and '----' will be displayed.
- This function is useful for slowing down retracts and flaps. It would not normally be recommended to slow down any primary control function.

### Caution note

When the servo speed has been set, carefully confirm the servo speeds using actual switch operation before flying.



Helicopter



Airplane



Glider

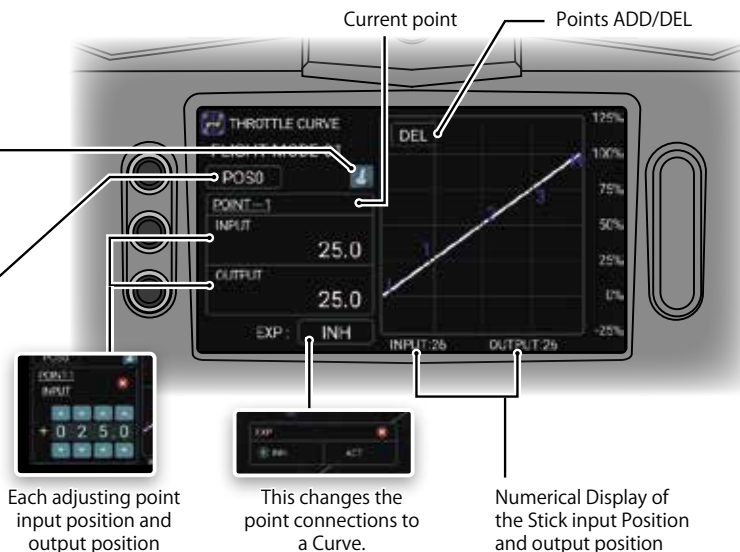


## THROTTLE CURVE

Switch select options



Current Flight Mode position



Each adjusting point input position and output position

This changes the point connections to a Curve.

Numerical Display of the Stick input Position and output position



### Function explanation

This function adjusts throttle servo operation in response to throttle stick operation. The servo position can be set independently for a maximum of 8 point positions. In addition, an EXP (exponential) function can be activated to smooth the curve between the programmed points. Several different throttle curves can be programmed, and selected from a wide variety of switches. This function can set a maximum of 15 different throttle curves, both for airplanes and helicopters. Additional options are available from the submenu, depending on the model type, including delay to smooth the transit between curves, trim input settings, hover throttle setting, throttle trim offset and curve type selection.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select throttle curve.
- ③ Up to 15 different curves can be programmed. First touch on 'POSx' and add curves as required by touching 'position add'. Curves can be removed by touching 'position delete'. Use the back button to return to the previous screen.
- ④ Now touch the switch icon to define switches to activate the required

throttle curves. Select a switch or switches in the usual manner (see page 3-22).

- ⑤ Next select the curve you wish to modify. Either select the profile using the switch you have selected, or touch the 'POSx' indicator, and select from the available options.
- ⑥ There are three initial curve points set at the low, center, and high positions. To add a point, set the throttle stick to the desired position and press "ADD" on the screen. To delete a point, position the throttle stick so the point is highlighted, and press "DEL" on the screen.
- ⑦ To change values at each point, position the throttle stick at the desired point, and click on 'output' to change the value at that point.
- ⑧ The position of the points can be fine-tuned by pressing 'input', and then changing the horizontal position of the point.
- ⑨ The 'EXP' function can be activated to smooth the throttle curve between points. Simply touch on 'INH' and change to 'ACT'.
- ⑩ Pressing the sub menu button allows the setting of several other options depending on the model type. Further information is given below.
- ⑪ After setting the required throttle curves, return to the home screen by pressing the back button.

## ■ Helicopter

Typical helicopter throttle curves may look like this:

Normal mode (for hovering)



Stunt mode (for 3D)



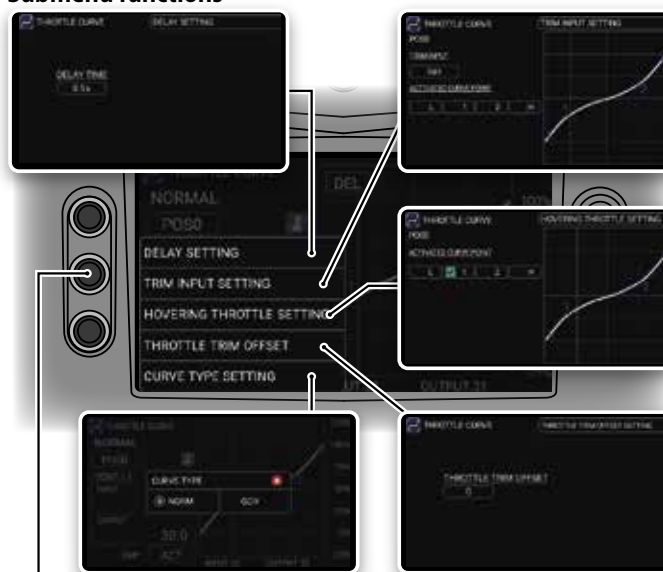
## ■ Airplane



### Tips

- The numerical value 'input' shows the position of the throttle stick and the numerical value 'output' shows the output value to the servo.
- Adjustment is possible over an adjusting range between -25 and 125% for each of the low to high (up and down) directions.

## ■ Submenu functions



Submenu key

Additional submenu features include

- Delay setting  
A delay of 0-10 seconds can be used to smooth transition between various curves. Simply touch the delay option and enter a value up to 10 seconds as required.
- Trim input setting  
This option allows a trim input device ([see page 5-8](#)) to be chosen to change any selected combination of points on the curve. The trim input device must first be defined before it can be activated.
- Hovering throttle setting  
It is possible to choose which curve points will be changed using the hover throttle trimmer.
- Throttle trim offset  
This allows different trim positions on each curve.
- Curve type settings  
This function is useful if you are using a governor which requires a flat line throttle curve. When the setting is changed to 'gov', the throttle curve is automatically changed to a flat line, which you can move up and down.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.

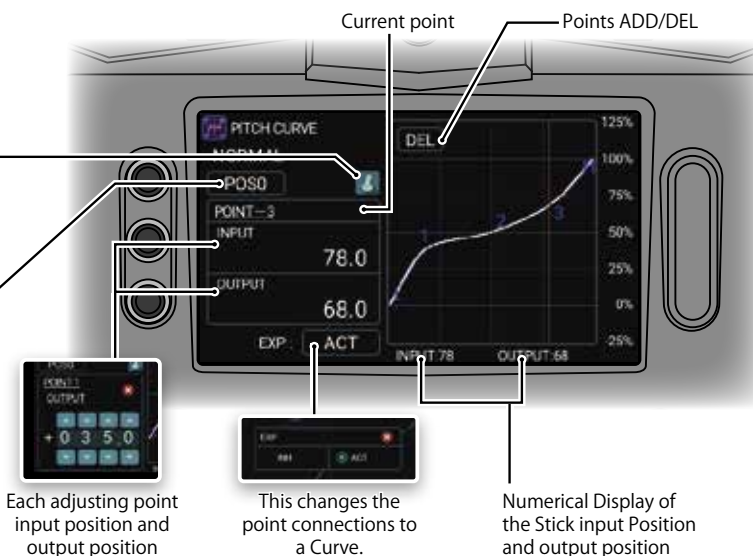


## PITCH CURVE

Switch select options



Current Flight Mode position



Each adjusting point  
input position and  
output position

This changes the  
point connections to  
a Curve.

Numerical Display of  
the Stick input Position  
and output position



### Function explanation

This function adjusts pitch operation in response to throttle stick operation. The servo position can be set independently for a maximum of 8 point positions. In addition, an EXP (exponential) function can be activated to smooth the curve between the programmed points. Several different pitch curves can be programmed, and selected from a wide variety of switches. This function can set a maximum of 15 different pitch curves. Additional options are available from the submenu, depending on the model type, including delay to smooth the transit between curves, trim input settings, high pitch setting, hover pitch setting.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select pitch curve.
- ③ Up to 15 different curves can be programmed. First touch on 'POSx' and add curves as required by touching 'position add'. Curves can be removed by touching 'position delete'. Use the back button to return to the previous screen.
- ④ Now touch the switch icon to define switches to activate the required pitch curves. Select a switch or switches in the usual manner(see page 3-22).
- ⑤ Next select the curve you wish to modify. Either select the profile using the switch you have selected, or touch the 'POSx' indicator, and select from the available options.
- ⑥ There are three initial curve points set at the low, center, and high positions. To add a point, set the throttle stick to the desired position and press "ADD" on the screen. To delete a point, position the throttle stick so the point is highlighted, and press "DEL" on the screen.
- ⑦ To change values at each point, position the throttle stick at the desired

point, and click on 'output' to change the value at that point.

- ⑧ The position of the points can be fine-tuned by pressing 'input', and then changing the horizontal position of the point.
- ⑨ The 'EXP' function can be activated to smooth the pitch curve between points. Simply touch on 'INH' and change to 'ACT'.
- ⑩ Pressing the sub menu button allows the setting of several other options depending on the model type. Further information is given below.
- ⑪ After setting the required pitch curves, return to the home screen by pressing the back button.



## ■ Submenu functions

### ■ Helicopter

Additional submenu features include

- Delay setting  
A delay of 0-10 seconds can be used to smooth transition between various curves. Simply touch the delay option and enter a value up to 10

seconds as required.

- Trim input setting  
This option allows a trim input device (**see page 5-8**) to be chosen to change any selected combination of points on the curve. The trim input device must first be defined before it can be activated.
- High pitch setting  
It is possible to choose a high pitch trim input device, define its sensitivity, and select a switch to turn the high pitch trim off and on.
- Hover pitch setting  
It is possible to define the curve points the hover pitch trim controls.

### ■ Airplane

Submenu features include

- Delay setting  
A delay of 0-10 seconds can be used to smooth transition between various curves. Simply touch the delay option and enter a value up to 10 seconds as required.
- Trim input setting  
This option allows a trim input device (**see page 5-8**) to be chosen to change any selected combination of points on the curve. The trim input device must first be defined before it can be activated.

### Tips

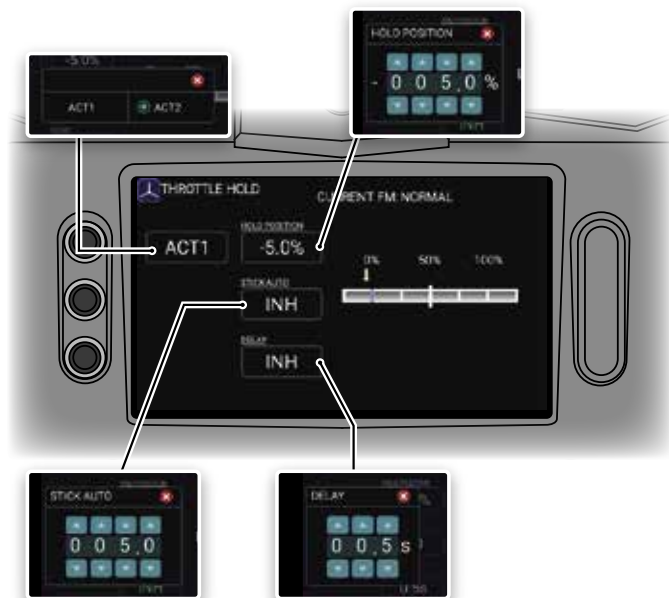
- The numerical value 'input' shows the position of the throttle stick and the numerical value 'output' shows the output value to the servo.
- Adjustment is possible over an adjusting range between -25 and 125% for each of the low to high (up and down) directions.
- In airplane mode, a pitch servo must first be defined in channel setting (**page 5-15**) for the pitch curve function to be active.

### ■ Caution note

After the setting, operate the servos and carefully confirm each of the Flight Mode settings before flying.



## THROTTLE HOLD



### Function explanation

This function is for autorotation landings with helicopters, and can be used as a safety switch while airplanes are on the ground – it places and holds the throttle servo at a low position. Using a selected switch, the engine can be cut, or fixed at an optional slow position. Further, there is also a stick auto function that allows switching of the servo to the hold position when the stick is lowered to a preset position.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select throttle hold.
- ③ After setting the function, return to the home screen by pressing the back button.

### Helicopter

- ① Before being able to use throttle hold, it is necessary to add a switch to the 'hold' flight mode. Please see [page 5-3](#). It is possible to use a switch in any desired switch location.
- ② Two separate throttle hold setups can be programmed. These are called 'ACT1' and 'ACT2'. These are selectable from within the throttle hold function. You may decide to program 'ACT1' as a throttle hold setting for practice – not killing the motor or engine completely. 'ACT2' may be set to completely kill the engine or motor for competition use. You will need to manually select ACT1 or ACT2.
- ③ To change the hold position, touch the 'hold position' area and enter your desired value. Positive values result in idle speeds higher than with the throttle stick at the lowest position. Negative values result in idle speeds lower than with the throttle stick at the lowest position. Be careful setting hold values, especially when using an electric motor.



### Stick auto

When stick auto is activated, the servo will change to the hold position when the stick is lowered past a predetermined point. Initially this function is inhibited. To activate this function, touch on 'inh', and enter a stick auto trigger value.

This value should typically be higher than your hold position. Now if you are at a high throttle setting and activate the throttle hold switch, throttle hold will not activate till the throttle stick is decreased to the stick auto point or below. To 'INH' this function, set the stick auto value to zero.

### Hold delay

It is possible to set a delay to prevent a sudden increase in engine rotations when the hold switch is set to off. The duration of the delay can be set between 0-10 seconds. If the hold delay is set, any throttle setting in the servo speed function will be cancelled.

### Tips

- When using a throttle hold flight mode, it is possible to set dedicated dual rates, pitch curve, etc.
- Always be aware of throttle stick position when you turn off throttle hold.

## ■ Airplane

- ① This function is 'inh' by default. Set the function to 'act' by touching 'inh' and selecting 'act'.
- ② Then enter the hold position value required by touching the value input area and entering a value.
- ③ The hold switch is used by default, but this selection can be modified by touching the switch icon and selecting an appropriate switch(see page 3-22).

### Tips

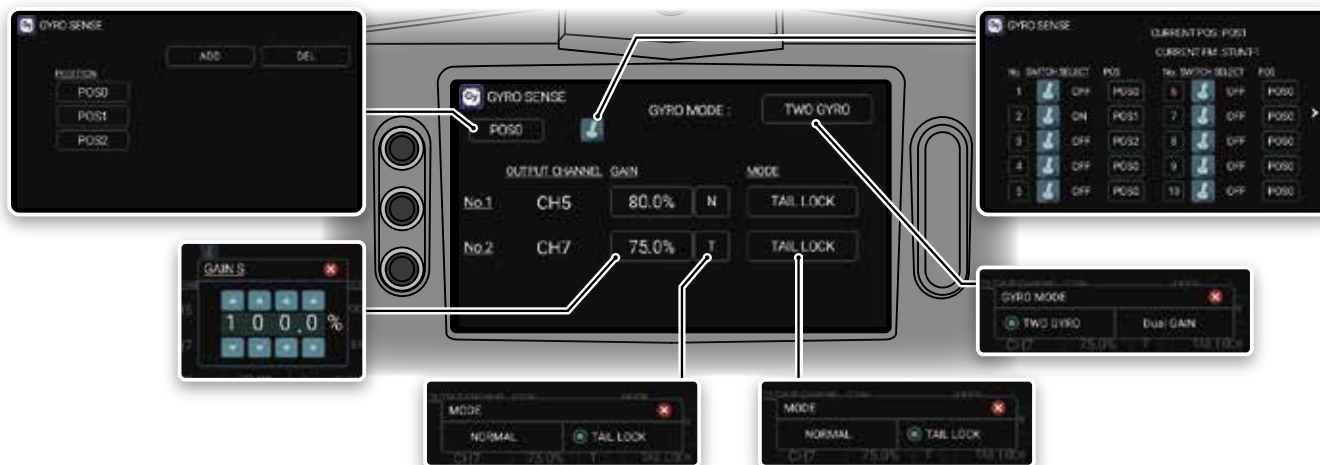
- When using more than one engine (see page 5-17) it is possible to allocate the same or different switches for each motor, and set independent hold points.
- Always be aware of throttle stick position when you turn off throttle hold.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## GYRO SENSITIVITY



### Function explanation

This function controls gyro sensitivity using one or more channels as defined in the system menu, channel setting (page 5-15). It allows adjusting the gyro sensitivity from the transmitter. Further, it supports a special type of 'dual gain' as used by JR's G7000 tail gyro where two channels are required. It also supports two or three separate gyros. In addition, it supports 3 axis gyros such as the JR TAGSO1/TAGSmini for helicopters, and the JR Axis airplane gyro, with separate gains for yaw, pitch and roll axis. The sensitivity switching of each gain can be with individual switches, or combined using the flight mode switch. Note that the exact gyro setup will depend on your gyro or flybarless controller. Many flybarless controllers set the gains within the controller software, and the gyro gain function in the transmitter is simply used to switch between different 'banks' or setups'. You will need to study the manual for your flybarless controller to learn about these details. The gyro submenu gives access to additional functions depending on model type including delay setting, lift up setting and trim input setting. A calibration function is also provided for JR helicopter 3 axis gyros.

### Setting method

#### Helicopter

- ① From the home screen, press the menu button on the touch screen.
- ② It is first necessary to select the number of gyro gain channels to be used. So go to the system menu, channel setting. Here allocate the number of gyro gain channels you require (1-3). See page 5-15 for help with the channel setting menu. If you have not done this, you will get the following error when activating this function.
- ③ From the function list, select gyro.
- ④ Next define how many gyro gain options you wish to use. First touch the 'POSx' indicator. Here you can add or remove gyro gain options, up to 14 separate gain values.
- ⑤ Next touch the switch icon, and here you can select the switch or switches to use for selecting each gyro gain option. Select a switch or switches in the usual manner (see page 3-22). Press the back button to return to the previous screen.
- ⑥ Now select the gyro type. The options available will vary depending on the number of gains selected in the channel menu. With one gain, there are no options. With two gains you can select from 'two gyro' or 'dual gain' – which is used exclusively with the JR G7000 tail gyro. With three

gain settings, only 'triple gyro' is available.

- ⑦ Next set the mode – either tail lock or normal. With dual gain, one gyro channel must be set to normal, and one to tail lock – please refer to the JR G7000 gyro for details. In single or dual gyro mode, normal or tail lock can be selected. If three gains are being used, only tail lock mode is available.
- ⑧ With three gains (tail lock mode), the gain can be set to normal or stunt. With two gains, the mode can be set to T (tail lock) or N (normal). In single gyro mode, when tail lock is selected, N (normal) or T (tail lock) can be used.
- ⑨ The gain is set in the usual manner. Note the differences between normal and tail lock gain values.
- ⑩ Pressing the submenu button allows the setting of several other options. Further information is given below.
- ⑪ After setting the function, return to the home screen by pressing the back button.

#### Single axis gyro

In single gyro mode, the mode can be set to either till lock or normal. In tail lock mode, T (tail lock) or N (normal) can be selected.

#### Two axis gyros

In two gyro mode, the mode can be set to either tail lock or normal. In tail lock mode, T (tail lock) or N (normal) can be selected.

#### Dual gyro gains (JR G7000)

If dual gains are selected, the display changes to allow the easy setting of both gains as required by the JR G7000 gyro. Please see the gyro manual for further information.

#### Three Axis gyros

For 3 Axis gyro applications (such as the JR TAGS01 or TAGSmini) three separate gain channels can be used. Each sensitivity for yaw, pitch and roll axis can be set using individual switches, or combined onto the flight mode switch. The gyro sensitivities can also be changed to normal or stunt modes when using the JR TAGS01/TAGSmini.

#### Airplane

The basic channel setting and overall gyro menu adjustment is similar in airplane mode.

#### Single gyro mode

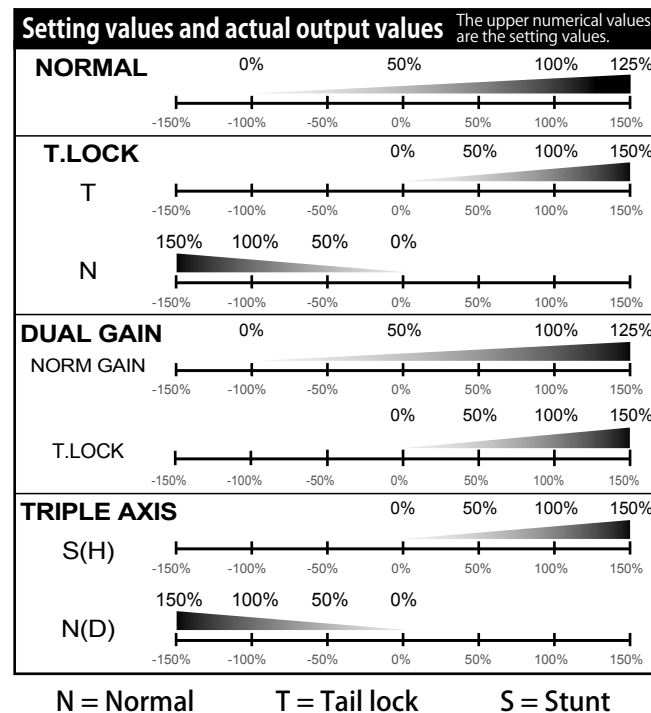
In single gyro mode, the mode can be set to either till lock or normal. In tail lock mode, T (tail lock) or N (normal) can be selected.

#### Two gyro gains

In two gyro mode, the mode can be set to either till lock or normal. In tail lock mode, T (tail lock) or N (normal) can be selected.

#### Three gyro gains

If you are using the JR Axis 3 axis airplane gyro, please refer to the gyro manual in combination with these instructions for information on setting three separate gyro gains for aileron, elevator and rudder. Only tail lock gain is available, and you can select between D (damping) or H (head lock) gains.



## Submenu functions



### ● Gyro delay

To avoid excessive servo hunting when switching the gyro sensitivity from a low to higher sensitivity setting, it is possible to set an up delay on this function. The delay will smoothly change the gain over a defined period of time (0-10 seconds).

Is possible to set a down delay when changing from a high to low sensitivity. The delay will smoothly change the gain over a defined period of time (0-10 seconds).

### ● Lift up (takeoff) setting

The takeoff function allows gyro gains to be temporarily lowered for takeoff. This is possible for single axis and multi axis gyros or flybarless units, but only if the gain is being directly controlled by the transmitter gain setting. First select a switch to activate this function during takeoff – see page 3-22 for information on switch selection. Next enter how much you wish to decrease the gyro gain during takeoff by. Typical values may be -5 to -10%. This gain reduction is then available on a switch, and is especially useful during takeoff with some gyro systems.

### ● Trim Input

This option allows a trim input device (see page 5-8) to be chosen to change any selected gyro gain. The trim input device must first be defined before it can be activated.

### ● Calibration for 3 axis gyros (3 gyro mode only)

The JR 3 axis gyro system (TAGS01 or TAGSmini) as used for Flybarless R/C helicopters requires calibration prior to flying. This is required to recognize the type of CCPM being employed, and learn the servo travel ranges used. Calibration requires precise gimbal stick movement of one function at a time (elevator or pitch stick up & down, and aileron stick right to left). If, for example, the aileron stick is pushed by mistake during elevator calibration, the calibration will be incorrect. In order to avoid this problem, the calibration function allows single channel calibration.

Simply touch 'start' on the function you wish to calibrate. The other two functions will be kept at zero. After you have calibrated the required function, simply touch 'stop'. Repeat this process for all three functions.

## Tips

- Follow and understand the details of the JR TAGS01/TAGSmini 3 axis gyro manual completely prior to using this calibration function.
- By using the trim Input function, it is possible to change the gyro sensitivity values using a trim lever. Therefore, it is possible to easily adjust the sensitivity during flight.

## Caution note

Be sure to understand your gyro manual thoroughly to allow correct use of this function.

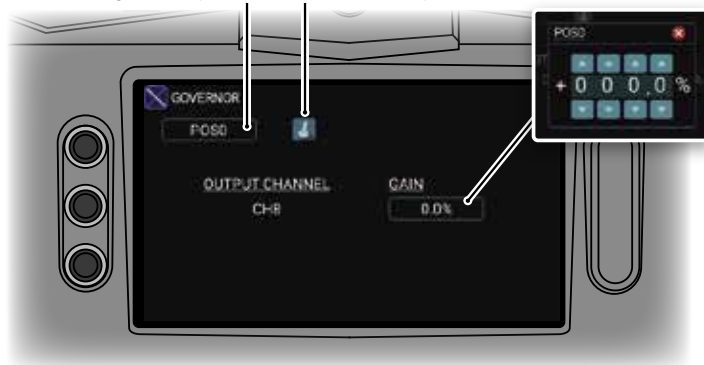
Carefully check the direction of the tail servo and be sure that everything works correctly before flight.



## GOVERNOR

Current Flight Mode position

Switch select options



Submenu key



### Function explanation

A governor maintains the rotor rotation speed at a uniform value. This function sets the rotation speed of the governor to aid in stable flight. Different rpm settings can be made separately for each flight mode.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② It is first necessary to select the channel to use for governor. So go to the system menu, channel setting. Here allocate the governor channel. See

page 5-15 for help with the channel setting menu. Press the back button to return to the previous screen. If you have not done this, the following screen will appear.



- ③ From the function list, select governor.
- ④ Next define how many governor speed options you wish to use. First touch the 'POSx' indicator. Here you can add or remove governor speed options, up to 14 separate speed values.
- ⑤ Next touch the switch icon, and here you can select the switch or switches to use for selecting each governor gain option. Select a switch or switches in the usual manner (see page 3-22). Press the back button to return to the previous screen.
- ⑥ Now set the governor speed (gain) percentage for each governor mode.
- ⑦ Pressing the sub menu button allows the setting of several other options. Further information is given below.
- ⑧ After setting the function, return to the home screen by pressing the back button.

### Submenu functions

#### • Delay

To avoid fast changes in head speed, a delay can be utilized (0-10 seconds) to smooth out requested changes in head speed.

#### • Trim input

This option allows a trim input device (see page 5-8) to be chosen to fine tune the selected governor gain. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the governor speed value using a trim lever, making it is easy to fine tune the rpm during flight.

### Tips

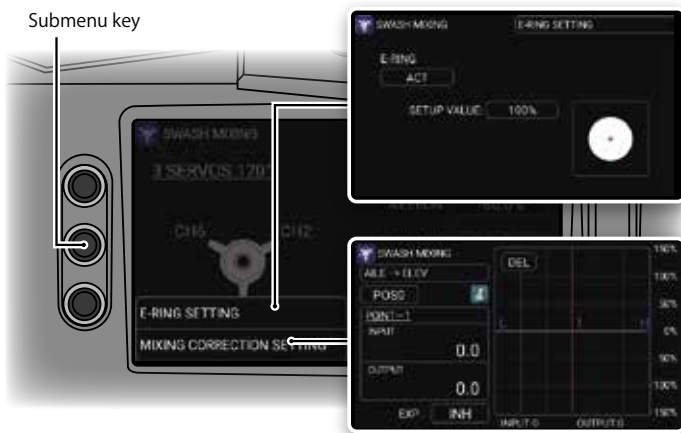
- Always start with a lower value (head speed) and increase as necessary.
- The trim input function is very useful for fine tuning head speed during flight.
- It is possible to link governor speeds to each flight mode by selecting the appropriate switch.
- Note that because the setting from the transmitter is a numeric adjustment, the actual rotation speed should be set and confirmed by using an optical head speed measuring device.

### Caution note

Be sure to understand your Governor manual thoroughly to allow you to use this function correctly.



## SWASH MIX



### Function explanation

This function sets the mixing relating to the swash plate and swash plate servos (1-4) to allow coordinated control of the helicopter. This swash mixing is essential for helicopters that incorporate CCPM systems. CCPM is a type of pitch mixing in which the servos are directly linked to the swash plate. Before using the swash mix function, it is first necessary to set the swash type in the system menu ([page 5-16](#)). Match the swash type in the system list with your helicopters servo configuration. The submenu

allows the use of an electronic cyclic ring and various swash correction settings.



### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② It is first necessary to select the swash plate type. Go to the system menu, swash type. Here select the swashplate configuration which matches your helicopter. [see page 5-16](#) for help with swash type selection. Press the back button to return to the previous screen.
- ③ From the function list, select swash mixing.
- ④ Next, you will be able to set the aileron, elevator and pitch values for swash mix. Note negative values can be used to reverse function direction.
- ⑤ For certain swash types it is possible to activate EXP which acts to correct for servo geometry at extremes of swashplate travel. Note this should not be used with any flybarless unit.
- ⑥ Pressing the sub menu button allows the setting of several other options. Further information is given below.
- ⑦ After setting the function, return to the home screen by pressing the back button.

※ Note that some flybarless systems require the swash type to be set to 1 servo (normal). The JR flybarless systems require the transmitter configured in a traditional manner, using the swashplate configuration used by the helicopter. The default settings for the swash mix are +60% on Aileron, Elevator and Pitch. If necessary, adjust the mixing amount and direction according to the type of helicopter and servo setup.

### Submenu functions

#### ● E-ring function

By activating this function, the e-ring electronically corrects the swash to move in the same angle in all directions. The operation of the stick and e-ring can be confirmed on the graph. The diameter of the circle is the swash tilt angle, which can be set as desired. Simply touch the setup value and adjust as desired. The e-ring should not be used when using a flybarless unit as this function is performed by the flybarless system.

#### ● Correction mixing

These corrective mixers should not be used on flybarless helicopters.

► PIT → AILE, PIT → ELEV

This mix corrects the swashplate in the aileron and elevator axis when the pitch stick is moved up and down. Adjustment of the

mixing amount can be carried out separately to the front and rear and to the left and right. The mix can be switched on and off of using a switch or flight modes as desired.

► AILE → ELEV, ELEV → AILE

This is used to correct interactions where aileron and elevator movement influence each other. The aileron and elevator mutual mixing amount can be separately adjusted. The switching on/off of the mixing on this screen can be set using a switch or flight modes as desired. It is also possible to use trim input to adjust the mix during flight using a trim lever.

These corrective mixing functions are individually programmed in the usual manner. An additional submenu is available within these functions to adjust delay and trim input settings for the individual mixes.

● Corrective mix setup

This example shows the setup of an aileron to elevator corrective mix. The other corrective mixes are programmed in a similar manner.

- ① From the swash mix screen, press the submenu button. Touch 'mixing correction setting'.
- ② To select which mix you wish to adjust, touch on the mix description area (eg aileron to elevator), and select from the available options.
- ③ Now select the switch to activate the two profiles. Touch the switch icon to define switches to activate the two curves. Select a switch or switches in the usual manner (**see page 3-22**). Use the back button to return to the previous screen.
- ④ Select the mix profile you wish to program. Either touch the POSx part of the screen and select the profile to program, or use the switch to select the desired profile.
- ⑤ Now move the aileron stick and add any points to the mix curve. Up to eight points can be added. To add points to the curve, move the aileron stick and press 'add' when the stick is in the desired location to add a point. Typically, it is only necessary to hold full left aileron and add a point, then full right aileron and add a point.
- ⑥ After adding any additional mix points, move the aileron stick to the desired position and touch the output area and change the mix value to elevator as required.
- ⑦ The EXP function can be used to smooth the curve between points. Simply touch on the 'INH' and select 'ACT'.
- ⑧ The submenu button provides additional options to set a delay when changing corrective mix curves to smooth the transition, and a trim input function to allow fine tuning of the mix in flight.

- ⑨ After setting the function, return to the home screen by pressing the back button.

**Tips**

- If the servo direction is incorrect, it is possible to set the mixing amount in a negative direction to achieve an appropriate setting.
  - The setting value in this function should be between 0 to  $\pm 125$ , with a practical range of  $\pm 50$ -70%). If the mixing values are too low, adjust the servo horn hole position inward.
  - With some flybarless systems, the swash mix should be set to 1 servo (normal).
  - With flybarless systems, the e-ring function and corrective mixing should not be used in the transmitter and instead fine-tuned in the flybarless unit.
- ※ Note that swash phase adjustment is performed in the swash type menu (system list) - **see page 5-16**.

■ **Caution note**

Actually operate the servos and carefully confirm the settings before flying.



## THRO TRIM



This screen is for Airplane type.

### Function explanation

Throttle cut allows a single switch to cut the motor regardless of throttle stick position. If you choose not to use the throttle cut function, you can instead use the throttle trim offset memory function. When the trim is lowered in a single action, the trim position immediately prior to the movement will be memorized, and when the trim is raised again, the trim will automatically return to the memorized position with just a brief single push up. The throttle cut and throttle trim offset memory functions are only available in 'normal' flight modes, as defined in flight mode setup, [page 5-3](#). An idle adjust function is available in airplane mode. This function allows the motor idle speed to be adjusted either up or down using a switch, and also the option of fine tuning using a trim input device. Two different idle adjustments are available.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select throttle trim.
- ③ Use the right and left navigation arrows to change between the various function pages.
- ④ After setting the function, return to the home screen by pressing the

back button.

### Throttle cut

- ① The throttle cut can be used by setting it to 'ACT'. Activating this function automatically inhibits the throttle trim offset memory function.
- ② Next touch the switch icon, and here you can select the switch or switches to use for this function. Select a switch or switches in the usual manner ([see page 3-22](#)).
- ③ Next enter the throttle cut position. Negative values reflect a lower than idle throttle setting, and would normally be used here.
- ④ Finally it is possible to enter a time lag. This function is to avoid the sudden stopping of the engine if the throttle cut switch is activated in error. This is especially useful when using a momentary switch, and it is then possible to use this momentary switch as timer switch at the same time as throttle cut. When the time lag function is activated, throttle cut only activates when the switch is held on for a certain duration. The timer can be activated by a momentary action as usual. The time lag duration can be set between 0.1 to 10 seconds.
- ⑤ After setting the function, return to the home screen by pressing the back button.



### Throttle trim offset memory

- ① To use this function, you must first inhibit the throttle cut function.
- ② Use the right arrow to move to the next page.
- ③ Next activate the throttle trim offset memory function by touching the 'ihn' on the screen.
- ④ After setting the function, return to the home screen by pressing the back button.

### Idle adjust (airplane mode only)

The idle speed when the throttle stick is at the low position can be adjusted using a switch, and fine-tuned using an optional trim input function. This allows the motor idle speed to be decreased using a switch for landing.

- ① When you enter the throttle trim menu, use the right arrow to move to the page showing the idle adjust function.
- ② Two different idle adjusts may be programmed, but only one with a delay function.
- ③ First touch the switch icon, and select a switch to use for this function. Often this may be the same switch which is used to lower the flaps for landing, so that when configured for landing the idle speed is decreased. [see page 3-22](#) for information on switch selection.

- ④ Next enter a value to (typically) decrease idle speed for landing. This would be entered as a negative value.
- ⑤ You may also set up a trim input to fine tune the final idle speed. Please first define a trim input device (**see page 5-8**) and then select the device under trim input.
- ⑥ Finally a delay is available for one of the idle adjust functions. The delay smooth's the change between two idle adjust positions.
- ⑦ After setting the function, return to the home screen by pressing the back button.



### Tips

- Please carefully confirm the linkage does not jam when the carburetor is closed.

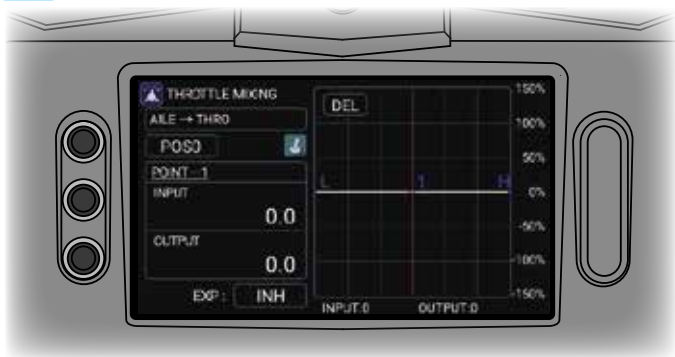
### ■ Caution note

Be very careful when programming this function when using an electric motor. Program the transmitter with the motor disconnected, and then confirm the function behaves as described on the monitor screen before plugging the motor back in.

In helicopter mode, throttle cut will only work when the flight mode is set to 'normal'.



## THROTTLE MIX



Submenu key



### Function explanation

When operating the cyclic or yaw controls on a helicopter, the rotor speed may be reduced due to loading. This mixing function is intended to correct for this effect when you are not using a governor. Each mix (from aileron, elevator, and rudder) can be programmed independently. Note this mix function is designed not to drive the throttle beyond the high travel adjust setting – thus avoiding jammed linkages, etc.

### Setting method

- 1 From the home screen, press the menu button on the touch screen.
- 2 From the function list, select throttle mixing.
- 3 First select the mix you wish to adjust. Do this by touching the current

mix function. You will be able to select from aileron, elevator or rudder to throttle mixes.



- 4 Next touch the switch icon, and here you can select the switch or switches to use for selecting each throttle mix option. Select a switch or switches in the usual manner (see page 3-22). Press the back button to return to the previous screen.
- 5 There are two mix curves available – POS0 and POS1. Typically POS0 would be left as default, as a 'mix off' position.
- 6 To select POS1 to program the mix curve, either change the selected switch to select POS1, or simply touch the POSx icon, and select POS1.
- 7 Now program the mix curve in the usual manner. Move the current control function (aileron, elevator or rudder) and add points to the mix curve as required.
- 8 Then alter the 'output' at those points to set additional throttle as required. Confirm the throttle moves as expected on the monitor screen.
- 9 EXP may be activated to smooth the lines on the mix curve.
- 10 Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- 11 After setting the function, return to the home screen by pressing the back button.

Each mix from aileron, elevator, or rudder can be switched on and off using an independent switch. After setting the switches, please confirm the monitor display for correct operation.

### Submenu functions

- Delay  
To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds).
- Trim input  
This option allows a trim input device (see page 5-8) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. The point(s) on the mixing curve the trim input device fine tunes can be selected.

### Tips

- As a rough guide to values, it is recommended that the aileron and elevator should be set to 10%-30%, and the rudder should start from left 10% and right 15%.
- Confirm the mix direction increases the throttle setting.

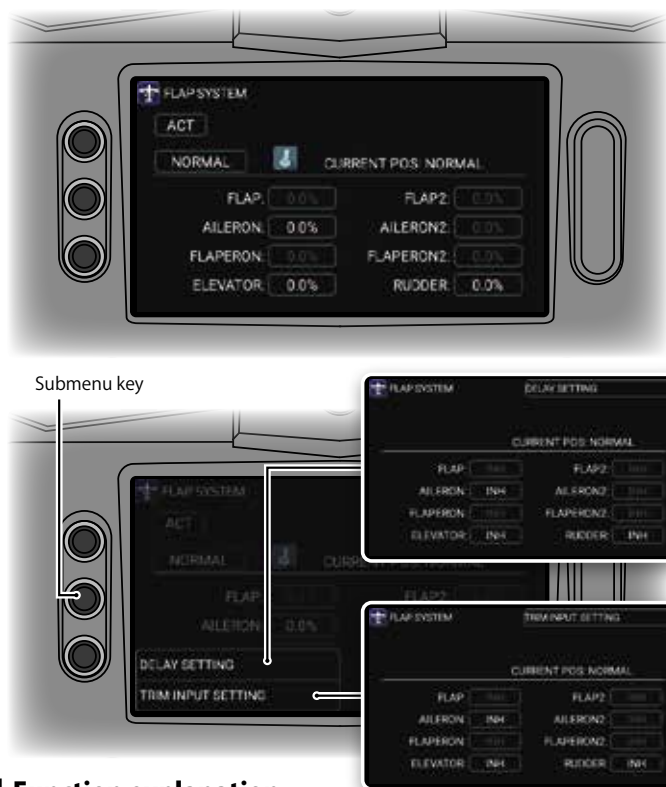
### Caution note

When using a governor, this function is not required, and the numerical values should all be set to zero.

Actually operate the servos and carefully confirm the settings before flying.



## FLAP SYSTEM



### Function explanation

The flaps can be controlled in three stages using a switch. As well as setting the position for the flap servo(s), the aileron servo(s) (and flaperon servos if being used) can be freely adjusted as required. Further, the elevator and rudder can be adjusted so the model remains perfectly in trim as the flaps are deployed. The submenu contains a flap delay function to slow the transition of all control surfaces associated with this function. Additionally, trim input switches can be used to fine tune each of the flap system settings in flight.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select flap system.

③ First activate the function.

④ Next touch the switch icon, and here you can select the switch or switches to use for selecting each flap system option. Select a switch or switches in the usual manner (see page 3-22). Note that if an analogue position switch is used (page 5-7), it is possible to activate the flap system using the throttle stick. Press the back button to return to the previous screen.

⑤ The display to the left of the switch icon indicates the current flap position. To set this function, either move the switch to select and then program each flap position in turn, or alternatively select the position to program by touching the current flap position indication and changing from here.

⑥ Now set values for your desired flap position, aileron, elevator and rudder positions as required. In order to off-set the pitching action upon activating the flaps, it is possible to set an independent elevator trim position with each flap position. It is also possible to set a correction to roll and yaw in the same way.

⑦ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.

⑧ After setting the function, return to the home screen by pressing the back button.

### Submenu functions

#### • Delay

To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction as the flaps are lowered.

#### • Trim input

This option allows a trim input device (see page 5-8) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected flap system control surface deflection using a trim lever. Therefore, it is possible to easily adjust the flap system setup during flight.

### Tips

- This function is very handy for fine tuning model behavior when the flaps are deployed. The elevator can be trimmed to eliminate any pitch up or down tendency, as well as any roll or yaw induced with flap deployment.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## SNAP ROLL



### Function explanation

This function is useful for executing snap rolls. There are four presets, and normally activation is carried out using a momentary switch. However, stick switches are also incorporated that automatically enter a snap roll when the stick is operated by a fixed amount. Further, it is also possible to select which flight modes the snap switches are active in.

### Setting method

- From the home screen, press the menu button on the touch screen.
- From the function list, select snap roll.
- There are four snap roll presets available, and they are initially set to 'INH'. First select the snap roll preset you wish to program by touching the snap roll preset selection area. You can now select snap roll preset 1-4.

#### PRESET

|         |            | AILE  | ELEV  | RUDD  |
|---------|------------|-------|-------|-------|
| S.Roll1 | Left UP    | L100% | U100% | L100% |
| S.Roll2 | Left DOWN  | L100% | D100% | R100% |
| S.Roll3 | Right UP   | R100% | U100% | R100% |
| S.Roll4 | Right DOWN | R100% | D100% | L100% |

- Next activate the chosen preset by touching 'INH' and selecting 'ACT'.



- Next touch the switch icon. On this screen there are several selections to be made.

- First decide if the snap roll preset should be active in all flight modes or just selected flight modes.

This is done by touching the flight mode area and selecting either 'on' (active all the time) or selecting individual flight modes for the preset to be active in.

- Next you must set the switch to activate the snap roll preset. Touch under 'snap device' – and here select a switch to turn on the snap roll preset. Select a switch or switches in the usual manner (see page 3-22).

- It is also possible to activate the snap roll preset using the aileron, rudder, or elevator sticks, or a combination of two or three of these. When using stick activation of a snap roll preset, we would certainly suggest having this function only active in certain flight modes.

- Return to the previous screen by pressing the back button. Here you can set the control surface deflections for the snap roll preset.

- Now set any control surface movement delay as the switch is activated, and when the switch is released.

- After setting the function, return to the home screen by pressing the back button.

### Tips

- This function allows precise adjustment of control throws during snap rolls. Most models snap best with less rudder and elevator travel, and more aileron travel.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## DIFFERENTIAL

### Function explanation

This function can be used when either the aileron, rudder, and flap channels have been set to dual channel (two or more servos are being used for each control function).

Taking ailerons as an example, if the wing is a high-lift style, and the ailerons are moved up and down by the same angle, greater air resistance will be generated on the underside, causing the aircraft to yaw in the opposite direction to the intended turn. Differential acts to correct this effect by moving the down going aileron less than the up going aileron. On a glider there will be situations during, for example, butterfly movements where differential is not necessary.

To prepare for this, the break function can cancel the differential when the spoiler stick is lowered. It is possible to set up to fourteen independent differential settings. The submenu contains a delay function to slow the transition of all control surfaces when different differential settings are selected. Additionally, trim input switches can be used to fine tune each of the differential settings in flight.

### Setting method

Note that you can only adjust differential for functions which you have previously set up to use multiple servos. Please see wing type selection on page 352.

#### Airplane



- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select differential.

- ③ First set the number of different differential settings you wish to use. Touch the POSx area and add presets as required. Use the back button to return to the previous screen.



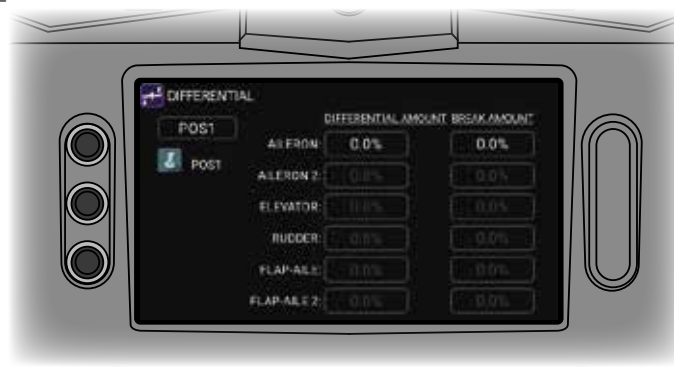
- ④ Next touch the switch icon, and here you can select the switch or switches to use for selecting each differential option. Select a switch or switches in the usual manner (see page 3-22). Press the back button to return to the previous screen.



- ⑤ Now select the differential preset you wish to alter. This can be done by activating the preset switch, or touching POSx and then touching the position you wish to adjust.
- ⑥ Each differential amount can be adjusted positive or negative. If the servos are plugged into the recommended channels, positive differential will decrease the throw of the down going control surface. This would usually be the correct direction for differential adjustment.
- ⑦ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑧ After setting the function, return to the home screen by pressing the back button.

Aileron differential can be used on any wing type which employs two or more aileron servos. Rudder differential can be used with v-tails or dual rudder setups. And flap differential can be used when there are two or more flap servos.

#### Glider

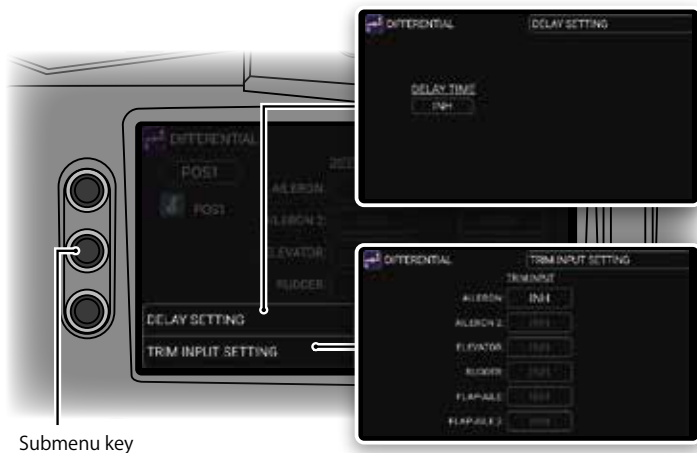


The differential settings are very similar to those described above, except a break function is also available.

## ■ Break differential function

The spoiler stick position can be used to break (remove) any differential settings. The stick can be set to have no effect on differential (0%). You can set any position between 0% and 100% (full spoiler activation) for which the break to be activated, resulting in any differential settings being removed.

## ■ Submenu functions



- Correct differential is important for optimal model performance. First equalize aileron up and down travels using travel adjust, and then fine tune the required differential using this function.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.

### ● Delay

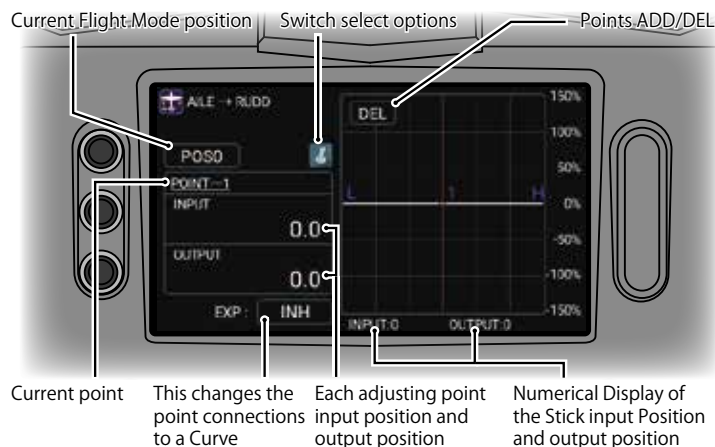
To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction as differential settings are changed.

### ● Trim input

This option allows a trim input device ([see page 5-8](#)) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected differential using a trim lever. Therefore, it is possible to easily adjust differential settings during flight.



## AILERON TO RUDDER MIX



### Function explanation

This function helps achieve smooth coordinated turns for scale model aircraft and gliders. In addition, in glider models, the break function can be used to automatically turn off this mix when rudder or elevator operation is sensed. The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected. Trim input switches can be used to fine tune each of the mix settings in flight.

Additionally, a break/hold setting allows the elevator or rudder stick to turn off the mix



### Setting method

It is possible to use different mixing amounts for left and right aileron. Switches can be freely selected to change between up to fifteen different aileron to rudder mix profiles.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select aileron to rudder mix.
- ③ First define how many possible mix curves you would like to set up. Touch the POSx part of the screen, and then add additional mix profiles as required. Use the back button to return to the previous screen.
- ④ Next touch the switch icon, and here you can select the switch or switches to use for selecting each aileron to rudder mix option. Select a switch or switches in the usual manner (see page 3-22). Use the back button to return to the previous screen.
- ⑤ Select the mix profile you wish to program. Either touch the POSx part of the screen and select the profile to program, or use the switches to select the desired profile.
- ⑥ Now move the aileron stick and add any points to the mix curve. Up to eight points can be added. To add points to the curve, move the aileron stick and press 'add' when the stick is in the desired location to add a point.
- ⑦ After adding any additional mix points, move the aileron stick to the desired position and touch the output area and change the mix value as required.
- ⑧ The EXP function can be used to smooth the curve between points. Simply touch on the 'INH' and select 'ACT'.
- ⑨ Pressing the submenu button allows setting of additional functions including a delay setting, trim input setting, and a break/hold setting.
- ⑩ After setting the function, return to the home screen by pressing the back button.

## ■ Submenu functions

### ● Delay

To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction if rudder mix settings are changed.

### ● Trim input

This option allows a trim input device ([see page 5-8](#)) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected rudder mix using a trim lever. Therefore, it is possible to easily adjust rudder mix settings during flight.

### ● Break

As you move the elevator or rudder stick, the amount of mixing can be decreased.

For example, if you set the elevator break to 30%, the amount of mix will decrease by up to 30% as you feed in more up elevator. And if you set the rudder break to 30%, the amount of mix will decrease by up to 30% as you feed in more rudder.

### ● Hold

If the elevator stick is moved beyond the designated position, the rudder will be fixed in its current position. If you go back to center, the rudder starts working again.

Note, to inhibit these functions, touch the touch the selection area, and then touch and hold the value display till 'inh' is displayed.

## Tips

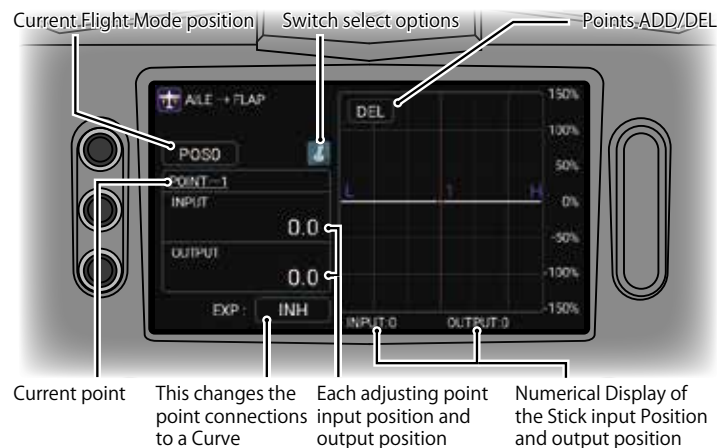
- Aileron to rudder mix is great on scale models and gliders for easing the workload on the pilot when performing coordinated turns. We would not however use this function on an aerobatic aircraft.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## AILERON TO FLAP MIX



## ■ Function explanation

This function mixes aileron operation to flaps. This allows maneuvering using the whole trailing edge of the wing as an aileron - minimizing the generation of air resistance when you wish to speed up the roll rate. The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected. Trim input switches can be used to fine tune each of the mix settings in flight. Additionally, the aileron trim settings can be reflected in the flaps as desired.

## ■ Setting method

For this function to be active, the main wing type selected in the system menu (**page 5-17**) must use at least two flap servos. If this is not the case, the following warning will be displayed:

It is possible to use different mixing amounts for left and right aileron. Switches can be freely selected to change between two different aileron to flap mix profiles.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select aileron to flap mix.
- ③ Next touch the switch icon, and here you can select the switch or switches to use for selecting each aileron to flap mix option. Select a switch or switches in the usual manner (**see page 3-22**). Use the back button to return to the previous screen.
- ④ Select the mix profile you wish to program. Either touch the POSx part of the screen and select the profile to program, or use the switches to select the desired profile.
- ⑤ Now move the aileron stick and add any points to the mix curve. Up to eight points can be added. To add points to the curve, move the aileron stick and press 'add' when the stick is in the desired location to add a point.
- ⑥ After adding any additional mix points, move the aileron stick to the desired position and touch the output area and change the mix value as required.
- ⑦ The EXP function can be used to smooth the curve between points. Simply touch on the 'INH' and select 'ACT'.
- ⑧ Pressing the submenu button allows setting of additional functions including a delay setting, trim input setting, and aileron trim include.
- ⑨ After setting the function, return to the home screen by pressing the back button.

## ■ Submenu functions

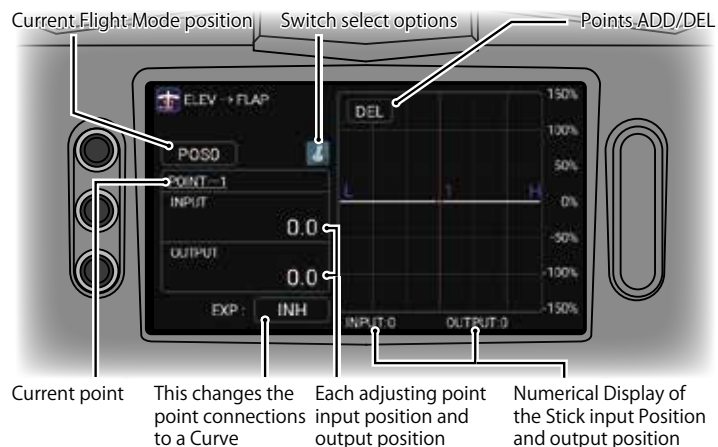
- Delay  
To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction if aileron to flap mix settings are changed. Touch the delay time area on the screen, and input a delay time value. Press the back button to return to the previous screen.
- Trim input  
This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected aileron to flap mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.
- Aileron trim include  
Including the aileron trim allows the flaps to move with the ailerons as the aileron trim is changed. This greatly decreases the drag of the wing if aileron trim changes are required.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## ELEVATOR TO FLAP MIX



### Setting method



For this function to be active, the main wing type selected in the system menu (page 5-17) must include a flap component. It is possible to use different mixing amounts for up and down aileron. Switches can be freely selected to change between two different elevator to flap mix profiles.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select elevator to flap mix.
- ③ Next touch the switch icon, and here you can select the switch or switches to use for selecting each elevator to flap mix option. Select a switch or switches in the usual manner (see page 3-22). Use the back button to return to the previous screen.
- ④ Select the mix profile you wish to program. Either touch the POSx part of the screen and select the profile to program, or use the switches to select the desired profile.
- ⑤ Now move the elevator stick and add any points to the mix curve. Up to eight points can be added. To add points to the curve, move the elevator stick and press 'add' when the stick is in the desired location to add a point.
- ⑥ After adding any additional mix points, move the elevator stick to the desired position and touch the output area and change the mix value as required.
- ⑦ The EXP function can be used to smooth the curve between points. Simply touch on the 'INH' and select 'ACT'.
- ⑧ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑨ After setting the function, return to the home screen by pressing the back button.

### Function explanation

This function mixes elevator operation to flaps, for so-called 'air combat flaps' (snap flaps). The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected. Trim input switches can be used to fine tune each of the mix settings in flight.

## ■ Submenu functions

- Delay

To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction if elevator to flap mix settings are changed.

- Trim input

This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected elevator to flap mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

### Tips

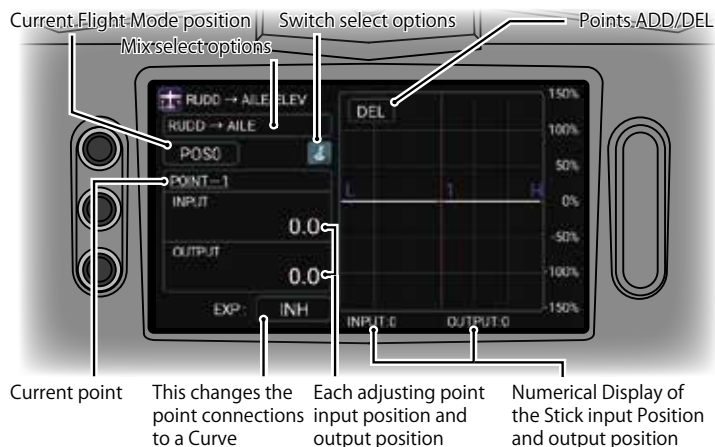
- This function is perfect to increase the maneuverability of a variety of models.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## RUDDER TO AILERON/ELEVATOR MIX



### Setting method

Switches can be freely selected to change between two different mix profiles.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select rudder to elevator/aileron mix.
- ③ Select the mix you wish to adjust – either rudder to aileron, or rudder to elevator. It is easy to switch between these two mixes by simply touching the screen and selecting the desired mix.
- ④ Next touch the switch icon, and here you can select the switch or switches to use for selecting each mix option. Select a switch or switches in the usual manner (see page 3-22). Use the back button to return to the previous screen.
- ⑤ Select the mix profile you wish to program. Either touch the POSx part of the screen and select the profile to program, or use the switches to select the desired profile.
- ⑥ Now move the rudder stick and add any points to the mix curve. Up to eight points can be added. To add points to the curve, move the rudder stick and press 'add' when the stick is in the desired location to add a point.
- ⑦ After adding any additional mix points, move the rudder stick to the desired position and touch the output area and change the mix value as required.
- ⑧ The EXP function can be used to smooth the curve between points. Simply touch on the 'INH' and select 'ACT'.
- ⑨ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑩ After setting the function, return to the home screen by pressing the back button.

### Function explanation

This function mixes rudder operation to the ailerons and elevators. This is convenient for removing biases in knife-edge flight. The mixing amounts from can be set separately for left and right as two independent settings. The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected. Trim input switches can be used to fine tune each of the mix settings in flight.

## ■ Submenu functions

- Delay

To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction if mix settings are changed.

- Trim input

This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

### Tips

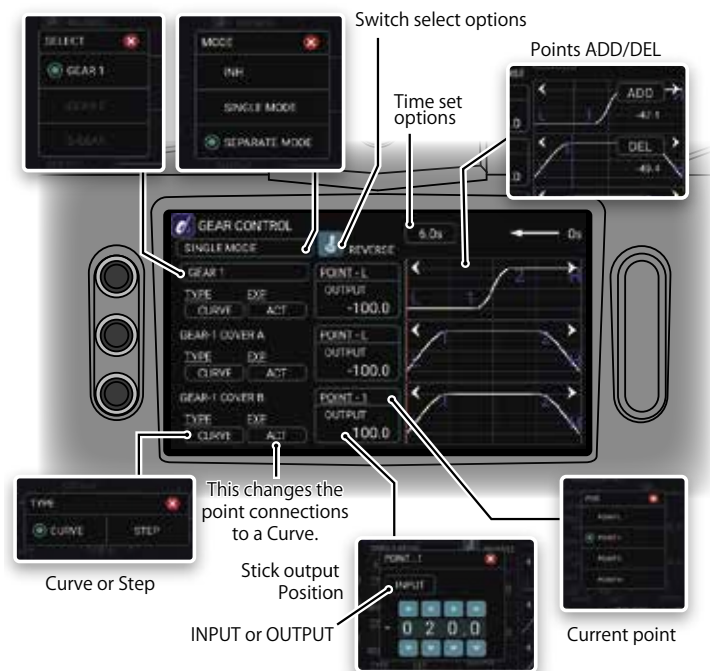
- This function is ideal for making a precision aerobatic model fly in a 'pure' manner with respect to yaw behavior.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## GEAR CONTROL



### Function explanation

This function allows the precise mixing of retractable landing gear and landing gear doors (inner and outer) to be accomplished with ease. We recommend you set this function up with all servo linkages disconnected, so you can be sure of correct operation before connecting everything up.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select gear control.
- ③ If you do not have appropriate servos assigned (see **CHANNEL SETTINGS**, page 5-15), the following warning will be displayed.
- ④ Assign channels for all necessary functions - landing gears or covers (gear doors) using the channel setting menu (page 5-15).
- ⑤ The function is initially inhibited. So first touch 'inh' and then select the

required mode of operation.

- a. Single mode: In this mode up and down gear actuation follows the same sequence
- b. Separate mode: In this mode up and down gear and door action can be different.
- c. Curve movement can be made slowly. Activating exp makes the curve smooth.  
'Step' is for a quick movement. Operation time is the servo speed.
- d. Set the time required from moving from the left to right of the graph.
- e. To add a point, press the triangular arrow on the left and right sides of each graph. That changes the position of the blue line. Move the blue line to the desired point and press the 'add' key..
- f. Switch select - allows the appropriate switch to be defined.



### Point setting

To set the output value at each point, tap the adjusting point display ('POINT-L, etc.) and select the point to be set from the submenu. Then, tap the output position of the adjusting point and set the value.

### Tips

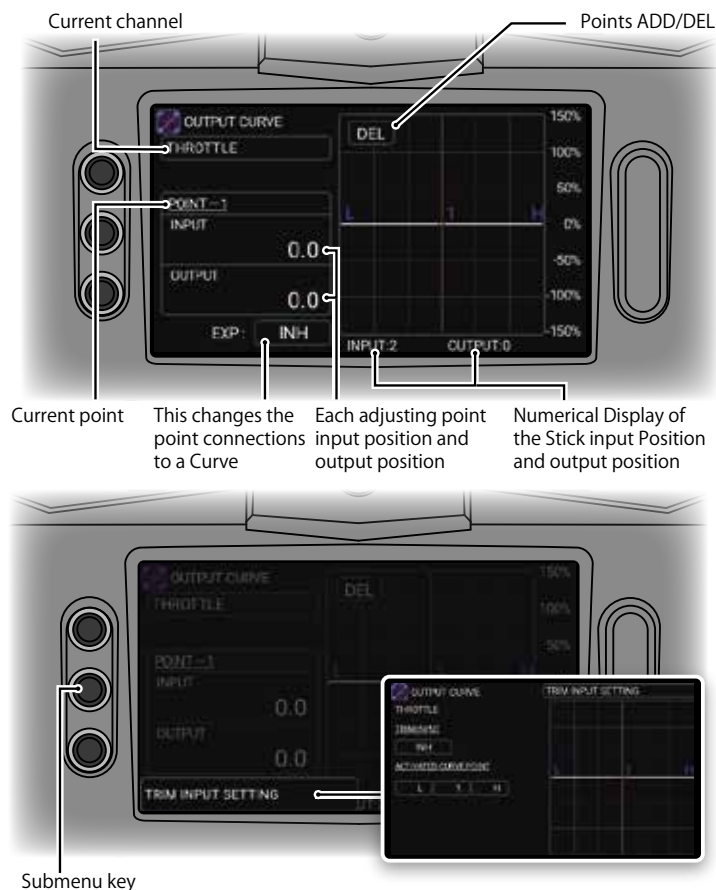
- This function is ideal for correctly sequencing the operation of complex retractable landing gear and gear doors. Take your time to set the function up as accurately as you can.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## OUTPUT CURVE



### Function explanation

This function is used to correct for individual servo characteristic to equalize the travel of each control surface. It is available on all 16 proportional channels, but particularly useful when using multiple aileron, elevator, and flap servos. It is also useful when more than two servos are used on a control surface. The submenu contains trim input setting can be used to fine tune each of the output curves in flight.

### Setting method

#### Airplane

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select output curve.
- ③ Select the servo output curve you wish to modify. It is possible to fine tune the output curve for each of the 16 proportional channels. Touch the channel selection area and select the channel to modify.
- ④ Add points to the output curve. Often you would only need to add points at maximum control deflection for each channel.
- ⑤ Now modify the output curve as required.
- ⑥ You can activate the EXP function to smooth the response curve between points.
- ⑦ Pressing the submenu button allows setting of additional functions including trim input setting.
- ⑧ After setting the function, return to the home screen by pressing the back button.



### Submenu functions

#### Trim input

This option allows a trim input device ([see page 5-8](#)) to be chosen to fine tune any selected output curve. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the output curve using a trim lever. Therefore, it is possible to easily adjust the settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

#### Tips

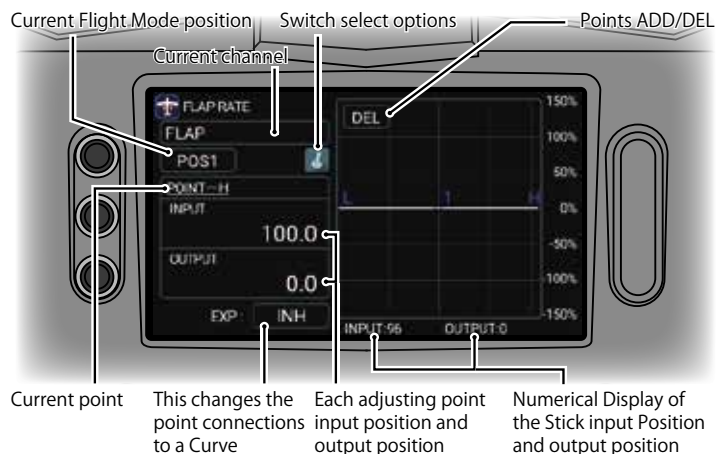
- For each servo, eight points can be adjusted, along with the high and low points. This allows not only exact matching of the servo neutrals, but also matching of additional points including full travel.
- By using the EXP function, it is possible to smooth the transition between points on the curve.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## FLAP RATE



### Function explanation

This function sets the maximum up and down movement of the flap control surface angles independently in each flight mode when using the flap lever. The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected. Trim input switches can be used to fine tune each of the mix settings in flight.

### Setting method



- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select flap rate.
- ③ Flap rates can be set for flap, flap 2, flaperon, flaperon 2 – touch the channel selector, and select the function you wish to adjust.
- ④ Next select how many different profiles you would like for this function. Touch the profile area and add profiles as necessary. Use the back button to return to the previous screen.
- ⑤ Next touch the switch icon, and here you can select the switch or switches to use for selecting each flap rate option. Select a switch or switches in the usual manner ([see page 3-22](#)). Use the back button to return to the previous screen.
- ⑥ Select the mix profile you wish to program. Either touch the POSx part of the screen and select the profile to program, or use the switches to select the desired profile.
- ⑦ Now move the flap lever and add any points to the mix curve as required. Up to eight points can be added. To add points to the curve, move the lever and press 'add' when the cursor is in the desired location to add a point. Often it is fine to just use the default low and high points.
- ⑧ After adding any additional mix points, move the flap lever to the desired position and touch the output area and change the flap rate as required.
- ⑨ The EXP function can be used to smooth the curve between points. Simply touch on the 'INH' and select 'ACT'.
- ⑩ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑪ After setting the function, return to the home screen by pressing the back button.

Initially, the flap rate is set to 0% (default for each flight mode). To change this setting, adjust the numeric values. The default lever for this function is the right side flap lever. This can be changed in the channel setting menu ([page 5-15](#)) – the lever input is that assigned to flap.

## ■ Submenu functions

- Delay

To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooths the model reaction if mix settings are changed.

- Trim input

This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

### Tips

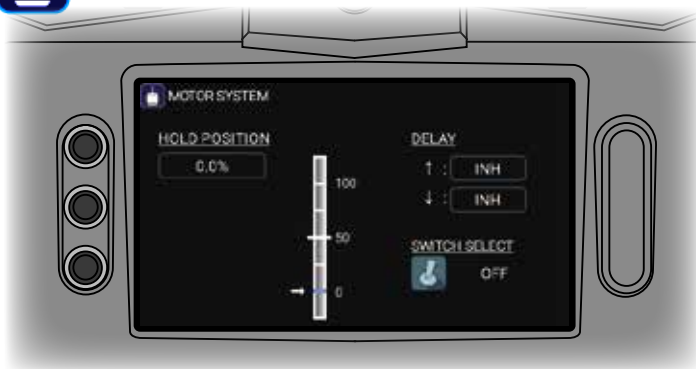
- When operating a competition aircraft where there is concern regarding mistaken operation of the flap switches or levers, set the outputs to zero. Flap operation can still be carried out using other mixing – for example using the camber system.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## MOTOR SYSTEM



Delays from 0-10 seconds are possible.

- ⑥ After setting the function, return to the home screen by pressing the back button.



### ■ Caution note

Be sure to set the 'warning' function in the system list and be aware of the motor starting unexpectedly.

It is very easy to accidentally turn on a switch and the motor start, and not immediately realize why. Always program this function with the motor disconnected. Finally run the motor and carefully confirm the settings before flight.

### ■ Function explanation

This function is used to switch off (hold) the motor channel using a switch. By using the delay function, it is possible to smoothly change motor speed (the speed controller must have a linear transition to correctly use this function).

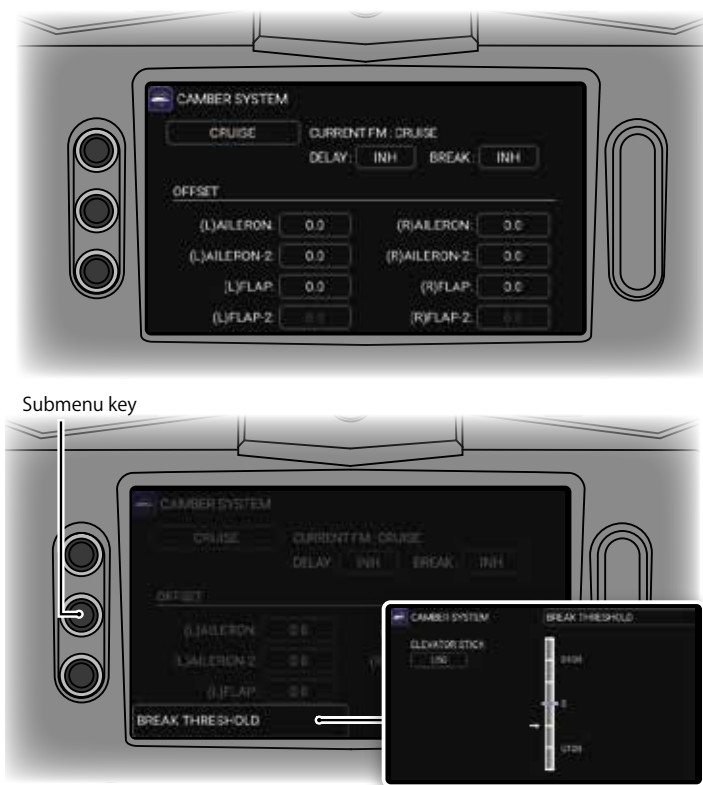
### ■ Setting method

In order to use this function, it is necessary to set a motor channel in the channel setting menu (system menu). Here you can also define the control lever for the motor (see page 5-15). If you have not defined a motor channel, the following warning will be displayed when you enter this function.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select motor system.
- ③ First select a switch to activate the hold function. Touch the switch icon, and here you can select the switch or switches to use for selecting each option. Select a switch or switches in the usual manner (see page 3-22). Use the back button to return to the previous screen.
- ④ Next select the hold position. This would typically be motor off, with a value of 0%. Touch the appropriate area of the screen and set the value here.
- ⑤ Now set the hold delay. This function slows the throttle change rate between high and low settings. The up arrow indicates the speed to increase throttle, and the down arrow the speed to decrease throttle.



## CAMBER SYSTEM



### Function explanation

It is possible to have a glider which uses full span ailerons or flaps + ailerons on the main wing and move these control surfaces up and down simultaneously to change the airfoil section. Because changing the airfoil can vary the rate of descent and drag, it is possible to change the flight endurance and glide ratio.

These settings can be set for each flight mode. In addition, the delay time during transition can be adjusted, so the aircraft does not react wildly. During this delay time, rapid cancellation is possible using the elevator stick (break function). The submenu contains a break threshold function.

### Setting method



There are two ways of setting the amount of camber offset in each flight mode.

One is to set it using this function, and the other method is changing the camber trims in each flight mode.

Using the camber system function, it is possible to set the camber off-set with a desired delay and break function, and also precisely set each control surface.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select camber system.
- ③ Select the desired flight mode to change the camber settings for. This can be done by selecting the flight mode by moving the flight mode switch, or touching the flight mode area on the screen and selecting the flight mode.
- ④ The desired camber offsets can now be input. Touch the control surface to change, and enter the desired offset value. Do this for each control surface across the wing.
- ⑤ A delay can be added (0-10 seconds) to slow the transition between flight modes. The delay is applied when entering the flight mode the delay is set for.
- ⑥ Finally you can choose to activate the camber system break.
- ⑦ Pressing the submenu button allows setting of additional functions including a break threshold setting.
- ⑧ After setting the function, return to the home screen by pressing the back button.

### Break function

With the break function active, movement of the elevator stick will discontinue the delay function immediately.

### Trim levers

It is possible to allocate the flap trim and Flaperon trim to a desired trim lever. The default setting is that the flap trim is allocated to "FLAP TR", and the flaperon trim is allocated to "FPRN". Once the lever is selected, it is possible to fine tune the camber settings. The trim levers can be changed in the trim system menu (page 5-5).

## ■ Submenu functions

### ● Break threshold

The break threshold setting defines the elevator stick position at which the delay function is deactivated.

## Tips

- To prevent unnoticed changes of the camber trim position that has been set in each flight mode, the sensitivity of the camber trim levers can be set to zero.

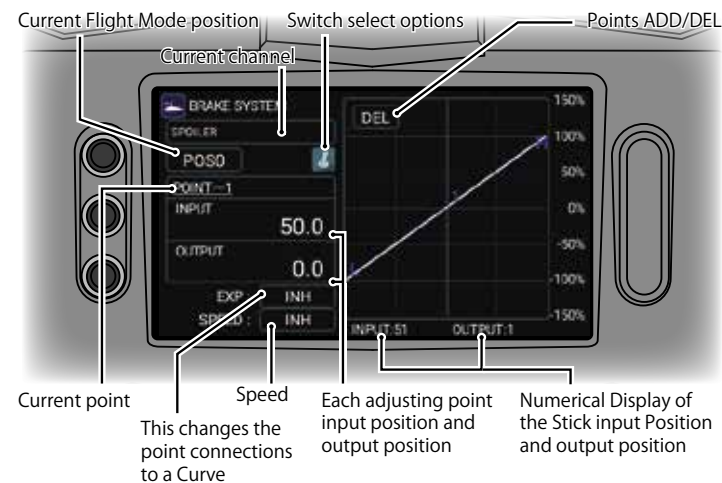
After fine tuning the camber trim settings, the FLAP and FPRM trim steps in the trim system screen (page 5-5) can be set to zero. By doing so, even though the trim lever will not actually operate, the set positions will remain memorized.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## BRAKE SYSTEM



## ■ Function explanation

This function creates air brakes to slow the model using a combination of any of the following controls: spoilers, ailerons, and/or flaps.

The function is also known as butterfly mixing or crow mixing. When the spoiler stick is lowered, the flaps will lower and the ailerons will be lifted, and spoilers deployed if available. Looking from the front of the aircraft you

will see the whole wing will no longer generate lift, and will have a huge amount of drag. A dead band can be set to prevent unintentional operation if the stick is just moved a small amount.

In addition, trim correction provided by the elevator can be finely adjusted to the air brake position using an adjustable mixing curve. The submenu contains a trim input setting can be used to fine tune each of the brake settings in flight.

## ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select brake system.
- ③ First select a switch to change between POS0 and POS1. Touch the switch icon, and here you can select the switch or switches to use for selecting each option. Select a switch or switches in the usual manner (see page 3-22). Use the back button to return to the previous screen.
- ④ Touch on the function select area, and select 'start position'.
- ⑤ Here you can set the start position (or dead band at the start of spoiler stick travel) for brake activation.  
Touch on the position area, and change the start position as desired. We would recommend using a value of 90-95.
- ⑥ Touch on the function select area, and select 'spoiler'.
- ⑦ On this screen you are able to adjust spoiler operation as the spoiler stick is moved. You are able to set two different spoiler profiles.  
First touch the switch icon and select the switches to use to activate the different profiles.  
To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
- ⑧ Up to eight user definable points can be added to the spoiler response curve. Simply move the spoiler stick and touch add.  
You will see you are able to delete points by touching delete.  
The curve output at each point can be adjusted by moving the spoiler stick to the desired point and touching on 'output' and making adjustments as required.
- ⑨ EXP can be activated which will smooth the defined response curve.
- ⑩ The speed of spoiler movement can also be slowed – touch on speed and enter a value between 0-10 seconds.  
This modifies the speed of spoiler response in both directions.
- ⑪ Again touch on the function select area, and select 'spoiler to elevator'.
- ⑫ On this screen you are able to adjust elevator compensation as the spoiler stick is moved.

You are able to set two different elevator compensation profiles.

First touch the switch icon and select the switches to use to activate the different profiles.

To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.

- ⑬ Up to eight user definable points can be added to the elevator compensation response curve. Simply move the spoiler stick and touch add. You will see you are able to delete points by touching delete.  
The curve output at each point can be adjusted by moving the spoiler stick to the desired point and touching on 'output' and making adjustments as required.
- ⑭ EXP can be activated which will smooth the defined response curve.
- ⑮ The speed of elevator movement can also be slowed – touch on speed and enter a value between 0-10 seconds. This modifies the speed of elevator response in both directions.
- ⑯ Again touch on the function select area, and select 'spoiler to flap'.
- ⑰ On this screen you are able to adjust flap operation as the spoiler stick is moved. You are able to set two different flap profiles.  
First touch the switch icon and select the switches to use to activate the different profiles.  
To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
- ⑱ Up to eight user definable points can be added to the flap response curve. Simply move the spoiler stick and touch add. You will see you are able to delete points by touching delete.  
The curve output at each point can be adjusted by moving the spoiler stick to the desired point and touching on 'output' and making adjustments as required.
- ⑲ EXP can be activated which will smooth the defined response curve.
- ⑳ The speed of flap movement can also be slowed – touch on speed and enter a value between 0-10 seconds. This modifies the speed of flap response in both directions.
- ㉑ Touch on the function select area, and select 'spoiler to flaperon'.
- ㉒ On this screen you are able to adjust flaperon operation as the spoiler stick is moved. You are able to set two different spoiler profiles.  
First touch the switch icon and select the switches to use to activate the different profiles.  
To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
- ㉓ Up to eight user definable points can be added to the spoiler response curve. Simply move the spoiler stick and touch add. You will see you are

able to delete points by touching delete. The curve output at each point can be adjusted by moving the spoiler stick to the desired point and touching on 'output' and making adjustments as required.

- ②4 EXP can be activated which will smooth the defined response curve.
- ②5 The speed of flaperon movement can also be slowed – touch on speed and enter a value between 0-10 seconds.  
This modifies the speed of spoiler response in both directions.
- ②6 Spoiler to flap 2 and spoiler to flaperon 2 can be set in the same manner if present.
- ②7 Pressing the submenu button allows setting of additional functions including trim input setting.
- ②8 After setting the function, return to the home screen by pressing the back button.

### ■ Submenu functions

- Trim input

This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated.

By using the trim input, it is possible to change the amount of any selected mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

Trim input settings are available for each of the brake system curves. This is particularly useful for the spoiler to elevator mix, and allows fine turning of this function during flight.

### Tips

- In quick summary: The spoiler stick is used to control the brake function. It can be linked to spoilers, flaps and/or flaperons. As more brake is added, it is possible to precisely adjust the elevator mix so the model does not stall.

### ■ Caution note

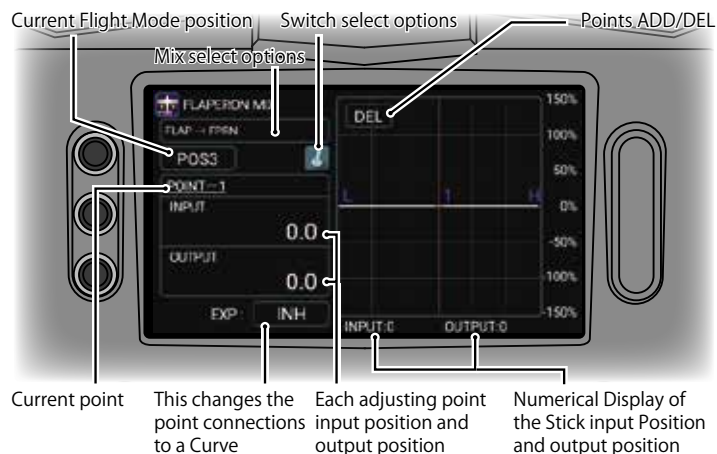
When this function is fully operated, the servos will move a considerable amount. At this time, care is required to avoid jamming any of the control surfaces.

Use the limit adjust function to apply limits to servo movement to avoid damaging the control surfaces or servos.

After programming these settings, operate the servos and carefully confirm each of the flight mode settings before flying.



## FLAPERON MIX



### Function explanation

This function allows flaperon mixing.

- 'Aileron to flap' (and aileron to flap 2):

This mixes from aileron to flap, to use the flaps as ailerons - therefore the roll rate can be increased with less drag.

- 'Flap to flaperon':

This mixes from flap to aileron, to use the ailerons as flaps.

- 'Flap to elevator':

This mixes from flap to elevator, to correct pitch variation caused by flap extension.

The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected.

Trim input switches can be used to fine tune each of the mix settings in flight.

Additionally, the aileron trim settings can be reflected in the flaps where appropriate.



### Setting method

#### Flap to flaperon

- ① From the home screen, press the menu button on the touch screen.
  - ② From the function list, select flaperon mix.
  - ③ Touch on the function select area, and select 'flap to flaperon'.
  - ④ On this screen you are able to adjust how the ailerons respond to flap operation. You are able to set up to 15 different mix profiles. Touch the profile area of the screen and add or remove profiles as necessary.
  - ⑤ Next touch the switch icon and select the switches to use to activate the different profiles. **see page 3-22.**
  - ⑥ To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
  - ⑦ Up to eight user definable points can be added to the flap to flaperon response curve. Simply move the flap lever and touch add. You will see you are able to delete points by touching delete. The curve output at each point can be adjusted by moving the spoiler stick to the desired point and touching on 'output' and making adjustments as required.
  - ⑧ EXP can be activated which will smooth the defined response curve.
  - ⑨ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
  - ⑩ After setting the function, return to the home screen by pressing the back button.
- If you are using 4 ailerons, flap to flaperon 2 mix is also available.

#### Aileron to flap

- ① From the home screen, press the menu button on the touch screen.

- ② From the function list, select flaperon mix.
- ③ Touch on the function select area, and select 'aileron to flap'.
- ④ On this screen you are able to adjust how the flaps respond to aileron operation. You are able to set up to 15 different mix profiles.  
Touch the profile area of the screen and add or remove profiles as necessary.
- ⑤ Next touch the switch icon and select the switches to use to activate the different profiles. To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
- ⑥ Up to eight user definable points can be added to the aileron to flap response curve. Simply move the aileron stick and touch add. You will see you are able to delete points by touching delete.  
The curve output at each point can be adjusted by moving the spoiler stick to the desired point and touching on 'output' and making adjustments as required.
- ⑦ EXP can be activated which will smooth the defined response curve.
- ⑧ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.  
Additionally, it is possible to have the aileron trim move only the ailerons or for the aileron trim to also move the flaps using the aileron trim include function.
- ⑨ After setting the function, return to the home screen by pressing the back button.
- If you are using 4 flaps, aileron to flap 2 mix is also available.

### ■ Flap to elevator

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select flaperon mix.
- ③ Touch on the function select area, and select 'elevator to flap'.
- ④ On this screen you are able to adjust how the elevator respond to flap operation. You are able to set up to 15 different mix profiles.  
Touch the profile area of the screen and add or remove profiles as necessary. Next touch the switch icon and select the switches to use to activate the different profiles.  
To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
- ⑤ Up to eight user definable points can be added to the elevator to flap response curve. Simply move the flap lever and touch add. You will see you are able to delete points by touching delete.

The curve output at each point can be adjusted by moving the flap lever to the desired point and touching on 'output' and making adjustments as required.

- ⑥ EXP can be activated which will smooth the defined response curve.
- ⑦ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑧ After setting the function, return to the home screen by pressing the back button.

### ■ Submenu functions

#### ● Delay

To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooth's the model reaction if flaperon mix settings are changed.

#### ● Trim input

This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected flaperon mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

#### ● Include aileron trim (aileron to flap or aileron to flap2 mix only)

Including the aileron trim allows the flaps to move with the ailerons as the aileron trim is changed. It is possible to have the aileron trim move only the ailerons (inh) or for the aileron trim to also move the flaps (act). This greatly decreases the drag of the wing if aileron trim changes are required.

### Tips

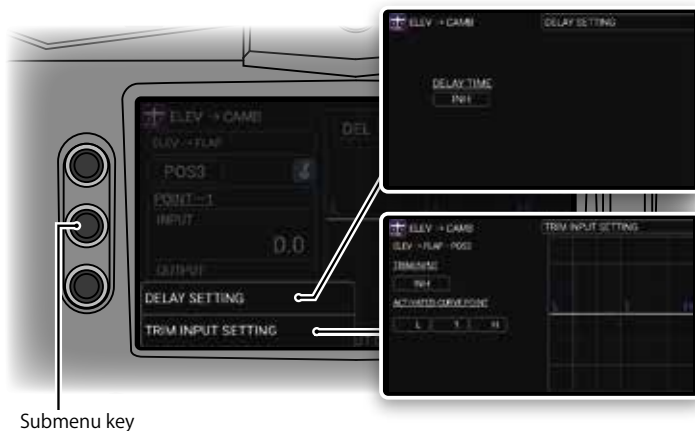
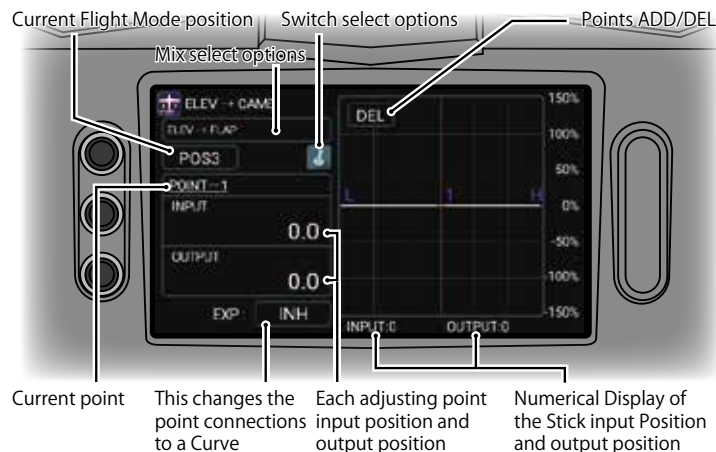
- The initial setting for the flap rate is set to 0%. When mixing from flaps, set the flap travel amount using the flap rate first, before setting this mix.

### ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## ELEVATOR TO CAMBER MIX



### Function explanation

This function changes main wing camber based on elevator operation. Adjustment of the wing root flaps and wing tip flaperons separately in both up and down direction is possible. This function can be modified in up to 15 different flight modes. The submenu contains a delay function to slow the transition of all control

surfaces when different mix settings are selected.

Trim input switches can be used to fine tune each of the mix settings in flight.



### Setting method

The mix amount to the flaps and flaperons can be set on each flight mode, with camber up and down directions set individually.

#### Elevator to flap

- 1 From the home screen, press the menu button on the touch screen.
  - 2 From the function list, select elevator to camber mix.
  - 3 Touch on the function select area, and select 'elevator to flap'.
  - 4 On this screen you are able to adjust how the flaps respond to elevator operation, allowing the elevator to alter the wing camber setting.
  - 5 You are able to set up to 15 different mix profiles. Touch the profile area of the screen and add or remove profiles as necessary.
  - 6 Next touch the switch icon and select the switches to use to activate the different profiles. [see page 3-22](#) for information on switch selection.
  - 7 To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
  - 8 Up to eight user definable points can be added to the elevator to flap response curve. Simply move the elevator stick and touch add. You will see you are able to delete points by touching delete.
  - 9 The curve output at each point can be adjusted by moving the elevator stick to the desired point and touching on 'output' and making adjustments as required.
  - 10 EXP can be activated which will smooth the defined response curve.
  - 11 Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
  - 12 After setting the function, return to the home screen by pressing the back button.
- If you are using 4 flaps, elevator to flap 2 mix is also available.

#### Elevator to flaperon

- 1 From the home screen, press the menu button on the touch screen.
- 2 From the function list, select elevator to camber mix.
- 3 Touch on the function select area, and select 'elevator to flaperon'.
- 4 On this screen you are able to adjust how the flaperons respond to elevator operation, allowing the elevator to alter the wing camber setting. You are able to set up to 15 different mix profiles. Touch the profile area of the screen and add or remove profiles as necessary.

Next touch the switch icon and select the switches to use to activate the different profiles. To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.

- ⑤ Up to eight user definable points can be added to the elevator to flaperon response curve. Simply move the elevator stick and touch add. You will see you are able to delete points by touching delete.
- The curve output at each point can be adjusted by moving the elevator stick to the desired point and touching on 'output' and making adjustments as required.
- ⑥ EXP can be activated which will smooth the defined response curve.
- ⑦ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑧ After setting the function, return to the home screen by pressing the back button.
- If you are using 4 ailerons, elevator to aileron 2 mix is also available.

### ■ Submenu functions

- Delay  
To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooth's the model reaction if mix settings are changed.
- Trim input  
This option allows a trim input device ([see page 5-8](#)) to be chosen to fine tune any selected mix. The trim input device must first be defined before it can be activated.  
By using the trim input, it is possible to change the amount of any selected elevator to camber mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight. It is possible to select which point or points on the curve you would like the trim input to adjust.

### Tips

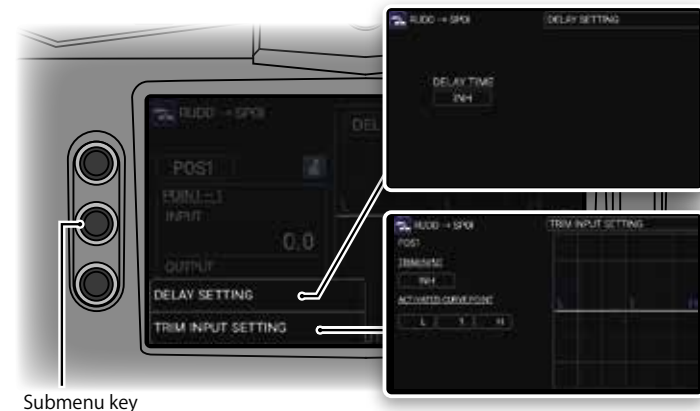
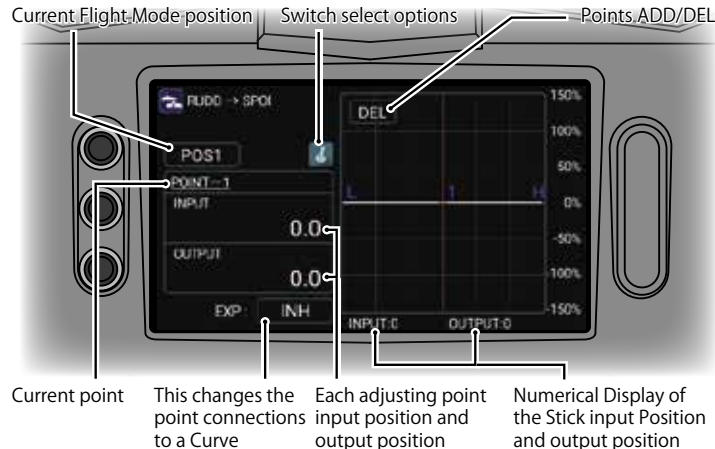
- Elevator to camber mix creates so called snap flaps and can be used on aircraft with main wings that have at least 2 aileron servos.
- To maximize stability, have less mix to the wing tip ailerons, and more mix at the wing root flaps.

### ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## RUDDER TO SPOILER MIX



### ■ Function explanation

This function emulates (or augments) rudder operation using spoilers on aircraft equipped with dual spoilers. This yaw method is also known as drag rudder.

According to the rudder stick operation, the left and right spoilers extend and retract. It is possible to program up to 14 different mix profiles.

The submenu contains a delay function to slow the transition of all control

surfaces when different mix settings are selected. Trim input switches can be used to fine tune each of the mix settings in flight.

## ■ Setting method

It is essential to set up dual spoilers in the wing type settings (page 5-17) for this function to be active. If you have not activated dual spoilers, the following warning will be displayed.

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select rudder to spoiler mix.
- ③ On this screen you are able to adjust how the spoilers respond to rudder operation, allowing the rudder to alter the spoiler positions. You are able to set up to 14 different mix profiles. Touch the profile area of the screen and add or remove profiles as necessary.
- ④ Next touch the switch icon and select the switches to use to activate the different profiles. **see page 3-22** for information on switch selection.
- ⑤ To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
- ⑥ Up to eight user definable points can be added to the rudder to spoiler response curve. Simply move the rudder stick and touch add. You will see you are able to delete points by touching delete.
- ⑦ The curve output at each point can be adjusted by moving the elevator stick to the desired point and touching on 'output' and making adjustments as required.
- ⑧ EXP can be activated which will smooth the defined response curve.
- ⑨ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
- ⑩ After setting the function, return to the home screen by pressing the back button.

## ■ Submenu functions

- Delay  
To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooth's the model reaction if mix settings are changed.
- Trim input  
This option allows a trim input device (**see page 5-8**) to be chosen to fine tune any selected mix.  
The trim input device must first be defined before it can be activated.  
By using the trim input, it is possible to change the amount of any selected rudder to spoiler mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight.

It is possible to select which point or points on the curve you would like the trim input to adjust.

## Tips

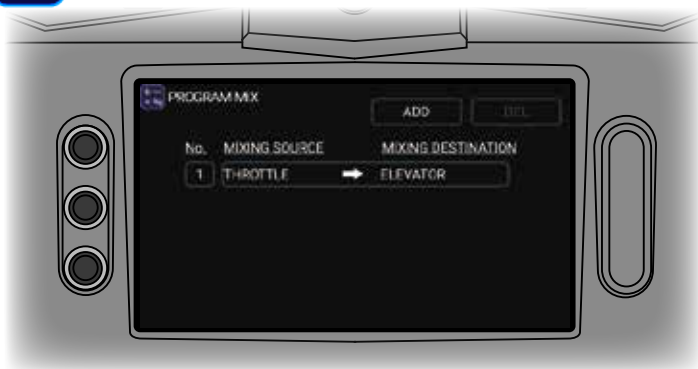
- On a large large-sized aircraft equipped with spoilers on its main wing, this form of augmented yaw control using spoilers is very effective.

## ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.



## PROGRAM MIXING [PROG.MIX1-10]



### Function explanation

If a mixing function is required that is not already incorporated in the transmitter, up to ten program mixing systems are available.

These can be used to freely structure your own mixes.

For this mixing, either simple normal mixing or curve mixing that allows setting of a curve using multiple points can be selected.

The submenu contains a delay function to slow the transition of all control surfaces when different mix settings are selected.

Trim input switches can be used to fine tune each of the mix settings in flight.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select program mix. If no program mix is yet defined, the following will be displayed.
- ③ To add a new program mix, touch on the 'add' area of the screen, and touch 'yes' to confirm you wish to add a mix.
- ④ To delete an existing program mix, touch on the mix number, then the delete area.  
Touch on 'yes' to confirm you wish to delete the mix. Having added a mix, click on the mix description to program the mix.
- ⑤ First select the master channel configuration. Touch the master channel area of the screen.
- ⑥ There are three ways to select the master channel.
  - a. Function Use:  
This allows the master channel to be selected based on channels

specifically set in the channel setting (see page 5-15).

b. Channel number:

This allows you to select any one of the 28 channels to use as the master for the mix.

For example, with a two aileron servo wing, you may decide to use only the output of the left aileron servo to drive the mix.

c. Device:

This lets you use a transmitter control directly as the master for a mix.



- ⑦ Having selected a master channel, next select options from the 'include' dialogue.

Items which can be included vary depending on the master channel selection, and model type. Touch 'include' and select from the list.

If you 'include' a function in the mix, it means its output will be used as part of the input to drive the mix. The items able to be included depend on model type. Please see the full list on page 4-51.

Examples are:

a. Input

b. D/R Exp

any dual rate and expo settings will affect the function of the mix.

c. Trim:

With trim selected, any trim applied to the master channel will be included in the mix.

- ⑧ Press the back button to return to the previous screen.

- ⑨ Now select the slave channel. Touch the slave channel area of the screen.

- ⑩ There are two ways to select the slave channel.

a. Function Use:

This allows the slave channel to be selected based on channels specifically set in the channel setting (see page 5-15).

For example, if you are using a two aileron servo wing, selecting aileron from the function mix will mean the mix moves both aileron servos.

b. Channel number:

This allows you to select any one of the 28 channels to use as the slave for the mix.

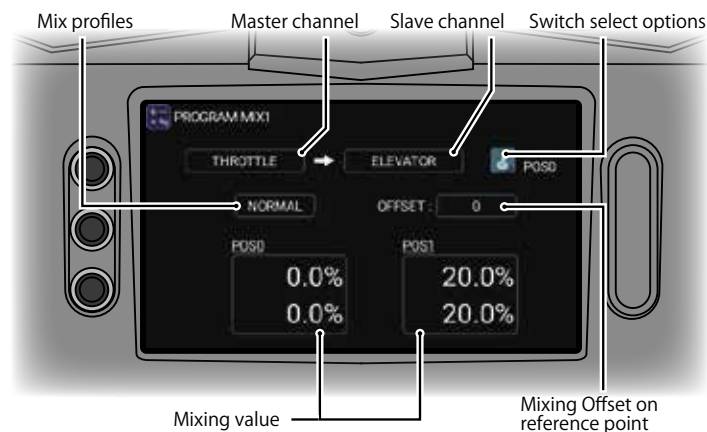
For example, if you are using a two aileron servo wing, you may choose that the mix only move one of the aileron servos.

- ⑪ Having selected a slave channel, next select options from the 'include' dialogue. Items which can be included vary depending on the slave channel selection. Touch 'include' and select from the list.

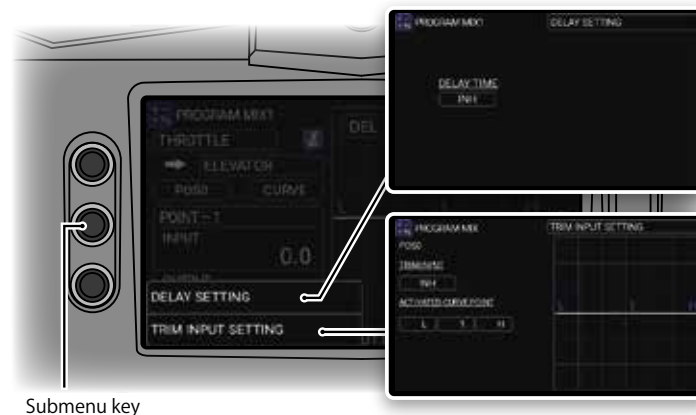
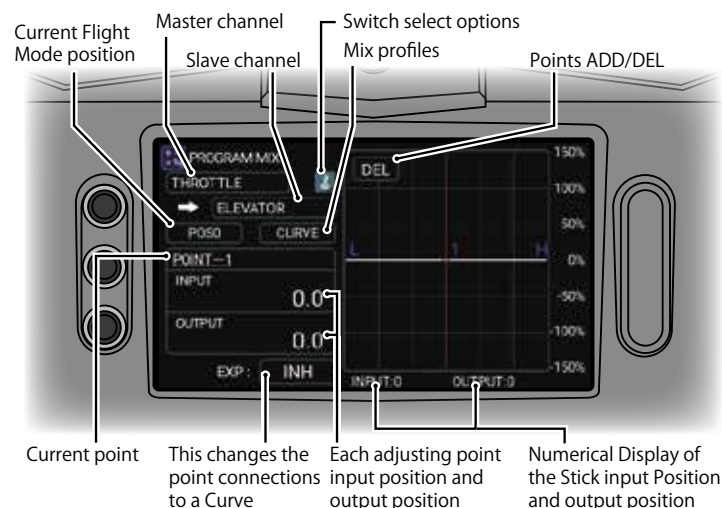
a. Differential:

For example, as a mix drives the ailerons, and differential settings will be respected by the mix function.

- ⑫ Press the back button to return to the previous screen.
- ⑬ Next select if you wish to use a normal mix or the curve mix function.  
The normal mix only allows adjustment of the endpoints of the mixing function. A curve mix allows the degree of mix to be changed based on the position of the master channel.  
Touch on the mix type (normal or curve) to select the type of mix you wish to use.
- ⑭ Next touch on the switch icon to select a switch to use for activating the mix. **see page 3-22** for information on switch selection.
- ⑮ Each mix allows two different mix profiles.
- ⑯ Normal mix:



- a. The total mix in each profile is set by touching the required profile (POS 0 or 1).
  - b. Move the master channel to each extreme of travel, and set the total mix required. If the master channel is in the center of travel, the mix in both directions can be adjusted simultaneously.
  - c. Often POS 0 would be set to 0% mix values (mix off), and POS 1 would have mix values entered (mix active).
- ⑰ Curve mix:



- a. On this screen you are able to adjust how the mix responds in a very exact manner. You are able to set two different mix profiles.
  - b. Touch the switch icon and select the switches to use to activate the different profiles.
  - c. To adjust each profile, either select the desired profile using the assigned switch, or touch the profile area on the screen and select from here.
  - d. Up to eight user definable points can be added to the mix curve. Simply move the master control, and touch add. You will see you are able to delete points by touching delete.
  - e. The curve output at each point can be adjusted by moving the master control to the desired point and touching on 'output' and making adjustments as required.
  - f. EXP can be activated which will smooth the defined response curve.
- ⑮ Pressing the submenu button allows setting of additional functions including a delay setting and trim input setting.
  - ⑯ After setting the function, return to the home screen by pressing the back button.

## ■ Submenu functions

- Delay  
To avoid sudden changes in the mix, a delay can be utilized (0-10 seconds). This smooth's the model reaction if mix settings are changed.
- Trim input  
This option allows a trim input device (see page 5-8) to be chosen to fine tune any selected mix.  
The trim input device must first be defined before it can be activated. By using the trim input, it is possible to change the amount of any selected mix using a trim lever. Therefore, it is possible to easily adjust mix settings during flight.  
It is possible to select which point or points on the curve you would like the trim input to adjust.

## Tips

- By very careful when programming a mix involving throttle. Always disconnect any electric motors.

## ■ Items which can be "INCLUDED" based on master channel

### ■ Helicopter

- D/R & exponential
- E-ring
- Throttle curve
- Pitch curve
- Throttle mix
- Swash mix
- Trim
- Throttle cut
- Throttle hold

### ■ Airplane

- D/R & exponential
- Throttle curve
- Pitch curve
- Flap system
- Trim
- Throttle cut
- Throttle hold

### ■ Glider

- D/R & exponential
- Motor hold
- Trim
- Camber system
- Brake system
- RUDD->SPOI mix
- ELEV->CAMB mix
- Flap rate
- AILE->RUDD mix
- Flaperon mix

## ■ Names and usage of master channels, and items which can be 'included'

### ■ About 'include'

When setting a master channel, trims and other items related to the selected master channel can be included in the mix.

For example, when ailerons are set to the master channel, D/R&EXP can be included. D/R&EXP settings are now reflected in the mixing. When the check is removed, the aileron stick position itself is purely used as the master for the mix.

In the same way, trim movement can be included in the mix by checking trim.



## ■ Helicopter

| Usage    | Items which can be "INCLUDED"   |
|----------|---|
| Throttle | Throttle trim, Throttle curve, Throttle mixing, Throttle hold, Throttle cut |
| Aileron  | Aileron trim, Dual rate   |
| Elevator | Elevator trim, Dual rate  |
| Rudder   | Rudder trim, Dual rate  |
| Pitch    | Pitch Curve   |

## ■ Airplane

| Usage    | Items which can be "INCLUDED"                              |
|----------|--|
| Throttle | Throttle trim, Throttle curve, Throttle hold, Throttle cut |
| Aileron  | Aileron trim, Dual rate                                    |
| Elevator | Elevator trim, Dual rate                                   |
| Rudder   | Rudder trim, Dual rate                                     |
| Flap     | Flap trim, Flap system                                     |

## ■ Glider

| Usage    | Items which can be "INCLUDED"   |
|----------|---|
| Flaperon | Flaperon mixing, Camber system, Brake system, Elevator to flap mixing |
| Aileron  | Aileron trim, Dual rate, Camber system                                |
| Elevator | Trim, Dual rate, Flaperon mixing, Brake system                        |
| Rudder   | Trim, Dual rate, Aileron to rudder mixing                             |
| Flap     | Trim, Flaperon mixing, Brake system, Elevator to flap mixing          |

## ■ Names and usage of slave channels, and items which can be "INCLUDED"

### ■ Helicopter

| Usage | Items which can be "INCLUDED"   |
|-------|---|
| CH2   | When the swash type is set, the channel 2 is included in the mix.     |
| CH3   | When the swash type is set, the channel 3 is included in the mix.     |
| CH6   | When the swash type is set, the channel 6 is included in the mix.     |
| CH8   | When the swash type is set, the channel 8 is included in the mix.     |
| NEDL  | A channel that is set to a needle channel can be included in the mix. |

### ■ Airplane

| Usage | Items which can be "INCLUDED"  |
|-------|--|
| FPRN  | When the wing type is dual ailerons, four ailerons, or six ailerons, mixing flap operations to the ailerons is possible. |

| Usage | Items which can be "INCLUDED"   |
|-------|---|
| AILV  | When the wing type (tail wing) is dual elevators or four elevators, mixing aileron operations to the elevators is possible. Aileron differential can be "INCLUDED". |
| RDVT  | When the wing type (tail wing) is dual rudders, mixing elevator operations to the rudders is possible.  |
| FLAI  | When the wing type (main wing) is dual flaps, mixing aileron operations to the flaps is possible. Flap differential can be "INCLUDED".                              |

### ■ Glider

| Usage | Items which can be "INCLUDED"   |
|-------|---|
| AILV  | When the wing type (tail wing) is dual elevators, mixing aileron operations to the elevators is possible. Aileron differential can be "INCLUDED". |
| RDVT  | When the wing type (tail wing) is dual rudders, mixing elevator operations to the rudders is possible.  |
| FLAI  | When the wing type (main wing) is dual flaps, mixing aileron operations to the flaps is possible. Flap differential can be "INCLUDED".            |
| SPRD  | When the wing type (main wing) is dual spoilers, mixing rudder operations to the spoilers is possible.  |
| MOTO  | A channel that is set to a motor channel can be included in the mix.  |

## ■ Names of slave channels when used

### ■ Helicopter

| Usage  | Items which can be "INCLUDED"   |
|--------|---|
| Gear   | A channel that is set to a gear 1 channel can be included in the mix. |
| Needle | A channel that is set to a needle channel can be included in the mix. |

### ■ Airplane

| Usage   | Items which can be "INCLUDED"  |
|---------|--|
| Aileron | When the wing type (main wing) is two or four ailerons, or delta, differential can be 'included'.  |
| Rudder  | When the wing type (tail wing) is two rudders, differential can be 'included'.   |
| AILV    | When the wing type (tail wing) is two elevators, mixing aileron operations to the elevator is possible. Further, differential can be 'included'. |
| RDVT    | When the wing type (tail wing) is two rudders, mixing elevator operations to the rudder is possible.   |
| FLAI    | When the wing type (main wing) is two or four flaps, mixing aileron operations to the flap is possible. Further, differential can be 'included'. |

| Usage          | Items which can be "INCLUDED"  |
|----------------|--|
| Gear           | Channels that are set to gear 1 and gear 2 can be included in the mix.   |
| S-gear         | A channel that is set to a S-gear channel can be included in the mix.  |
| Gear cover     | A channel that is set to a gear cover channel, such as the gear 1 cover, can be included in the mix.   |
| Right throttle | When the wing type (throttle) is two, three, or four throttles, a channel that is set to the right throttle 1 or 2 can be included in the mix. |
| Left throttle  | When the wing type (throttle) is two, three, or four throttles, a channel that is set to the left throttle 1 or 2 can be included in the mix.  |

## Glider

| Usage          | Items which can be "INCLUDED"  |
|----------------|--|
| Aileron        | Differential can be 'included'.  |
| Rudder         | When the wing type (tail wing) is two rudders, differential can be 'included'.   |
| AILV           | When the wing type (tail wing) is two elevators, mixing aileron operations to the elevator is possible. Further, differential can be 'included'. |
| RDVT           | When the wing type (tail wing) is two rudders, mixing elevator operations to the rudder is possible.   |
| FLAI           | When the wing type (main wing) is two or four flaps, mixing aileron operations to the flap is possible. Further, differential can be 'included'. |
| Spoiler Rudder | When the wing type (spoiler) is two spoilers, mixing rudder operations to the spoiler is possible.   |
| Motor          | A channel that is set to a motor channel can be included in the mix.   |

### ※ Note:

- ▶ **AILV:** Ailevator, the elevator halves can act as ailerons
- ▶ **RDVT:** Ruddervator, angled dual rudders can be mixed to help provide elevator control
- ▶ **FLAI:** Flapperon, the flaps can help provide aileron control

## Caution note

- Actually operate the servos and carefully confirm the settings before flying.



## TIMER



Submenu key

## Function explanation

This transmitter incorporates three Independent timer systems.

Each system has two types of timer – a countdown timer and a stop watch timer. The timers can be started and stopped using a variety of switches and functions.

The submenu contains an interval setting function, a function to record the accumulated time on a particular model memory, and a record of the last 20 times on each of the three timers.

## ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select timer.
- ③ Touch the timer you wish to program, and then select from count down timer or stopwatch. If using a countdown timer, it is necessary to set the required count down time.
- ④ Next touch the switch icon to select the switch to use to activate and stop the timer. **see page 3-22** for more information on switch selection.
- ⑤ Pressing the submenu button on any screen allows setting of additional functions including an interval setting function, a function to record the accumulated time on a particular model memory, and a record of the last 20 times on each of the three timers.
- ⑥ After setting the function, return to the home screen by pressing the back button.
- ⑦ Next you should place a timer widget on the home screens – one widget for each timer you wish to use. **see page 8-1** for information on the timer widget, and setting up the timer widget.

### ■ Countdown timer

The default value for the countdown timer is 10:00 – 10 minutes and 00 seconds.

The countdown timer can be set to a maximum of 59 minutes 59 seconds. As the timer counts down, an alert signal will sound every 10 seconds once the time is under 1 minute, and then every second once 10 seconds remaining is reached. From zero, the timer will start counting up and "+" will be displayed.

### ■ Stop watch timer

The start setting for the stop watch timer is 00:00 – 0 minutes and 0 seconds. The stop watch timer can run to a maximum of 59 minutes 59 seconds and then returns to 0 minutes, 0 seconds. While the timer is running, a signal will sound every minute.

## ■ Submenu functions

### ● Interval setting

The interval timer settings allows selection of a regular 'beep' based on switch selection. Touch the interval time area and select the frequency of beeps, and then touch the switch selection icon to select a switch to turn the interval timer on and off – **see page 3-22** for information on switch selection.

Additionally, the interval time is adjustable during flight. You can select a 'setting time' which defines the range (interval time minus this number to interval time plus this number) over which a trim device can adjust the interval time.

Next select the required trim device by touching the trim device area, and making the required selection. Use the back button to return to this screen.

Finally, a count reset switch can be defined. This switch resets (or synchronizes) the interval time.

### ● Initializing the accumulated timer

This function records the total time the current model has been in use. The accumulated timer can be reset by touching the timer on the screen and selecting 'yes'.

### ● Time reset

This function allows resetting of the accumulated time on the particular model memory. Touch the time area to reset.

### ● Timer record

The timer record lists the last 20 times recorded from each of the three timers.

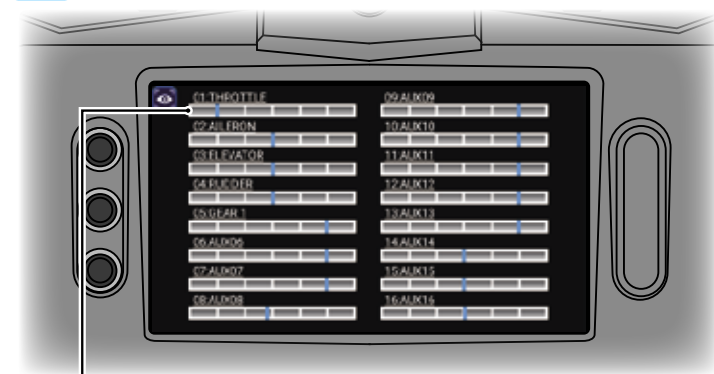
The records for each timer can be reset by touching the corresponding 'reset' areas on the screen.

## Tips

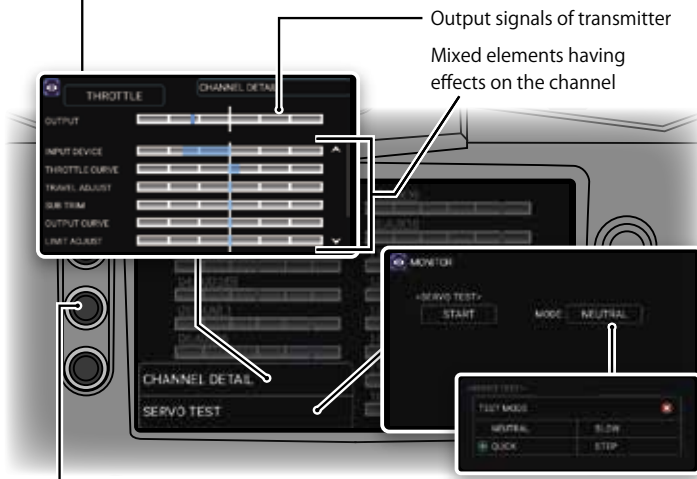
- Place a timer widget on the home screen. Touching this will allow full control of the timer. **see page 8-1**.



## MONITOR



When you touch any channel in the list, the screen will change to individual channel display. Return to the list by pressing the back button.



### Function explanation

This function gives a graphical representation of all functions as they will work on the model. Because this shows the 'final output' of all servo signals, provisional confirmation of correct programming can be carried out before actually connecting the servos. This is useful for discovering unintentional mixing and switch setting mistakes. The submenu contains information on each individual channel (channel detail) and a servo test function.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the function list, select monitor.
- ③ Here you can see final servo outputs as they will be sent to the model.
- ④ Touching an individual servo display will bring up a list of all inputs driving that servo (channel detail). This is very handy for determining where inputs to a particular servo are being derived from. This function is also accessible from the sub menu – please see the description below.
- ⑤ After viewing this function, return to the previous screen by pressing the back button.
- ⑥ Pressing the submenu button allows setting of additional functions including an individual servo monitor and servo check function.
- ⑦ Return to the home screen by pressing the home button.



### Submenu functions

#### ● Channel detail

This brings up the same screen as is obtained by touching an individual servo channel. This lists all inputs driving each servo.

This is very handy for determining where inputs to a particular servo are being derived from.

Change servos by touching the servo name and selecting from the list.

#### ● Servo test

A Servo Test can be carried out within this function. Select the required servo test mode from the four options. Note that if a limit adjust has been set (see page 4-5), servos will not move further than is allowed by the limit setting. In this way you can avoid damaging servos or linkages on the aircraft if servo travel is set below 100%.

#### The four test modes are

##### ► Neutral:

All the servos move to their neutral positions.

##### ► Slow:

All servos simultaneously move at slow speed linearly using  $\pm 100\%$  travel.

##### ► Quick:

All servos simultaneously move at high speed linearly using  $\pm 100\%$  travel.

##### ► Step:

Each channel's servo sequentially moves in turn using 100% travel.

Simply touch the start button to begin the test, and stop to finish.



## MODEL SELECT



Submenu key

### Function explanation

Here it is possible to start setting up a new model, and switch between existing models. The model select function also lets you name models, add a picture to your model, copy models to and from a SD card or USB stick, and also delete models. Up to 100 unique models can be stored in this transmitter.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, choose model select.

- ③ The transmitter will cease RF transmission while in this menu. This must be confirmed on the following screen by touching on 'yes'. Note that any active model should be first turned off.



### Creating a new model

- ① To create a new model, touch the 'new' area of the screen.
- ② It will be necessary to confirm new model creating by touching 'yes'.
- ③ Next it will be necessary to choose the type of model. This transmitter supports specific functionality for airplanes, helicopters and gliders. The type selection screen is automatically displayed when creating a new model. Simply touch on the model type required.
- ④ After the model is created, you will be returned to the model select screen. Here you will notice that the new model is automatically selected, as indicated by the red square around its model number.  
(picture missing the model name area)
- ⑤ Next we should name this model.

### Naming a new model (or changing the name of an existing model)

- ① The name of a model can only be changed if it is the currently selected model. The currently selected model is identified by the red square around its model number. If the model you wish to name (or change the name of) is not currently selected, first refer to 'model select' below.
- ② Touch on the area of the screen indicated. This is where the model name will appear.  
(picture missing the model name area)
- ③ A touch key board will appear. Enter or edit your desired model name. Remember to keep the name easy to remember which model it is referring to. Touch done when finished.

### Model select

- ① To select an existing model, touch on the model name, and then touch on 'select'.
- ② It will be necessary to confirm the change of model by touching 'yes'.
- ③ After selecting a new model, return to the home screen by pressing the back button.

### Model copy

- ① Touch on the model you wish to copy
- ② Touch on the copy button.

- ③ Next select where you would like to copy the model to. Options will be internal memory, SD card (if mounted) and USB device (if connected).
- ④ If copying to internal memory, the model will be copied to the next free model location. If copying to SD card or USB device, the model will be copied to the JR/MODEL/ folder, and the file name will include the memory location the model is being copied from and the name of the model. The file extension will be .JRM.
- ⑤ If the file name already exists, you will be asked if you would like to change the file name. Touching 'yes' will allow you to do this. Touching 'no' will cancel the copy. You cannot overwrite an existing file name.

### ■ Model load

- ① This function is only available when you first enter the model select menu.
- ② Touch on load, and you will be able to load a model from SD card or USB device if connected. The transmitter will initially look in the /JR/MODEL folder if present, but you can navigate to the folder of your choosing.
- ③ Touch on the model you wish to load, and then touch on done.
- ④ The model will be loaded to the first free memory location on the transmitter.

### ■ Model delete

- ① To delete a model from the transmitter memory, first touch on the model to be deleted on the model list. Note that the currently selected model cannot be deleted.
  - ② You will be asked to confirm you wish to delete the model. Touch yes.
- Once you are finished using this function, return to the home screen by pressing the back button.

### ■ Submenu functions

- Sort  
This function allows the transmitter internal model memories to be sorted by model number, model name, date & time created or date and time updated.  
Simply touch on the option you wish to use, and the model list will be appropriately sorted.
- Display select  
Touching display select toggles between two display options in the model select menu.

### Tips

- Name models in such a way so they are easily recognizable.
- It is possible to add an image of the model to help identify it.

### ■ Adding a model image to the model menu

You will need image files on a SD card in the folder /pictures/. The images should be .jpg's, you will be able to crop them during image selection.

- ① First select the model you wish to change the image for.
- ② Next touch on the image placeholder for the model.
- ③ Confirm you wish to add an image by touching yes.
- ④ Any images in the pictures folder of the SD card will be displayed.
- ⑤ Select an image. Now you will be able to crop the image as required. Select the area of the image to use, then touch 'crop'.
- ⑥ The image will now been shown alongside the model information.

### ■ Caution note

Actually operate the servos and carefully confirm the correct model is selected before flying.

Never remove the SD card without either un-mounting it or turning the transmitter off. Doing this may destroy model data on the card. See **page 2-2** for details.



## TYPE SELECT



### Function explanation

This function allows selection of model type. This transmitter supports specific functionality for airplanes, helicopters and gliders. The type selection screen is automatically displayed when creating a new model.

If the model type is change for an existing model, all model data is reset.

### Setting method

When this function is selected, the model type of the currently selected model can be changed. All model data will be reset when a change of type is made.

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select type select.
- ③ You will be asked to confirm that RF transmission will stop. Touch 'yes'.
- ④ The current model type will be displayed.
- ⑤ Touch on the model type you wish to change to. You will receive a warning that the model data will be reset. Confirm you understand this by touching 'yes'.
- ⑥ The model type has now been changed.
- ⑦ Return to the home screen by pressing the home button.

### Caution note

Because the previous data will be erased when the model type is changed, any important model data should be copied and backed-up beforehand. When the model type is changed, the new model setup wizard will start automatically.



## FLIGHT MODE SETUP



Submenu key

### Function explanation

In this screen, flight modes can be activated, their name changed, switches allocated. Up to fifteen flight modes can be used. The submenu allows flight mode priorities to be set.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select flight mode setup.
- ③ Next add or delete flight modes so the flight mode list contains the

number of flight modes you wish to use. Do this by touching the add or delete areas on the screen.

- ④ For each flight mode, first touch the flight mode name – this will bring up the name change dialogue where you can modify the flight mode name as required. Press the back button to return to the previous screen.
- ⑤ On helicopter models, you can also choose the flight mode type – normal, stunt, or hold. Normally you would set up one flight mode as 'normal', one as 'hold', and one or more flight modes defined as 'stunt'.  
If a flight mode is defined as 'normal', throttle cut and throttle trim offset functions are available.  
If a flight mode is defined as 'hold', activation of this flight mode will activate the throttle hold function (**page 4-13**).
- ⑥ Finally select the switch to activate each flight mode. Switch selection follows the usual procedure as described on **page 3-22**.
- ⑦ Pressing the submenu button allows setting of additional functions including setting flight mode priorities.
- ⑧ After setting the function, return to the home screen by pressing the back button.

## ■ Submenu functions

- Priority settings

In this function, each flight mode can be given a different priority setting. For example, if two flight modes are activated at the same time, it is important the transmitter knows which flight mode should be used. Simply touch each flight mode as required to move it up the priority list, one step at a time.

## Tips

- The flight mode name is displayed on the home screen flight mode widget as well as each function showing flight mode condition.

## ■ Default flight modes are as follows

### ■ Helicopter

- 1) NORMAL . . . . . ☒ SW POS0
- 2) STUNT-1 . . . . . ☒ SW POS1
- 3) STUNT-2 . . . . . ☒ SW POS2

HOLD (throttle hold) is not set. If necessary, set HOLD with a name and switch position.

### ■ Airplane

- 1) FLIGHT MODE 01 . . . ☒ SW POS0
- 2) FLIGHT MODE 02 . . . ☒ SW POS1

- 3) FLIGHT MODE 03 . . . ☒ SW POS2

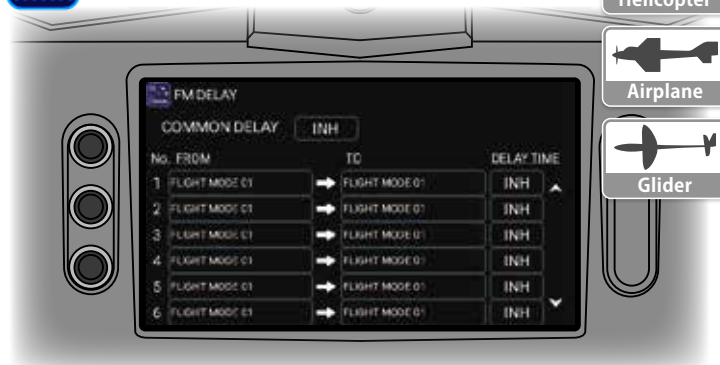
### ■ Glider

- 1) LAUNCH . . . . . ☒ SW POS1
- 2) SPEED . . . . . ☒ SW POS0
- 3) THERMAL . . . . . ☒ SW POS2
- 4) CRUISE . . . . . ☒ SW POS1

If necessary, set LAND, ZOOM, DISTANCE, etc. with names and switch positions.



## FLIGHT MODE DELAY



### Function explanation

When the flight mode is changed, the servos may move suddenly, causing a jerky reaction in flight. To prevent this, it is possible to set a delay during which the servos will move slowly to the new position when switching flight modes. Up to 20 delays can be set. If a particular servo is being moved by a control at the time of flight mode change, the delay is ignored, and the servo immediately moves to the new position.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select flight mode delay.
- ③ Here you can program delays for up to 20 different flight mode transitions. Select the flight mode you are changing from, and the flight mode you are changing to, and then enter a delay value (0-10 seconds). Do this for each flight mode change you would like a delay set for.
- ④ It is also possible to set a common delay, which is applied over all the flight mode changes, regardless of the flight modes being entered on this list. Touch the common delay setting, and enter a delay between 0-10 seconds.
- ⑤ After setting the function, return to the home screen by pressing the back button.

### Sub menu functions

#### Channel settings

By default, flight mode delay acts upon all channels, but you may not need a delay on all channels. Deselect any channels that do not need a delay.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## TRIM SYSTEM



### Function explanation

Various settings relating to the trims can be changed. The resolution of each trim and the trim type can be set for each flight mode. Using this function, you can easily change the trim settings. The submenu allows the trim for each function to be independent on each flight mode, or grouped to two or more flight modes – using the flight mode group settings

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select trim system.
- ③ First touch on the channel select area to select the channel you wish to

change the trim setup for.

- ④ Next choose the trim input device. Touch the trim input device area, and select the trim device from the graphic. Selecting 'INH' inhibits the trim function.
- ⑤ Now set the trim step. This determines how much trim you get with each click of trim. This can be set between 0-200. Not that if you set the step to 0, the trim will be inactive. With the trim set to 200, full trim deflection occurs with one click. Note the trim step does not change the total trim throw – only how many clicks it takes to get to full trim deflection.
- ⑥ The trim can also be reversed. Touch the reverse box, and select on or off.
- ⑦ The trim type can also be selected – either normal or LST.
  - a. Normal trim (norm): Results in the trim lever having an effect over the entire servo operation range.
  - b. Limit stroke trim (LST): The trim has its greatest effect when the control function is at neutral, and the effect of the trim will disappear at the stick end positions. End point travel adjustment is not changed by the trim settings. It is possible to avoid damage to servos, linkages and control surfaces by using LST.
  - c. The throttle function automatically uses a special form of LST. This trim only functions at the low position of the throttle stick, and by half throttle the trim has no effect.
- ⑧ A switch can also be selected to turn the trim on and off. With the trim off, current trim settings are maintained. See **page 3-22** for information about switch selection.
- ⑨ Some functions include a 'use' menu, trim rate, input type and offset.
- ⑩ Pressing the submenu button allows setting of trim flight mode groups.
- ⑪ After setting the function, return to the home screen by pressing the back button.

### ■ Submenu functions

#### ● Flight mode group settings

In this function, the trims associated with each function can be set individually for each flight mode (separate trim), or grouped together and set for two or more flight modes (common trim).

After selecting this function, first select the trim function you wish to program – touch the function area of the screen and select the trim.

Now select the trim group for each flight mode. Up to 15 individual trim groups can be used.

If the trim is set to a different group for each flight mode, the trims are

all set individually in each flight mode. If all flight modes are set to the same group, altering the trim in one flight mode will also change the trim in another. This function is set individually for each trim function.

#### Tips

- By setting the trim step to "0" it is possible to inhibit the operation of a trim lever.



## ANALOGUE POSITION SWITCH



### Function explanation

This function allows switching (on/off) of virtual switches using stick operation. Virtual switches can be programmed to any stick position, and then used to switch various functions on and off.

### Setting method

Ten analogue position switches (APS) are available (APS0-APS9). All the switches are initially inhibited.

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select analogue position switch.
- ③ There are ten definable APS's. Simply touch the arrows to change screens.
- ④ Activate an APS by touching 'INH' and selecting 'ACT'.
- ⑤ Next choose an input device for the switch. Touch the input device box, and select the input as either a device or channel.
  - a. Device: The input is taken from raw values from a control, irrespective of any mixes, etc that may be effecting the function.
  - b. Channel: Selecting a channel means the final channel output is used for the APS. This would include any trim settings, mixes, etc.
- ⑥ Now set the switch logic. The switch can be set with three possible on/off configurations, and four user defined switching zones. There is an on/off indication on the screen which is of great help when programming the APS logic. Start by deciding in which basic areas you wish the APS to be on or off. Three zones can be set as shown below.

After setting these zones, it is now necessary to set the switch logic within each zone. I will use an example of an APS setup as on-off-on.



The first position box sets the point the APS will change from on to off, as the stick is moved from the extreme of travel toward center. This is shown by the grey bar.

Next set the point at which the APS will change from off to on, when the stick is moved from the center position back to the left position on the image. The point of switching is indicated by the blue bar.

The remaining two switch points are set in a similar manner.

※ Note that at least one switch point must be set for the APS to function.

As you experiment with different set points, you will discover how powerful this function is.

- ⑦ After setting the function, return to the home screen by pressing the back button.

### Tips

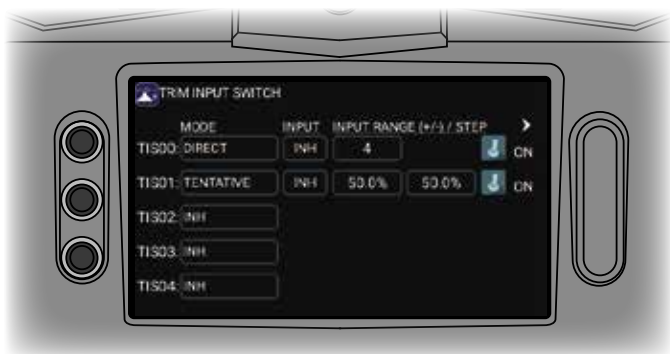
- In various functions, by choosing analogue position switch, it is possible to turn functions on and off using stick control.
- The function display shows the current APS switch position (on/off) - this is very useful when setting up this function.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## TRIM INPUT SWITCH



### Function explanation

This function allows adjustment of mixing values, gyro sensitivity, and other functions, using a chosen trim lever. It is a very useful function to enable fine tuning during flight. It is possible to define up to nine trim input switches.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select trim input switch. There are two pages of trim input switches available. Use the arrows to move between pages.
- ③ To define a trim input switch, first touch the mode area. Here you can select from direct or tentative.
  - a. Direct: Setting a trim input switch as direct means the device will move defined points on a mix curve up and down together.
  - b. Tentative: Setting a trim input switch as tentative will allow the mix curve to rotate about a defined axis.
- ④ Next select the input for the trim input switch. Touch the input box and select an input from the graphic.
- ⑤ Now select the input range – this defines how much effect the trim input switch can have. The range is settable from 0-100 in direct mode, and +/- 200% in tentative mode.
- ⑥ Finally touch the switch icon and select a switch to turn the trim input switch on and off if necessary. See [page 3-22](#) for information on switch selection.

- ⑦ After setting the function, return to the home screen by pressing the back button.

### Tips

Trim input switches have different uses depend on each model type. After the trim input switch is defined in this function, it must be selected as a trim input device in the submenu of the primary function. Some examples are:

#### Helicopter

- Gyro sensitivity
- Governor head speed
- Swash compensation mixing
- Throttle curve points
- Pitch curve points

#### Airplane

- Flap system elevator trim
- Differential
- Gyro sensitivity
- Rudder to aileron or elevator mix amounts

#### Glider

- Brake system at defined points (eg. maximum braking), change the mixing amount.
- Aileron to rudder mix

### Caution note

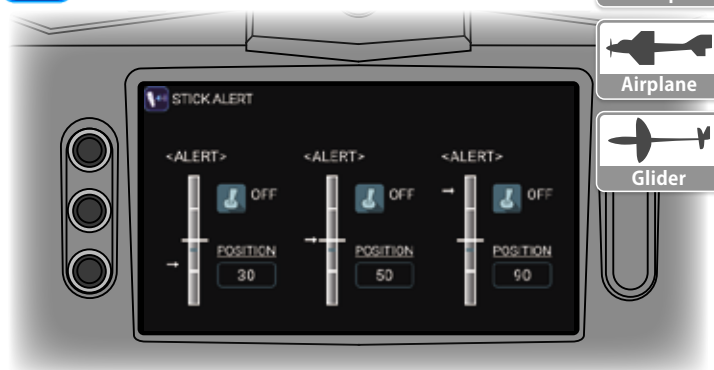
Actually operate the servos and carefully confirm the settings before flying.

When a trim input switch is activated the normal function of the trim is inhibited.





## STICK ALERT



### ■ Function explanation

This function will sound an alert when the throttle stick reaches a certain position. It is convenient to confirm the hover position or zero pitch with an alert. Up to three different alerts can be set.

### ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select stick alert.
- ③ First select a switch to turn the alert on and off as required. See page 47 for information on switch selection.
- ④ Next touch the position area and set the position for the throttle alert to activate. This indicates actual stick position, from 0-100.
- ⑤ After setting the function, return to the home screen by pressing the home button.



## WARNING



### ■ Function explanation

If the throttle stick or switches are set to potentially dangerous positions when the transmitter is switched on, an alert is triggered. A warning will be displayed on the LCD screen, and radio waves will not be emitted until the throttle stick and switches have been returned to safe positions.

### ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select warning.
- ③ The throttle stick warning can be set to active or inhibit. Touch the selection area to change this setting.
- ④ With the throttle stick warning set to active, you can set the position and area for the throttle stick warning to be active. Typically you would want the warning to activate if the throttle stick was at a position above idle when the transmitter was turned on.
- ⑤ It is also possible to set a warning for various switch positions. Touch the switch icon and select switches and positions where the warning will activate. For electric gliders, do not forget to alarm the switch that operates the motor. Page 47 will be helpful in understanding switch positions.
- ⑥ After setting the function, return to the home screen by pressing the back button.

## Warning defaults

- Helicopter  
Initially, the warning alert will not shut off unless the following conditions are met:  
Throttle stick set to the lowest position.  
Flight mode switch set to normal mode.
- Airplane  
Initially, the warning alert will not shut off unless the following conditions are met:  
Throttle stick set to the lowest position.
- Glider  
There is no warning alert default for glider mode. If necessary, set a warning which suits your application. For example, with an electric power glider, you may set a warning to ensure the motor switch is in the off position when the transmitter is turned on.

## Caution note

For safety reasons, be certain to activate this function and check the warning works as expected.



## TRANSMITTER SETTING



Submenu key

## Function explanation

This function allows basic adjustment of transmitter settings such as battery mode, idle alert, alarm volumes, etc. The submenu allows calibration of the transmitter sticks.

## Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select transmitter setting. There are three screens of information accessible using the arrow keys.

- ③ Battery logic:
  - a. It is possible to change how the two transmitter batteries are used. Battery A may be used first, or battery B, or both used simultaneously.
  - b. Touch the battery area, and select from the menu.
  - c. The battery alarm voltages can be set by touching the alarm voltage area and setting a new alarm voltage.
- ④ Idle alert:
  - a. It is possible to change the transmitter idle time (latency) before the idle alert sounds. This can be set between 0 (inhibit) and 254 minutes.
- ⑤ System sounds can be adjusted.
 

The tone and volume can be changed. Simply touch the area to modify.

The last screen in this function shows the current transmitter firmware version.

Pressing the submenu button allows calibration of the transmitter sticks. After setting the function, return to the home screen by pressing the home button.
- ⑥ LED brightness
 

Controls the brightness of the power switch LED. Select from high (default) or low.

## ■ Submenu functions

- Stick calibration
 

This function calibrates the neutral position of the sticks, and stick travel which is especially useful after changing stick modes (mode 1 to mode 2, etc) and after any changes to stick travel.

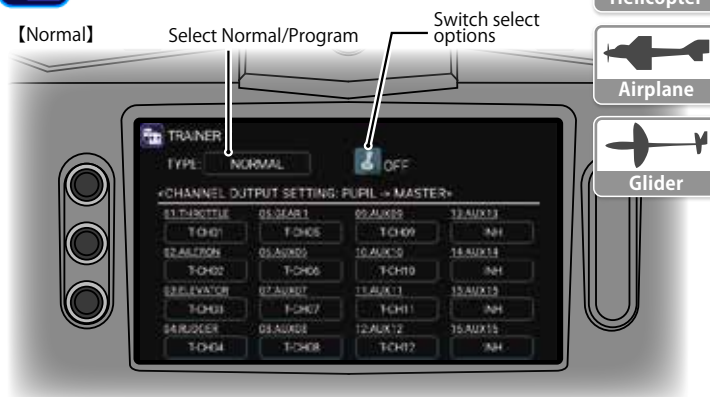
After entering this function, the calibration procedure is as follows.

  - ① Set both right and left sticks to their center positions, and press the set key to calibrate neutral.
  - ② Next move both right and left sticks up and down and right to left and then press the set key to calibrate stick travel.
  - ③ Be sure to check control movement and neutral positions on the servo monitor screen.



## TRAINER SYSTEM

【Normal】



【Program】



## ■ Function explanation

This function allows two transmitters to be connected via a trainer cable (sold separately) to allow dual control flight instruction. A skilled pilot can teach a beginner how to fly an aircraft using this trainer system. The 28X can function as the master (trainer) or pupil (trainee). Control can be changed between master and pupil using the master transmitter's trainer switch (user defined).

## ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select trainer system.
- ③ The trainer type can be set to normal or program – touch the type

selection area and select the desired mode.

- ④ The switch to allow the master transmitter to give control to the pupil transmitter ('trainer switch') can be freely selected. Touch the switch icon, and select a switch. See **page 3-22** for information on switch selection.
- ⑤ After setting the function, return to the home screen by pressing the back button.

### ■ As a master transmitter

When using the 28X as the master:

- ① The main power must be turned on - the transmitter is transmitting radio waves - and is bound to the aircraft.
- ② The trainer cable is plugged in.  
The 'trainer switch' is selected in the master transmitter as above. There are two modes available for the master transmitter.  
In normal mode the pupil transmitter can be another JR 28X, JR XG 6, 8, 11, 14 or JR 11X. Some Spektrum transmitters are also compatible. The pupil transmitter should always have its power switch in the off position. In program mode, the pupil transmitter must be a compatible JR transmitter which includes program mode as a 'slave'. Examples include the JR 28X, JR XG 6, 8, 11, 14 or JR 11X.

### ■ Normal mode

The master transmitter normally controls the model. Control data coming from pupil transmitter is only sent to the aircraft by switching control from master to pupil using the defined trainer switch. Both master and pupil transmitter must have the same program settings, including servo reverse, trim and dual rate settings, etc. Data from the pupil transmitter is sent directly to the model. The pupil transmitter should be in PPM mode (not slave mode).

Always carefully check all control functions of the master and pupil transmitters. If any pupil control inputs are moving the wrong functions, this can be corrected in the below screen. Simply change the channel controlling the particular function.

Additionally, this screen can be used to define pupil transmitter controls to different functions on the aircraft. For example, it is possible to have a master transmitter control the primary functions, and have a pupil transmitter control say a camera gimbal on a multirotor model.

### ■ Program trainer

The master transmitter must be programmed and bound to the model. The pupil transmitter does not need to be programed to match the model. Flight mode, dual rate and trim settings are all controlled by the master transmitter.

Both transmitter must be set to program mode.

If the 28X is the master, simply select from the left hand list which stick inputs from the pupil transmitter should control which functions on the aircraft. Select one or more channels to be controlled by the pupil transmitter. This allows the beginner pilot to learn a single control at a time. This makes it easier to learn, without the worry of controlling all functions at once. The data coming from pupil to master is combined with data from the master transmitter settings (trim, dual rates, mixing, etc...) before being transmitted to the model. Precise adjustments and settings must be done on the master transmitter. The pupil transmitter must be selected as a pupil (slave) in the pupil transmitter programming. This trainer program is available on most recent JR computer transmitters.

### ■ As a pupil transmitter

When using the 28X as a pupil transmitter:

- ① The main power switch must always remain off.
- ② The trainer cable is plugged in.

There are two modes available for the pupil transmitter:

- Normal mode:  
When the master transmitter is set to normal mode, the pupil transmitter should also be set to normal mode. There are no specific setting requirements, however, if the radio has a trainer program, do not set it to pupil.
- Program mode:  
Use this mode when the master transmitter is set to "**program trainer**". When set as a pupil, only the gimbal stick functions pass control outputs to the master transmitter. Therefore, settings such as dual rates and mixing are ignored completely.

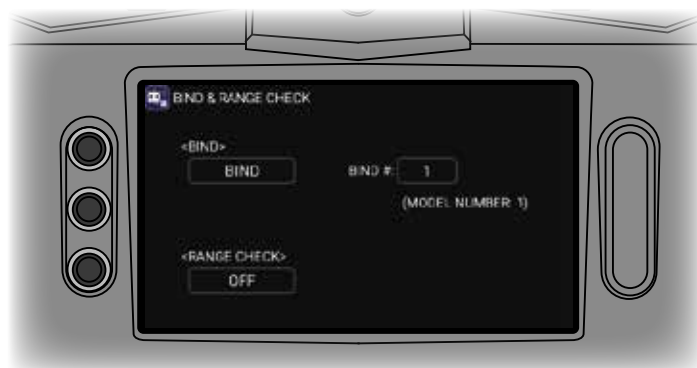
The master transmitter can be another JR 28X, JR XG 6, 8, 11, 14 or JR 11X. Some Spektrum transmitters are also compatible. The master transmitter should always have its power switch in the on position, and be bound to the model.

### ■ Caution note

Be sure to check both master and slave transmitters for correct function and control prior to commencing flight training using two transmitters. Pay particular attention to control direction, dual rates, trim settings, mixing, etc.



## BIND & RANGE CHECK



### Function explanation

This function allows binding (pairing) with the receiver. In addition, transmitter power output can be reduced for carrying out a range check. Note that some receivers use a new 'ez-bind' function, the binding of which is described in the receiver manual.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select bind and range.
- ③ To bind the transmitter to a receiver:
  - a. Place the receiver in bind mode (see page 3-7)
  - b. Touch the bind area on the screen.
  - c. 'Binding' will be displayed.
  - d. If success is shown, the bind has been successful.
  - e. If timeout appears, please try the bind process again.
- ④ Range check:
  - a. Activate range check mode to change output RF power from normal to low. The blue LED will flash, and a range check can be carried out. Place the aircraft approximately 40 meters (131 feet) away from the transmitter, and ensure all the controls function normally. Also see page 3-7.
- ⑤ Bind #:
  - a. This function allows more than one transmitter memory to be bound to a single receiver. This is very useful if you require a windy and calm program for a particular model.

The transmitter has storage for 500 unique model setups. So it contains 500 unique codes for binding to receivers. You may decide to use one

of these unique codes for more than one model memory, meaning several model memories will communicate with the same receiver.

This is very useful if you require a 'windy' and 'calm' weather setup, for say a competition glider. You would initially setup the glider on one model memory. After test flying the model and finalizing the majority of the settings, you would copy the model to a new model memory, and then change the names of the models to say "Xmodel calm" and "Xmodel windy". Look at the bind number used by the original model – and copy this bind number to the copy of the model. Now on a windy day you can control the model using "Xmodel windy" and on a calm day use "Xmodel calm". Each model memory can be optimized for the expected flight conditions.

- ⑥ After setting the function, return to the home screen by pressing the back button.

### Tips

- If there is a difficulty in binding a receiver, please confirm the following:
  - ▶ Are the transmitter and receiver batteries fully charged? Please fully charge the batteries.
  - ▶ Are the transmitter and receiver too close to each other? If they are set too close each other, RF swamping may interrupt the binding process. Please try binding again with the transmitter and receiver further separated.
  - ▶ If the transmitter and receiver are on a metal table or desk, binding may be difficult. Please try binding on a different surface.
- Only JR DMSS receivers may be bound to the transmitter.
- Using the bind # function, it is possible to have say model 2 as a 'calm day' setup, and model 3 as a 'windy day setup' for the same model, and swap between these without re-binding.

### Caution note

Be sure to set the fail safe (page 5-14) after the binding procedure is complete. It is essential to use the fail safe to minimize the risks associated with RF signal loss. Be conscious about safety all the time. Check the actual fail safe settings by turning off the transmitter, and monitoring the response of the servos.

When the model type is changed in the transmitter, it will be necessary to re-bind the receiver.

NEVER fly the aircraft in range check mode.



Helicopter



Airplane



Glider



## FAIL SAFE



### Caution note

- For safety reasons, engine-powered and electric powered aircraft should have the throttle function set to failsafe, and this should be programmed to engine off.
- If the reverse switches or stick mode are changed after setting the fail safe, the throttle fail safe may end up set to full throttle. In order to avoid making this dangerous mistake, be certain to program the fail safe settings after completing the aircraft set-up.
- Before flying, be certain to confirm the failsafe settings by switching off the transmitter power, and observing that the servos move to the positions intended. Be especially careful with this test when using an electric motor.

### Function explanation

If the receiver does not receive a valid RF signal from the transmitter it is possible for the servo to remain in their last position (hold) or for one or more servos to move to predefined positions. This is very useful on the throttle channel – to avoid the possibility of an uncontrolled crash at a high throttle setting. Be sure to set the fail safe before flying each aircraft.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select fail safe.
- ③ Select hold or 'FS' (fail safe) for each channel. If you select failsafe, the failsafe position is stored when you confirm the change to failsafe. So it is important to hold the appropriate control in your desired failsafe position when confirming this change.
- ④ After setting the function, return to the home screen by pressing the back button.

### Tips

- 'Hold' maintains the servo positions as they were immediately before the radio signal was lost. This is the default setting.
- 'Failsafe' this can be set individually for each channel as required. The servo(s) move to predefined positions in the event of loss of radio signal.



## CHANNEL SETTINGS



Submenu key

### Function explanation

This screen is where receiver channels are assigned to particular transmitter functions, and input devices for those functions are assigned. The submenu allows setting of auxiliary channels. The transmitter is initially configured for sixteen 14ms channels. If you require more than 16 channels, you can choose to add four (56ms) channels at a time, in place of one 14ms channel. So the final 28 channels are in a configuration of twelve 14ms channels, and sixteen 56ms channels, all fully proportional.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select channel setting.
- ③ The left hand column indicated the receiver output channel. Channels in red have been locked and no changes are possible. To unlock a channel, simply touch the channel indicator, and confirm you wish the channel unlocked. To lock a channel, click on the channel indicator, and confirm you wish to lock the channel. It is a good idea to lock the channels after

the model is set up so no inadvertent changes can be made.

- ④ The middle column indicates the function assigned to the particular receiver channel – it defines the channel output. The functions available depend on the model type selected, and on other settings such as wing type, etc. It is here you would assign one or more gyro channels, governor channel, etc. This must be done prior to setting up these functions. The following pictures include just some of the output functions available. Note that some functions must be activated before the output is seen. For example, three gyros must be activated in the gyro menu before the three gyro outputs are seen here.
- ⑤ Finally the input column allows you to select a physical input device for the channel. Selecting 'INH' as the input device means there is no physical input for the channel. However, mixing functions, etc can still be used to manipulate the channel. (left and right sliders missing) When a two axis stick is selected, it is necessary to then pick which axis of the stick will be used.
- ⑥ Pressing the submenu button allows setting of auxiliary channels – see below.
- ⑦ After setting the function, return to the home screen by pressing the back button.



### Submenu functions

- Auxiliary (extra) channel setting  
The transmitter is configured for sixteen 14ms channels. If you require more than 16 channels, you can choose to add four (56ms) channels at a time, in place of one 14ms channel. Simply press the add button and confirm the addition.

The delete button can be used to remove a group of four auxiliary channels. So the final 28 channels are in a configuration of twelve 14ms channels, and sixteen 56ms channels.

All channels are always fully proportional, and 14/56ms channels all have identical functionality, it is just that the 14ms channels are updated four times as often.

### Tips

- When you define a channel output to 'aux', the aux number matches the channel number. So if you define channel 5 to 'aux', it becomes 'aux 5'. In this way, the aux channel number does not change if you add aux channels prior to an existing aux channel in the channel list.
- Even though a channel input can be set to inhibit, it is still possible to use the channel with a program mix, etc.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## SWASH TYPE



Submenu Key

### Function explanation

This function allows electronic CCPM mixing to match the mechanical structure and control of the helicopter swash plate. After making the swash type selection, detailed settings should be made using swash mixing in the function list (page 122). The submenu allows swash angle correction (electronic swashplate phasing adjustment).

### Setting method

- ① From the home screen, press the menu button on the touch screen.

- ② From the system list, select swash type.

- ③ Touch the area of the screen representing the swashplate.

- ④ From here select the swash plate configuration which matches your helicopter. Note the top of the screen represents the front of the helicopter. There are twelve possible swash configurations, spread over two screens. Simply touch on the configuration which matches your helicopter.

- ⑤ Pressing the submenu button allows electronic setting of swashplate angle correction (phasing) – see below.

- ⑥ After setting the function, return to the home screen by pressing the back button.

※ Note that the actual mixing amount and direction settings, etc are made in 'swash mixing', found in the function list, **page 4-19**.



### Submenu functions

- Swash angle correction (phasing)

Selecting this function allows the phasing angle of the swashplate to be changed electronically. Note that this should not be done on flybarless helicopters using electronic stabilization – this should instead be done within the flybarless unit.

### Tips

- Many flybarless systems require the transmitter to be set to 1s normal swashplate configuration, regardless of the actual helicopter swash configuration. Please be careful of this when using a flybarless flight controller.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## WING TYPE



### Function explanation

Here the wing type can be set. Dual ailerons and dual flaps, dual elevators, dual rudders, tailless planes, and V-tail wings can be selected. Multiengine aircraft throttle configuration is also set here.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select wing type.
- ③ Now select the layout you would like to adjust – for example, 'main wing' or 'tail wing', and then select from the options available.
- ④ After setting the function, return to the home screen by pressing the back button.

This options available with this function vary depending on which model type you have selected – glider or airplane.

After selecting the various configurations, check the channels setting options (page331) and here you will be able to see (and change) the default receiver channel outputs for each control surface.

### Airplane

#### Main wing

Here select the main wing configuration. It is very easy to understand the wing servo configuration by looking at the pictures of each main wing type.

- One aileron – Select this option if the wing uses a single aileron servo.
- Flaperon – Select this option if you use two aileron servos, which can

also be used as flaps.

- Two ailerons – Select this option if you are using two aileron servos, and don't wish them to be used as flaps.
- Two ailerons + one flap – This option is used if you are using two aileron servos, and a separate single flap servo.
- Two ailerons and two flaps – This option is used if you are using two aileron servos, and two flap servos.
- Two ailerons and four flaps – This option is used if you are using two aileron servos, and four flap servos.
- Four ailerons – This option is used if your wing uses four aileron servos.
- Four ailerons and one flap – This option is used if you are using four aileron servos, and a separate single flap servo.
- Four ailerons and two flaps – This option is used if you are using four aileron servos, and two flap servos.
- Four ailerons and four flaps – This option is used if you are using four aileron servos, and four flap servos.
- Delta – This option is used when the ailerons must also act as elevators.
- Delta and one flap – This option is used when the ailerons must also act as elevators, and you have a single flap servo.
- Delta and two flaps – This option is used when the ailerons must also act as elevators, and you have two flap servos.
- Delta and four flaps – This option is used when the ailerons must also act as elevators, and you have four flap servos.

#### Tail type

Here you can choose the tail configuration of your plane.

- One elevator and one rudder – This is the 'standard' configuration for most aircraft. A single servo controls the elevator, and a single servo controls the rudder.
- Two elevators and one rudder – Choose this option if your model uses dual elevator servos.
- Two elevators and two rudders - Choose this option if your model uses dual elevator servos and two rudder servos.
- V-tail – choose this option if your model uses a v-tail, requiring mixing of two servos for elevator and rudder control.

#### Throttle

- One throttle – Use this option if your airplane uses a single motor and throttle servo.
- Two throttles - Use this option if your airplane uses two motors.



- Three throttles - Use this option if your airplane uses three motors.
  - Four throttles - Use this option if your airplane uses four motors.
- ※ Note that it is possible to add normal throttle trim to this second channel, or add a separate trim lever as the second throttle trim.
- The throttle hold function (**page 4-13**) is useful for bringing one or more motors back to idle and holding them there.

### ■ Caution note

Actually operate the servos and carefully confirm the settings before flying.

## ■ Glider

### ■ Main wing

Here select the main wing configuration. It is very easy to understand the wing servo configuration by looking at the pictures of each main wing type.

- Two ailerons + one flap – This option is used if you are using two aileron servos, and a separate single flap servo.
- Two ailerons and two flaps – This option is used if you are using two aileron servos, and two flap servos.
- Two ailerons and four flaps – This option is used if you are using two aileron servos, and four flap servos.
- Four ailerons and one flap – This option is used if you are using four aileron servos, and a separate single flap servo.
- Four ailerons and two flaps – This option is used if you are using four aileron servos, and two flap servos.
- Four ailerons and four flaps – This option is used if you are using four aileron servos, and four flap servos.

### ■ Tail wing

Here you can choose the tail configuration of your glider.

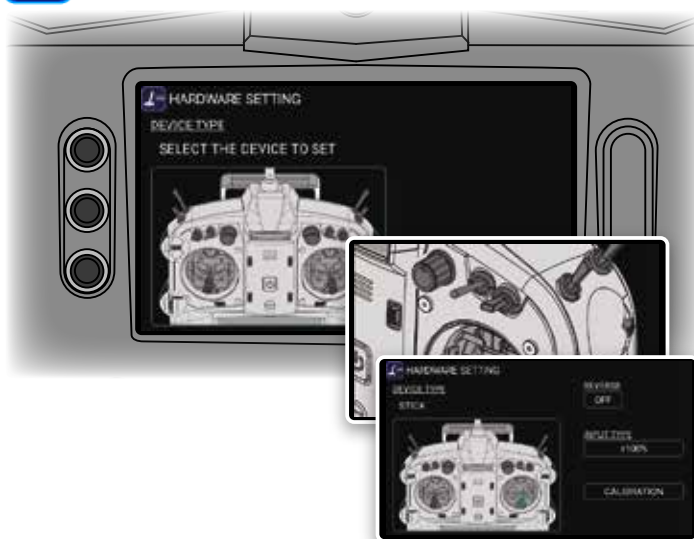
- One elevator and one rudder – This is the 'standard' configuration for most aircraft. A single servo controls the elevator, and a single servo controls the rudder.
- Two elevators and one rudder – Choose this option if your model uses dual elevator servos.
- Two elevators and two rudders - Choose this option if your model uses dual elevator servos and two rudder servos.
- V-tail – choose this option if your model uses a v-tail, requiring mixing of two servos for elevator and rudder control.

### ■ Spoiler

- One spoiler – Choose this option if your glider uses a single spoiler channel.
- Two spoilers - Choose this option if your glider uses two spoiler channels.



## HARDWARE SETTING



### Function explanation

This function enables the physical switch type to be modified as necessary if you physically change switches on the transmitter.

Each input device can be reversed, and analogue devices calibrated. Further, it is possible to define individual switch positions, which will affect their function.

For example, some pilots fly with the throttle stick working in the opposite sense to normal (stick away = idle, stick down = full throttle). This function allows the direction of operation of the throttle stick to be reversed. This is quite different from simply reversing the throttle channel. It is necessary to use this function (rather than the reverse switch) so that all mixing functions work correctly when flying using this technique.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select hardware settings.
- ③ Touch the particular input device you wish to program on the picture

of the transmitter. This will zoom the picture, so you can accurately select the device.

- ④ Fixed switches: If you have selected a switch which cannot be physically changed, you will get a menu including
  - a. Reverse – here you can set the direction for the switch.
  - b. Position options – you can define in software what each switch position should result in.
- ⑤ User changeable switches: If you have selected a switch which can be physically changed, you will get a menu including
  - a. Device type – here you can change the type of switch installed in this location. This is important to define if you install optional switches, or change switch locations. Examples include potentiometer, digital trim, two position switch, 3 position switch, and momentary switch.
  - b. Reverse - here you can set the direction for the switch.
  - c. Position options – you can define in software what each switch position should result in.
  - d. Calibration - for analogue input types, calibration can be carried out.
  - e. Input type – the settings here depend on the input device. It is possible to change the type of input a device gives. Examples include gain, two position, three position, momentary, etc.
- ⑥ After setting the function, return to the home screen by pressing the back button.



### Tips

- If you change the hardware configuration, always reflect these changes in the transmitter software.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## STICK ACCELERATOR



### Function explanation

This function enables the transmitter to accentuate the action of a particular stick movement. Two acceleration profiles are available, and switches can be set to change between these in flight. This function should be used with caution, and only be experienced pilots. If you quickly move a stick on the transmitter, this function anticipates you are requiring an immediate and large response, so sends a larger signal to the appropriate receiver channel. You can set the area of stick travel where the function is active, and set the degree of acceleration and recovery time.

### Setting method

It is possible to setup two accelerator profiles for two different controls (ACCEL1 and ACCEL2). A switch can be assigned to turn the accelerators on and off. Note the same switch is used to control both ACCEL1 and 2.

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select stick accelerator.
- ③ Select the accelerator profile you wish to program. Touch the ACCELx part of the screen and select the profile to program.
- ④ Next touch the switch icon, and here you can select the switch or switches to use for turning the accelerator on and off. Select a switch or switches in the usual manner (page 3-22). Use the back button to return to the previous screen.
- ⑤ Next select the stick you wish to use the stick accelerator function for. Click on the stick selection dialogue and select the stick from the available options.



- ⑥ Now program the area of stick travel the accelerator function will be active. Normally you would want the accelerator off in the center of stick travel (to allow small corrections normally required during flight), and have the accelerator on toward extremes of travel.

The setting of on/off points is then required. These are set in the same ways as the on/off points for the analogue position switch (APS) function, so it is useful to refer to that section of the manual for information on this setting. See page 5-7.

Note that it is possible to set a hysteresis for turning the accelerator on and off.

- ⑦ Now set the required scale - either low or center.  
Low means the accelerator works from low stick position. Center means the accelerator is based around center stick. This is the mode you would normally use.
- ⑧ Next set the rate and recovery time in both direction of travel.  
The rate sets the acceleration in that direction of travel.  
The return sets how quickly the servo will return to match the stick position.  
These values are set independently for both travel away from center, and travel toward center.
- ⑨ Now set the ACCEL parameter. This sets how long the overshoot position is held for.
- ⑩ After setting the function, return to the home screen by pressing the back button.

### Tips

- This function is ideal for experienced pilots experimenting with unique maneuvers requiring the fastest response times available.

### Caution note

Actually operate the servos and carefully confirm the settings before flying.



## ALL SERVO HOLD



\*This screen is for Helicopter type.

### Function explanation

This function holds (locks) all the servos in their current positions. It is used when the operator does not wish the servos to move, typically during some radio adjustments. When this function is set to on, the blue RF indicator LED on the switch will flash, indicating all servos are held.

### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select all servo hold.
- ③ Touch the 'off' button, and then 'yes' to activate this function. The servos will now remain held at their current positions.  
To de-activate the hold, touch 'on', and then select 'yes'. The servos are now active again.
- ④ After setting the function, return to the home screen by pressing the back button.

Additionally, for helicopter models, it is possible to disable the dialogue which normally asks if you wish to hold the servos while adjusting certain functions (dual rate & expo, throttle curve, pitch curve, gyro sensitivity).

With this turned off, the hold dialogue will not appear, and the servos will not be held during adjustment. Be very careful making adjustments when the servos are not held.

The function is disabled by touching the 'on' area, and confirming you wish to turn the function off.

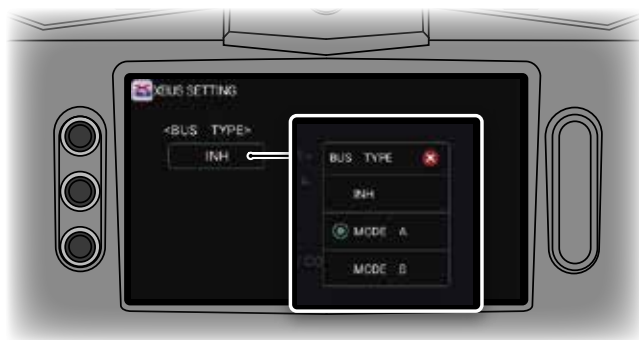
### Caution note

Warning: It is very dangerous to set this function to be activate at the same time as an electric motor is being connected, as the motor may start moving and not be able to be shut off immediately. Take extra care and attention to disconnect any electric motors before activating this function.





## X BUS FUNCTIONS



MODE A

### Function explanation

The XBus system uses JR's own serial bus data instead of PWM (pulse wide modulation) to communicate with XBus products such as servos, gyros, etc. Control signals are sent in a serial manner to all channels, with individual servos, etc recognizing their own data from the receiver. An XBus capable receiver must be used when employing serial data transmission. XBus servos must be programmed prior to use. Please refer to individual XBus product setup instructions for more information.

An XBus capable receiver (such as the JR RG712BX) must be used to realize XBus functionality. Using more than 17 channels is not possible with older XBus receivers (RG731BX and RG031BX). All other XBus receivers support the full 28 channels of this transmitter.

There are two XBus modes available

#### ● Mode A

This is a JR proprietary mode. It is used when employing JR XBus products such as JR NX series servos, the JR Axis gyro, and other JR XBus products. When mode A is selected, the "Servo/Converter" is displayed, enabling setting of devices. When in airplane mode, the JR Axis three-axis gyro can be selected.

#### ● Mode B

This is a generic serial protocol mode, as used by several other manufacturers. It can be used to communicate with the Freakware BeastX and Mikado V-Bar flybarless systems, along with others. The maximum number of available channels is twelve. The channel order using XBus mode B is as follows:

- 1) CH1: Aileron
- 2) CH2: Elevator
- 3) CH3: Rudder
- 4) CH4: AUX04 (pitch/flap)
- 5) CH5: Throttle
- 6) CH6: Gear 1
- 7) CH7: AUX07
- 8) CH8: AUX08
- 9) CH9: AUX09
- 10) CH10: AUX10
- 11) CH11: AUX11
- 12) CH12: AUX12

The channel order can be changed using 'channel setting' - see page xxx.

Note that the receiver PWM ports are inhibited when using XBus mode B.

When not using XBus accessories, or when using a receiver which does not support XBus, set the XBus mode to inhibit.



MODE A



## ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the system list, select XBus.
- ③ Select XBus mode A, mode B or inhibit as required.
- ④ If mode A is chosen, many other settings are available as required – see below. Note that there will be no PWM output signals from standard ports on the receiver when XBus has been activated in mode B. When using a DMSS receiver without XBus capability the bus type should be set to inhibit.
- ⑤ After setting the function, return to the home screen by pressing the back button.

## ■ XBus mode A settings

- XBus ID's
 

XBus components operate on the basis of a main ID and sub ID where:

  - ▶ The main ID identifies the function of that particular component e.g. aileron, elevator, rudder, throttle, and so forth. The channel name will vary depending on the wing type or swash type being used.
  - ▶ The sub ID number identifies 1-4 servos moving in unison on the particular function. XBus allows up to four components per function, meaning that each channel can control up to four servos. It is possible to fine tune the neutral position, servo direction, and travel limits for each sub ID independently.
- ID reset
 

The ID reset function will initialize (reset) all applicable data to factory settings including centering and travel limits.
- ID Change
 

ID setting of a device XBus can be performed from the transmitter. When setting one by one, use **"ID Single"**. When setting ID collectively for the XPort Duo (XB1-14DRS) or other similar devices, use **"ID Multi"**. Input the channel ID of the device and the channel ID to be changed and tap 'set'; to change the channel ID of the device supporting XBus. This also initializes the preset parameters.
- Reverse
 

Used to reverse servo movement. Set the particular servo's channel ID and sub ID, set either normal or reverse. To save the setting after confirming the reverse movement, tap **"set"**.
- Neutral
 

It is used to set the servo neutral. Set the particular servo's channel ID and sub ID, and tap "+" or "-" to change the neutral value. The initial value is 1 step. To zero the adjustment, lower the value to reach **"res"**

(reset) then touch **"set"** to reset the neutral setting. To save the setting after confirming the neutral movement, tap **"set"**.

- Travel
 

It is possible to set the travel (maximum movement angle) of each individual servo. Set the particular servo's channel ID and sub ID, touch on "+" or "-" to change the travel value. The initial value is 1 step. To zero the adjusted value, lower the value to reach **"res"** (reset). When it reaches to **"res"**, touch **"set"** to reset the neutral setting. To save the setting after confirming the travel movement, tap **"set"**.
- Additional parameters for servos supporting XBus
 

JR NX servos can be programmed (download / setup / upload the settings) using this function. First confirm the target main ID and sub ID is correctly selected. Default status for all items is **"\_\_"**. Tap **"load"** to read the parameter set in the servo. After reading the data, the values set in the servo are displayed. The servo operates in accordance with the setting after the values are changed and saved. However, note that the parameter is not stored at this point. When proper operation of the servo is confirmed, press **"set"** to store the parameter to the servo.
- Holding gain (HOLDING) -> Retaining force
  - + value increases the retaining force.
  - value decreases the retaining force.

[Setting range] -50 ~ +50
- Damping gain (DAMPING) -> Stopping characteristic of the servo + value stops the servo earlier. The servo decreases in speed before reaching the target angle.
  - value stops the servo later. The servo starts stopping after reaching the target angle and then returns (overshoots).

[Setting range] -50 ~ +50

Try to increase the damping gain first to remove any hunting. If there is hunting after increasing the holding gain, either decrease the holding gain or increase the damping gain. Sometimes hunting can occur after decreasing the holding gain. Try increasing the holding gain or decreasing the damping gain. JR NX servos are optimally set up at the factory. Apply +/- 0% for factory settings. The best settings depend on the application. Experiment to find the optimal settings.
- Dead band (DEAD BAND)
  - + value widens the dead band.
  - value narrows the dead band.

[Setting range] -10 ~ +10
- Boost (BOOST) -> power to start the motor.

+ value increases the starting power to the motor. This results in a better response but also characteristically rough running.

- value decreases the starting power to the motor. This results in smooth movement but with a slower response.

[Setting range] -999 ~ +999

- Alarm level (ALARM LEVEL)

A beep (high frequency) sound is used to provide feedback on servo load. Set the percentage of maximum load to alarm at.

[Setting range] 0% ~ 99%

- Delay time for alarm (ALARM DELAY)

Set the delay before the alarm sounds after sensing the set load.

[Setting range] 0.0s ~ 5.0s

- Angle (ANGLE)

Selectable 120° or 180° total servo travel.

- Slow start (SLOW START)

Enable (ON) / Disable (OFF) the servo slow start function. When selected, on initial power on, the servos will slowly travel to their neutral positions. Useful on large control surfaces.

- Stop mode (STOP MODE)

Select the servo action if receiver signal is lost.

Free: The servo is free to move - no power is applied to the motor. Useful if more than one servo is driving a control surface.

Hold: The servo holds its current position after signal loss.

These settings must be accomplished with the transmitter and receiver bound (paired) and XBus devices must be appropriately connected with power turned on.

※ **Note:** When the servo ID is set (or changed), the XBus servos and other devices will return to factory settings.

## ■ Setting up the JR Axis airplane gyro using XBus

The JR Axis three axis airplane gyros can be programmed by the 28X. The transmitter allows access to the same functions as the Axis Assistant, a PC application. Read the manual for the Axis carefully before commencing configuration.

### ■ Transmitter setup

Set the same trim values in each flight mode (refer to page 53 of the Axis manual).

By default, this transmitter does not use common trims in each flight mode. Set common trim values for each flight mode from the submenu → Flight Mode Group in the trim system (see page 5-5). Change all trims to a common group..

Channel assignment (transmitter) (refer to page 54 of the Axis manual). All

channel assignment in this transmitter is performed from 'channel setting' in the system list. To setup a switch for changing flight mode, see 'flight mode setting' in the system list.

### ■ Preparation

Before setting gyro gains, first assign gyro gain channels in the 'channel setting' menu (page 5-12). Assign three gyro gain channels - 1, 2, 3. Then, set the gyro gains in the gyro menu (page 4-11) in the function list.

### ■ Setting switches

Tap the switch icon on the gyro gain screen to show the switch selection screen. By default, the switch is linked to the flight mode.

### ■ Delay

To set a delay when switching gyro gains, select 'set delay' in the gyro submenu.

### ■ Gyro setup - page 63 of the Axis manual

Select airplane gyro (Axis) in the XBus settings..

### ■ Channel assignment

Touch the channel section of the channel assignment screen and designate the channel numbers to be used from the list.

### ■ Wing type setting

First, select the main wing type.

Touch on the main wing setting, and select from the list.

※ In the transmitter system list, select 1 aileron for the main wing, 1 Elevator + 1 Rudder for the tail wing.

### ■ Normal

Flap trim (up and down ( ↑ / ↓ ) trim for Axis)

### ■ Tail setting (tail type) (page 67 of the Axis manual)

- Sync trim

It is used to equalize the neutral position of the elevators on the right and the left.

### ■ Limit adjust (page 68 of the Axis manual)

#### ■ Stores the maximum travel in the axis.

1) Touch 'start' (the display changes to 'stop')

2) Move the transmitter sticks to the maximum angles in all four directions, from side to side and up and down.

3) Be sure to be in 'high rate' (maximum control throws) when doing this calibration.

※ Dual rates can be set later in the transmitter.

4) When the maximum movement angle is set, tap 'stop'. The display returns to 'start'. This can be repeated at any times. If you tap 'stop'

before you have moved the sticks in all directions, simply start the process again.

- 5) When the setting is complete, move the transmitter sticks to the maximum angles, from side to side and up and down again to check if each control surface moves to the maximum angle possible.

#### ■ Mounting the Axis (page 71 of the Axis manual)

- Setting of control direction  
Select 'setting of gyro mounting direction'. Tap either normal or reverse so that each control moves in the right direction.

### ■ Caution note

Actually operate the servos and carefully confirm the setting before flying.



## Telemetry System



### ■ Function explanation

The telemetry system allows various model parameters (airspeed, altitude, etc) to be viewed on the transmitter screen. In addition to the data on the display, alarms and voice alerts can be set, so aircraft conditions can be monitored without taking your eyes off the aircraft. Telemetry sensor data values can be displayed on the various home screens (see page 8-1, telemetry widgets). Note that these functions require optional telemetry sensors to be fitted to the aircraft.

### ■ Setting method

- ① First you must place telemetry widgets on the various home screens. Please refer to section (page 8-1) for information on this procedure.
- ② Touching on a telemetry widget once it is positioned on the home screen brings up a menu to change settings for that widget. The 'common setting' menu changes parameters for all telemetry widgets. Touching on 'setting' brings up this common menu.

#### Here you can set:

- ▶ Units for the telemetry functions (temperature, distance and speed).  
Touch on a unit of measure to be given options to change the unit.
- ▶ Voice output  
touching on voice output setting allows configuration of which widget functions will report their values when a defined switch is selected. It is also possible to move items up and down the list, so you can define the order in which data is given.
  - a. Select the items to be included in the voice output
  - b. Move items up and down the list as required, to set the order information will be reported
  - c. Touch the switch icon to select a switch to activate the voice data readout. See page xxx for more information on switch selection
  - d. Once you are done, press the back button to close this window.
- ▶ No link alarm  
if this is activated, the transmitter will alarm if the telemetry link is lost. When setting this function, a delay must be included, which is the length of time between the loss of telemetry data, and activation of the alarm.

#### Telemetry alarm switch:

This allows telemetry alarms to be turned on and off.

- ③ Additional individual telemetry widget settings can also be adjusted as

described below.

- ④ After setting the function, return to the home screen by pressing the back button.

## ■ Receiver voltage

Receiver battery voltage can be remotely monitored from the transmitter. In addition, a low voltage alarm can be set.

### ■ Receiver battery alarm

This function alerts to a drop in receiver battery voltage. Initially it is inhibited. To activate, touch on the widget once it is placed on the home screen. Here the alarm voltage can be set between 3.0V – 9.0V in 0.1V increments.

## ■ Temperature

Temperature can be remotely monitored from the transmitter. In addition, a high temperature alarm can be set. Temperature units are set in the common menu as described above.

### ■ Alarm

This sets the temperature at which the alarm will sound – between 30 and 500° C. Initially this alarm is inhibited. Set the temperature to the desired alarm point.

## ■ Revolutions per minute (RPM)

RPM can be remotely monitored from the transmitter. Various sensor types can be selected and programmed.

### ■ Sensor type magnetic

Using the optional JR hall effect (magnetic) sensor, rpm can be measured using a small sensor and magnet.

By setting the gear ratio, the transmitter can display actual final rpm even if the sensor is installed prior to the final output gear stage. Refer to your aircraft manual to confirm the gear ratio. Initially it is set as "INH" (inhibit). Input the necessary value (1.00 to 20.00) in 0.01 steps.

#### For example:

If used on a gas (or nitro) powered helicopter, it is possible to obtain main rotor blade RPM by installing the magnetic sensor on the clutch bell, and calculating rotor RPM using the gear ratio. On an electric helicopter, it is advisable to install the magnetic sensor on the main gear and directly measure rotor blade RPM (gear ratio 1.00).

### ■ Sensor type optical

Using the optional JR optical sensor, it is possible to monitor motor RPM by setting the number of propeller blades.

The optical sensor monitors RPM by counting the number of times light is

blocked by a passing blade. Therefore it is necessary to input the number of propeller blades. So input the actual number of propeller blades (eg 2, 3, etc). Initially, it is set to "INH". Input the necessary number of the propeller blades (1-20 blades).

### ■ Sensor type motor (pole)

It is possible to monitor the actual motor rpm of a brushless motor by installation of an optional motor pulse sensor. It is necessary to input the number of magnetic poles in order to have actual motor rpm displayed. Initially, it is inhibited. The number of magnetic poles can be set between 2-40 (even numbers).

## ■ Altimeter

Altitude can be remotely monitored from the transmitter. In addition, high altitude alarms can be set. Altitude units are set in the common menu as described above.

### ■ Sound (1,2,3)

It is possible to select from three types of audio for different altitude indications. Initially it is set to inhibit. If desired, set the alert sound depending on the situation. It is possible to set altitude between 1 ~ 2000m in 1.0 meter increments.

#### ■ Types of alert:

↑ : When the altitude is greater than the set value.

↓ : When the altitude is less than the set value.

~ : When flying within the set altitude range.

※ When the alert is set in an altitude range, it can be set between 0.3m ~ 9.9m in 0.3m increments.

If the three conditions overlap, priority is set as "SOUND3 > SOUND2 > SOUND1".

### ■ Switch select

It is possible to set an alert to be active by switches or stick position, or a combination of those devices.

Reset procedure for widgets

To reset the altitude to "0" meters (or "0" feet) touch and hold the widget. It will reset the altitude to zero.

## ■ Climb indicator (variometer)

Rate of climb or descent can be remotely monitored from the transmitter. In addition, rate of climb or descent alarms can be set.

### ■ Up sound

Rate of climb per second and a beep sound can be set. The default value is 'inh'. Rate of climb can be set by 0.1m/s, from 0.1m/s to 3.0m/s.

Pitch can be set by 0.1m/s, from 1.0m/s ~ 10.0m/s.

If the pilot knows the normal (still air) descent speed of the model, an alert can be set to a slightly lower descent speed, and therefore the pilot will be alerted to the presence of some thermal activity.

#### ■ Down sound

Rate of descent per second and a beep sound can be set.

The default value is 'inh'.

Rate of descent can be set by 0.1m/s, from 0.1m/s to 3.0m/s.

#### Setup example:

##### [To set an integrated vario]:

To know if the aircraft is climbing, set the up sound to be active at say 0.5m/sec (minimum value 0.1m/sec) - now if your aircraft climbs at greater than 0.5m/sec you will receive an audible tone.

##### [To set a net vario]:

Set a value more positive than the still air sink rate of your aircraft as the up sound to know if the surrounding air is rising. For example, if the aircraft still air sink rate is -1.0m/sec, set an alarm value of -0.7m/sec. With this setting, you get informed when the surrounding air is rising at more than 0.3m/sec.

To get a net sink rate, set the alarm to a value more negative than the still air sink rate of your aircraft. In this example, set the down sound to a value of -1.3m/sec.

※ **Note:** if the up sound and down sound are very close in values, you may get false alarms caused by small aircraft movements.

#### ■ Switch select

It is possible to set the alert to be active by switches or stick position, or a combination of those devices.

#### ■ Voltage - for motive power battery

Motive battery voltage can be remotely monitored from the transmitter. In addition, a low voltage alarm can be set.

#### ■ Motive power battery alarm

It is possible to set an alert for low motive power battery voltage. Initially it is set as Inhibited. Set the alert voltage as desired. The voltage can be set between 0.1V ~ 655.3V in 0.1V increments.

#### ■ Current - for motive power battery

Motive battery current can be remotely monitored from the transmitter. In addition, a capacity alarm can be set.

#### ■ Nominal capacity value

It is possible to set a nominal capacity value to match your motive power battery capacity. It can be set between 0mAh ~ 30,000mAh, in 10mAh increments.

#### ■ Battery capacity alarm

It is possible to set a capacity remaining alert based on the nominal capacity value of your battery. Initially it is set as Inhibited. To activate, set a percentage between 0-100%. The alarm will sound when this calculated percent capacity remaining reaches this figure.

Residual capacity of the battery is calculated and displayed by deducting the consumed capacity from the preset capacity.

The setting is by 1mAh, from 0mAh ~ 30000mAh.

#### ■ Airspeed

Airspeed can be remotely monitored from the transmitter. Speed alarms and

#### ■ Calibration

The TLS1-SPD monitors airspeed using a pressure sensor. Sometimes it is necessary to modify the displayed values slightly because of installation differences, etc. Here you can modify the displayed airspeed by inputting a +/- percentage.

#### ■ SPD-alarm

A high speed alarm can be set. The default value is disabled (INH). It is necessary to set a speed to enable the high speed alarm. The alarm range is from 1 km/h to 999 km/h in 1 km/h steps.

#### ■ VS1-alarm

Low speed alarm. The default value is disabled (INH). It is necessary to set a speed to enable the low speed alarm. The alarm range is from 1 km/h to 999 km/h in 1 km/h steps.

#### Tips

- By using the telemetry widgets, it is possible to display telemetry information on any of the 5 home screens.

#### ■ Caution note

The Telemetry sensor data is meant as an indication only, and therefore we cannot guarantee the accuracy of any recordings obtained.

## Other Android Functions

Because the transmitter uses the android operating system to interface the user to the RF section, this interface is also available for other functionality.



### Video

#### Function explanation

For use to view stored Picture image content.



### Calculator

#### Function explanation

This function allows you to perform calculations using your transmitter.

#### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the 'other' list, select calculator.
- ③ The calculator can be used in the normal manner.
- ④ Return to the home screen by pressing the home button.

#### Caution

Never attempt to perform calculations while flying.



### Clock

#### Function explanation

Time indication and various clock function is available.



### Music

#### Function explanation

This function allows you to browse music files stored on the SD card. You can browse by artist, albums, and songs. It is also possible to create playlists.

#### Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the 'other' list, select music.
- ③ Artists:  
Selecting the artists icon allows you to view music stored on the SD card by artist.
- ④ Albums:  
Selecting the albums icon allows you to view music stored on the SD card by album.
- ⑤ Songs:  
Selecting the songs icon allows you to view music stored on the SD card by song.
- ⑥ Playlists:  
Selecting the playlists icon allows you to view music stored on the SD card by playlist.
- ⑦ Now playing:  
Selecting the now playing icon allows you to view the currently playing song. From here you can stop or pause playback.
- ⑧ Return to the home screen by pressing the home button.

#### Tips

- It is handy to setup a music widget on the home screen to directly access your music collection.

#### Caution

Never allow music to distract you while flying.



## Explorer

### ■ Function explanation

This function allows viewing and manipulation of certain files on the transmitter and SD card.

### ■ Setting method

- ① From the home screen, press the menu button on the touch screen.
- ② From the 'other' list, select OI file manager.
- ③ Return to the home screen by pressing the home button.

### Tips

- Never use this function without understanding the consequences of file manipulation.

### ■ Caution

Never use this function while flying.

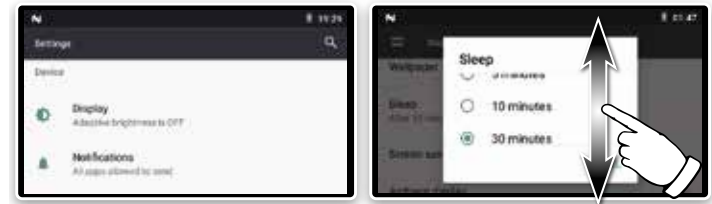


## Setting

### ■ Function explanation

This function allows you to change certain settings in the android operating system.

### ■ Setting method



- ① From the home screen, press the menu button on the touch screen.
- ② From the 'other' list, select setting.
- ③ Device:
  - a. Sound: Sound options can be modified.
  - b. Display: Display options can be modified.
  - c. Storage: Storage options can be modified.
  - d. Apps: App options can be modified.
- ④ Personal:
  - a. Location services: Location services options can be modified.
  - b. Security: Security options can be modified.
  - c. Language and input: Language and input options can be modified.
  - d. Backup and reset: Backup and reset options can be modified.
- ⑤ System:
  - a. Date and time: Date and time options can be modified.
  - b. Developer options: Information about the developer.
  - c. About Propo: Information about the transmitter.
- ⑥ Return to the home screen by pressing the home button.

### ■ Caution

Never use this function while flying.

## ■ Widgets



Widgets can be placed on the transmitter home screens to allow easy access to important data and functions.

Telemetry widgets allow the viewing of telemetry data, as well as the setup of telemetry alarms and audible telemetry information. Please see **page 6-1** for more information on the telemetry system.

There are five home screens available, and multiple widgets can be placed on each screen. Additionally, a single widget can be placed on more than one screen.

There is also a quick access menu on the right hand side of the screen which remains the same regardless of which home screen you are on. It is convenient to place here widgets which are commonly accessed – such as model select.

To place a widget on the home screen or quick access menu, touch the menu area of the screen, then go to widgets.

Find the widget you require, and touch it for a second or two until the display jumps to the home screen. While keeping your finger on the screen, you can move the widget to the left or right to change between the 5 home screens.

You can also position the widget on the quick start menu (compact size widgets only). Once you have positioned the widget where required, simply remove your finger from the screen.

Widgets can come from either the 'widgets' menu, or you can drag and drop icons from the function, system, or other lists.

If there is not enough room for the selected widget, it is necessary to remove a widget or reposition the widgets on the screen. Simply touch and hold a widget on the home screen or quick access menu until the widget quivers. Now you are able to reposition the widget, or drag the widget to the 'X' where you can drop it to remove it from the screen. You can of course add the widget again simply by going to the widget menu.

Telemetry widgets include common settings such as unit selection, voice output, and no link alarm.

The voice output is in English. You can select the parameters to be read out, and the order they will be reported. Tap the up/down arrows to move items up or down. An on/off switch for reading out parameter information can be set using switch select.

### ■ Transmitter battery voltage

The transmitter voltage widget provides a display of transmitter battery voltage. The voltage of each transmitter battery is displayed separately.

### ■ Timer

The timer widget gives information on each of the timers in the transmitter. If you are using all three available timers, three timer widgets can be placed on the screen. Briefly touching the timer widget (once placed on the home screen) allows you to set various parameters for the widget.

- You can select which timer (1, 2, or 3) the widget should display, including displaying total run time for the particular model.
- You are able to reset the time on the widget, including re-setting total model run time if that is currently displayed.

### ■ Music

The music widget opens a compact version of the music media player, allowing you to easily listen to music from the transmitter. See **page 7-1**, music.



## ■ Music playlist

The music playlist widget opens the full music player, allowing you to select albums and songs to listen to.

## ■ Photo gallery

Placing the photo gallery widget on the home screen gives options to either:

- Access a picture album
- Choose an image to display on the screen (it may need cropping)
- Or shuffle images on display

## ■ Trim position indicator

Multiple trim position indicators can be positioned on the home screens. Touching a trim position indicator allows you to set which trim function you wish it to display information for.

The orientation of the trim widget changes automatically depending on the assigned function.

## ■ Flight mode indicator

The flight mode indicator widget provides information on which flight mode is currently selected.

Voice annunciations can be turned on and off by touching the flight mode widget on the home screen. FM information is announced in preference to telemetry. Announcements are only made when the flight mode name is an English word.

## ■ Telemetry receiver voltage

The telemetry voltage widget provides a display of telemetry voltage.

## ■ Telemetry temperature

The telemetry temperature widget provides a display of telemetry temperature.

## ■ Telemetry rpm

The telemetry rpm widget provides a display of telemetry rpm.

## ■ Telemetry altitude

The telemetry altitude widget provides a display of telemetry altitude.

## ■ Telemetry airspeed

The telemetry airspeed widget provides a display of telemetry airspeed.

## ■ Telemetry current

The telemetry current widget provides a display of telemetry motive power pack current.

## ■ Telemetry variometer

The telemetry variometer widget provides a display of telemetry variometer.

## ■ Telemetry voltage

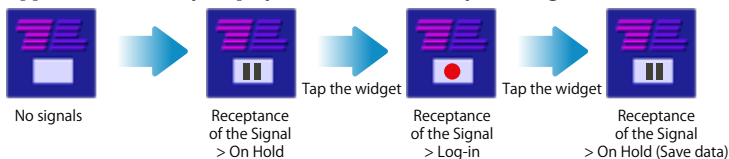
The telemetry voltage widget provides a display of telemetry motive power k voltage.

## Telemetry Log Data (Flight Log)

- During the data logging, by put it on standby, it is capable to save the data up to One hour maximum.
- When Data recording passes one hour, it automatically shuts the data recording. Recorded data can be transferred copy to SD card or to USB Flash memory.

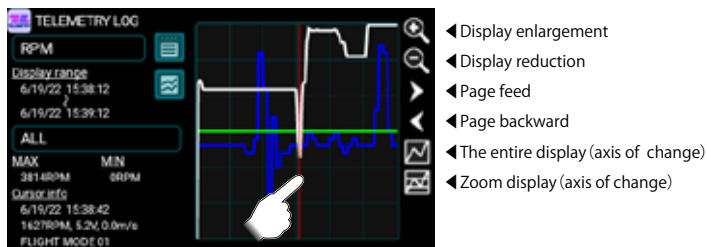
### Confirm the telemetry log data

Press to launch the Telemetry log App. After start of the Telemetry log App, it automatically displays the latest telemetry data log.



### [ Explanation of the display ]

Numerical data value showing the point where red bar and graph line are crossed. By touching the red bar, and slide it on the graph line, it is capable to read by each time axis.



Display items can be changed by touching the telemetry data frame.

Display the entire recorded data



By touching the ICON, it is capable to confirm recorded data or the read the data.



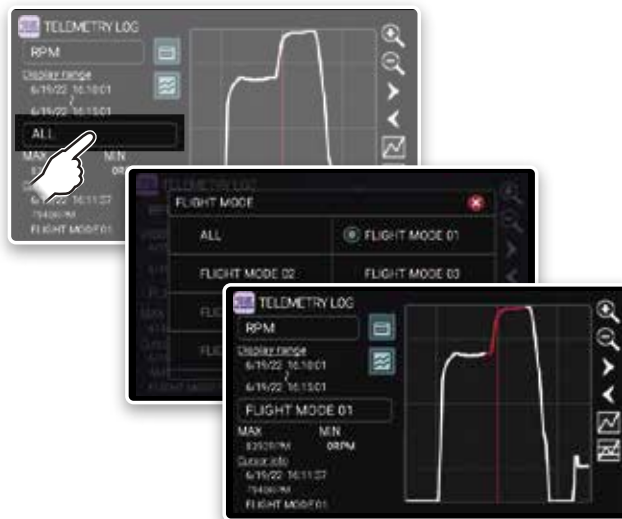
Overlapping the data with other telemetry data.

By touching the ICON, it is capable to overlap the telemetry data. Each selected item shall change its own color to show the data.



### Rotation telemetry data can be displayed by each flight mode with numerical value.

By touching the frame, Selection of the flight mode display shall start up. As an example, selecting the "FLIGHT MODE 01" selected data shall be indicated in red figure.



## ■ Repair and After Sales Service

### ■ Be sure to read the warranty carefully

Only if the product is found to be faulty under normal operations, within the warranty period, will we repair the product based on our assessment. The repair will be paid for by the consumer when the damage is due to improper use (crash damage, misuse etc.), or the warranty period has expired, or without the warranty attached (copies will not be accepted). Note that some damage may not be economical to repair. The scope of the warranty is limited to the Proportional Radio System and excludes aircrafts, engines, accessories and any non JR product. Please note we will not be responsible for any loss of model which was set or recorded by the customer, damage caused by misuse of the product, nor for any compensation for damage to human life, health or property, nor for any damage incidental to the above. When the warranty period has expired, we will repair the product for cost if requested by the customer, if we judge that the product may be used safely following the repair.

Please note in advance that the warranty period may vary depending on the JR Sales Agent (JR Distributor) in your country. Please contact them for further details concerning the warranty or After-Sales Service (repair services, purchase of parts and/or the accessories, etc). Please save any important model data on a data sheet or on a SD card, before requesting any repair. The product may be initialized to factory settings during the repair process. We will not be responsible for any damage or loss of data.

### ■ Caution

- 1) This product and the associated documents are copyrighted by Japan Remote Control Co., Ltd. It is prohibited by law to duplicate, copy, reprint, or modify the product or documents, either entirely or partially without prior notice and approval.
- 2) This product is not designed to be used as equipment or as an instrument which involves human life including as a medical instrument, aerospace instrument, transport equipment, or weapon system, or any other purpose in which high reliability is required, such as space satellite use. We will not be responsible for physical injury, fire, or any other social damage arising from the improper use of this product or any of the equipment or equipment control systems of the general type as described (but not limited to) the above.
- 3) The product and the contents in the document are subject to change without prior notice due to ongoing development.
- 4) If customers violate any of the terms listed in the 'Caution' section of this document, customers must terminate the use of the product if ordered by our company.
- 5) Please note that regardless of the above, we will not be responsible for any other effects which arise by operating this product.

## ■ FCC and IC Information

### ■ FCC Information

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- 1) This device may not cause harmful interference, and
  - 2) This device must accept any interference received, including interference that may cause undesired operation.
- Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

### ■ IC Information

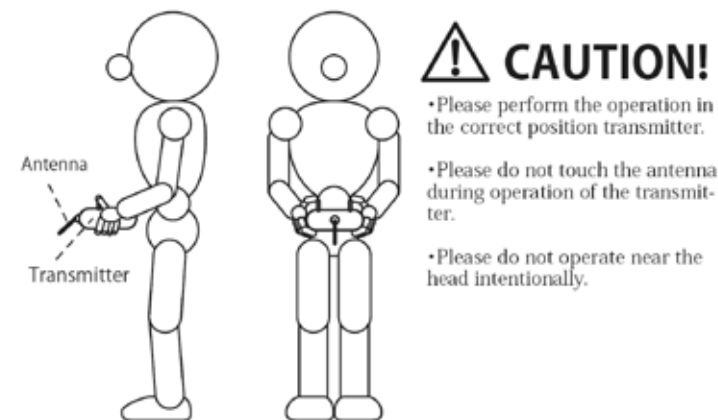
This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions:

- 1) This device may not cause interference, and
- 2) This device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes:

- 1) l'appareil ne doit pas produire de brouillage, et
- 2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

## ■ Precautions





The contents and specifications are subject to change without notice.